

Third MATH 4512 mid-term exam: Nov. 23, 2015

NAME:

(Each problem is 4 points)

1. Find the general solution of  $\frac{d}{dt}x = Ax$  where  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ . Find  $e^{At}$ .

The eigenvalues are  $\lambda=1$ ,  $\lambda=2$  and  $\lambda=3$ .

The corresponding eigenvectors are  $v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$   
and  $v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ .

then

$$\begin{aligned} x(t) &= e^{At} x_0 \\ &= e^{At} (x_{01} v_1 + x_{02} v_2 + x_{03} v_3) \\ &= x_{01} e^{At} v_1 + x_{02} e^{At} v_2 + x_{03} e^{At} v_3 \\ &= x_{01} e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_{02} e^{2t} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + x_{03} e^{3t} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} e^t & 0 & 0 \\ 0 & e^{2t} & 0 \\ 0 & 0 & e^{3t} \end{bmatrix} \begin{bmatrix} x_{01} \\ x_{02} \\ x_{03} \end{bmatrix}. \end{aligned}$$

Hence  $e^{At} = \begin{bmatrix} e^t & 0 & 0 \\ 0 & e^{2t} & 0 \\ 0 & 0 & e^{3t} \end{bmatrix}$ .

2. Find the general solution of  $\frac{d}{dt}x = Ax$  where  $A = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ . Find  $e^{At}$ .

$A$  has a single eigenvalue,  $\lambda=1$ , of multiplicity 3. Since

$$[A - \text{Id}\lambda]^3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

any set of linearly independent vectors generate the span of the generalized eigenvectors of  $A$ . We then can take

$$v_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, v_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

then

$$\begin{aligned} x(t) &= e^{At} (x_{01}v_1 + x_{02}v_2 + x_{03}v_3) \\ &= x_{01}e^{At}v_1 + x_{02}e^{At}v_2 + x_{03}e^{At}v_3 \\ &= x_{01}e^t (v_1 + t(A-\lambda\text{Id})v_1 + \frac{t^2}{2}(A-\lambda\text{Id})^2v_1) \\ &\quad + x_{02}e^t (v_2 + t(A-\lambda\text{Id})v_2 + \frac{t^2}{2}(A-\lambda\text{Id})^2v_2) \\ &\quad + x_{03}e^t (v_3 + t(A-\lambda\text{Id})v_3 + \frac{t^2}{2}(A-\lambda\text{Id})^2v_3) \end{aligned}$$

Since  $(A - \text{Id}\lambda) = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$ ,  $(A - \text{Id}\lambda)^2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ , we get

$$\begin{aligned} x(t) &= x_{01}e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + x_{02}e^t \begin{bmatrix} t \\ 1 \\ 0 \end{bmatrix} + x_{03}e^t \begin{bmatrix} \frac{t^2}{2} + t \\ t \\ 1 \end{bmatrix} \\ &= e^t \begin{bmatrix} 1 & t & t + \frac{1}{2}t^2 \\ 0 & 1 & t \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_{01} \\ x_{02} \\ x_{03} \end{bmatrix} \end{aligned}$$

this implies that

$$e^{At} = e^t \begin{bmatrix} 1 & t & t + \frac{1}{2}t^2 \\ 0 & 1 & t \\ 0 & 0 & 1 \end{bmatrix}.$$

3. Find the general solution of  $\frac{dx}{dt} = Ax$  where  $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ . Provide a plot of the solutions.

The eigenvalues are the solutions of

$$\lambda^2 + 1 = 0. \text{ Hence } \lambda = \pm i.$$

The corresponding eigenvectors are  $\begin{bmatrix} 1 \\ \mp i \end{bmatrix}$ .  
If  $v = \begin{bmatrix} 1 \\ -i \end{bmatrix}$ , then

$$x_0 = c_1 \operatorname{Re} v + c_2 \operatorname{Im} v$$

$$\Rightarrow \begin{bmatrix} x_{01} \\ x_{02} \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ -1 \end{bmatrix} \Rightarrow \begin{matrix} c_1 = x_{01} \\ c_2 = -x_{02} \end{matrix}$$

Then

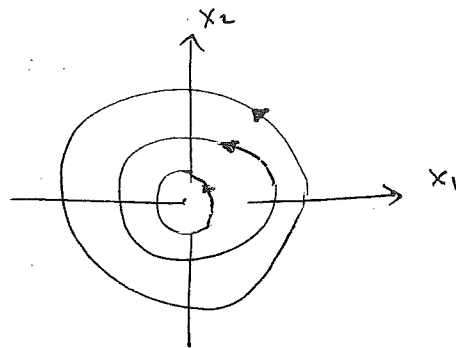
$$\begin{aligned} x(t) &= e^{At} x_0 \\ &= c_1 \operatorname{Re}(e^{At} v) + c_2 \operatorname{Im}(e^{At} v) \\ &= x_{01} \operatorname{Re}(e^{At} v) - x_{02} \operatorname{Im}(e^{At} v) \end{aligned}$$

$$\text{Since } e^{it} = \begin{bmatrix} \cos t + i \sin t \\ -i \cos t + \sin t \end{bmatrix}$$

we get

$$\begin{aligned} x(t) &= x_{01} \begin{bmatrix} \cos t \\ \sin t \end{bmatrix} - x_{02} \begin{bmatrix} \sin t \\ -\cos t \end{bmatrix} \\ &= \cos t \begin{bmatrix} x_{01} \\ x_{02} \end{bmatrix} + \sin t \begin{bmatrix} -x_{02} \\ x_{01} \end{bmatrix} \end{aligned}$$

Hence the solutions lie on circles



4. Find  $e^{At}$  where  $A = \begin{bmatrix} -2 & 4 \\ -1 & 2 \end{bmatrix}$ . Hint: Solve the problem  $\frac{d}{dt}x = Ax$ .

The eigenvalues are the solutions of  $\lambda^2 - \text{trace } A \lambda + \det A = 0$ . Since  $\text{trace } A = \det A = 0$ , the only eigenvalue is  $\lambda = 0$  and it has multiplicity 2.

Since  $(A - \lambda \text{Id})^2 = A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ , any set of linearly independent vectors generate the span of the generalized eigenvectors of  $\lambda = 0$ . So, we take

$$v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \text{ and } v_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

Then

$$\begin{aligned} e^{At} x_0 &= e^{At} [x_{01} v_1 + x_{02} v_2] \\ &= x_{01} e^{At} v_1 + x_{02} e^{At} v_2 \\ &= x_{01} [v_1 + t(A - \lambda I)v_1] \\ &\quad + x_{02} [v_2 + t(A - \lambda I)v_2] \\ &= x_{01} [v_1 + tAv_1] + x_{02} [v_2 + tAv_2] \\ &= x_{01} \begin{bmatrix} 1-2t \\ 0-t \end{bmatrix} + x_{02} \begin{bmatrix} 0+4t \\ 1+2t \end{bmatrix} \\ &= \begin{bmatrix} 1-2t & 4t \\ -t & 1+2t \end{bmatrix} \begin{bmatrix} x_{01} \\ x_{02} \end{bmatrix} \end{aligned}$$

Hence

$$e^{At} = \begin{bmatrix} 1-2t & 4t \\ -t & 1+2t \end{bmatrix}$$

(A shorter proof:  $e^{At} = \text{Id} + tA$  since  $A^2 = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$ .)

5. Find the solution of  $\frac{d}{dt}x = Ax + f(t)$  and  $x(0) = 0$ , where  $A = \begin{bmatrix} -2 & 4 \\ -1 & 2 \end{bmatrix}$  and  $f(t) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ . Hint: Find  $e^{At}$  by using the results in the previous problem.

We have that

$$x(t) = e^{At} x(0) + \int_0^t e^{A(t-s)} f(s) ds.$$

Since  $x(0) = 0$  and  $f(s) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , we have

$$x(t) = \int_0^t e^{A(t-s)} \begin{bmatrix} 1 \\ 0 \end{bmatrix} ds$$

By the previous result,  $e^{A(t-s)} = \begin{bmatrix} 1-2(t-s) & 4(t-s) \\ -(t-s) & 1+2(t-s) \end{bmatrix}$ ,

and so

$$x(t) = \int_0^t \begin{bmatrix} 1-2(t-s) \\ -(t-s) \end{bmatrix} ds$$

$$= \begin{bmatrix} \int_0^t (1-2t+2s) ds \\ \int_0^t (-t+s) ds \end{bmatrix}$$

$$= \begin{bmatrix} t - 2t^2 + t^2 \\ -t^2 + \frac{1}{2}t^2 \end{bmatrix}$$

$$= \begin{bmatrix} t - t^2 \\ -\frac{1}{2}t^2 \end{bmatrix}$$