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## A Remark on the Surface Brunn–Minkowski-Type Inequality<sup>\*</sup>

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In this note we would like to attract reader's attention to the following functional form for the surface Brunn–Minkowski-type inequality.

**Theorem 1.** *Let  $0 < t < 1$  and let  $u, v, w$  be non-negative, quasi-concave, smooth functions on  $\mathbf{R}^n$ , such that  $w(x) \rightarrow 0$ , as  $|x| \rightarrow \infty$ , and*

$$w(tx + (1-t)y) \geq u(x)^t v(y)^{1-t}, \quad (1)$$

for all  $x, y \in \mathbf{R}^n$ . Then

$$\int |\nabla w(z)| dz \geq \left( \int |\nabla u(x)| dx \right)^t \left( \int |\nabla v(y)| dy \right)^{1-t}. \quad (2)$$

A function  $w$  is called quasi-concave, if  $w(tx + (1-t)y) \geq \min\{w(x), w(y)\}$ , whenever  $x, y \in \mathbf{R}^n$  and  $0 < t < 1$  (cf. e.g. [C-F] for an account on equivalent definitions and basic properties of such functions.) In particular, all log-concave functions are quasi-concave. In this case, the assumption on smoothness may be removed from the hypotheses of Theorem 1.

Let  $A$  and  $B$  be convex bodies in  $\mathbf{R}^n$ . Approximating these sets by smooth log-concave functions  $u$  and  $v$ , inequality (2) yields

$$S(tA + (1-t)B) \geq S(A)^t S(B)^{1-t}, \quad (3)$$

and by homogeneity, for  $n \geq 2$ ,

$$S(tA + (1-t)B) \geq \left[ t S(A)^{1/(n-1)} + (1-t) S(B)^{1/(n-1)} \right]^{n-1}, \quad (4)$$

where we use  $S(\cdot)$  to denote the area size of the surface of a corresponding convex body. This is a Brunn–Minkowski-type inequality for the functional  $S$ , cf. [S]. The bound (4) is optimal in the sense that its right hand side

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provides minimum of  $S(tA + (1-t)B)$  in terms of  $S(A)$  and  $S(B)$ ; however, the advantage of the “log-concave” form (3) is that it remains to formally hold when one of the sets is empty.

Thus, inequality (2) under the hypothesis (1) may be viewed as a functional form for (4). The class of quasi-concave functions is natural in Theorem 1, since only for such functions the sets of the form  $A_u(\lambda) = \{x \in \mathbf{R}^n : u(x) \geq \lambda\}$  are convex, and since (4) is stated for convex sets.

Recall that, for all non-negative measurable functions  $u$ ,  $v$ , and  $w$ , satisfying the condition (1), we have the Prékopa–Leindler inequality ([Pr1-2], [L])

$$\int w(z) dz \geq \left( \int u(x) dx \right)^t \left( \int v(y) dy \right)^{1-t}, \quad (5)$$

which represents a natural functional form for the volume Brunn–Minkowski inequality

$$\text{vol}_n(tA + (1-t)B) \geq \left[ t \text{vol}_n(A)^{1/n} + (1-t) \text{vol}_n(B)^{1/n} \right]^n. \quad (6)$$

Other functional forms of (6), earlier references and discussion of history may be found in S. Das Gupta [DG] and R. Gardner [G]. Prékopa–Leindler’s theorem has found a number of interesting applications in Convex Geometry and Analysis; let us only mention the works by C. Borell [Bo1-2], K. Ball [Ba] and B. Maurey [M]. In fact, (5) being combined with (3) may also be used to derive inequality (2).

Indeed, assume the functions  $u$  and  $v$  are not identically zero, so that both vanish as  $|x| \rightarrow \infty$ , since  $w$  does. Hence, the sets  $A_u(\lambda) = \{u \geq \lambda\}$ ,  $\lambda > 0$ , are convex, bounded (and perhaps empty), and similarly for  $v$  and  $w$ .

Now, by the hypothesis (1),

$$tA_u(\lambda_1) + (1-t)A_v(\lambda_2) \subset A_w(\lambda_1^t \lambda_2^{1-t}), \quad \lambda_1, \lambda_2 > 0, \quad t \in (0, 1),$$

as long as both  $A_u(\lambda_1)$  and  $A_v(\lambda_2)$  are non-empty. Anyhow, by (3) and by monotonicity of  $S$ , the functions

$$f(\lambda) = S(A_u(\lambda)), \quad g(\lambda) = S(A_v(\lambda)), \quad h(\lambda) = S(A_w(\lambda))$$

satisfy  $h(\lambda_1^t \lambda_2^{1-t}) \geq f(\lambda_1)^t g(\lambda_2)^{1-t}$ , for all  $\lambda_1, \lambda_2 > 0$ . This property is a multiplicative version of (1) in dimension one, and it also implies (5), ([Ba], Lemma 3), i.e.,

$$\int_0^{+\infty} h(\lambda) d\lambda \geq \left( \int_0^{+\infty} f(\lambda) d\lambda \right)^t \left( \int_0^{+\infty} g(\lambda) d\lambda \right)^{1-t}.$$

Finally, applying the coarea formula  $\int_{\mathbf{R}^n} |\nabla u(x)| dx = \int_0^{+\infty} f(\lambda) d\lambda$  to  $u$ , as well as to the functions  $v$  and  $w$ , we arrive at the desired conclusion (2).

More generally, with a similar argument one may consider Choquet’s integrals  $\int \varphi d\mu \equiv \int_0^{+\infty} \mu\{\varphi \geq \lambda\} d\lambda$  for  $\varphi \geq 0$  with an arbitrary monotone set

function  $\mu \geq 0$  on  $\mathbf{R}^n$ , such that  $\mu(tA + (1-t)B) \geq \mu(A)^t \mu(B)^{1-t}$  in the class of all convex bodies in the  $n$ -space. Under the assumptions of Theorem 1, one then gets that

$$\int w \, d\mu \geq \left( \int u \, d\mu \right)^t \left( \int v \, d\mu \right)^{1-t}. \quad (7)$$

For example, the  $p$ -capacity  $\mu(A) = \inf\{\int |\nabla g(x)|^p \, dx : g \geq 1_A, g \in C_0^\infty(\mathbf{R}^n)\}$  is included in (7) whenever  $1 \leq p < n$ . In that case, the log-concavity of  $\mu$  was proved by C. Borell [Bo2] for  $p = 2$ ,  $n \geq 3$  (the case of Newton capacity) and by A. Colesanti and P. Salani for all  $p < n$ . When  $p = 1$ , (7) coincides with (2). On the other hand, when  $\mu$  is Lebesgue measure, we return to (5).

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