

Newton's method: Finding roots of functions f .

In pictures: pick initial point a_0 . Approximate f by tangent

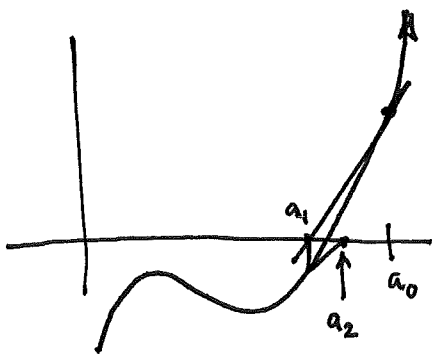
line at a_0 : $f(x) \approx f(a_0) + (x - a_0) f'(a_0)$

Find where tangent line = 0 : $x = -\frac{f(a_0)}{f'(a_0)} + a_0$

Should be close to 0. Let above soln be

called $a_1 = a_0 - \frac{f(a_0)}{f'(a_0)}$. Repeat.

$a_2 = a_1 - \frac{f(a_1)}{f'(a_1)}$, etc... Hope: $\{a_n\} \rightarrow$ root of f as $n \rightarrow \infty$.



Big questions:

- (1) What to pick for a_0 ?
- (2) When can we certify that $\{a_n\} \rightarrow$ root?

if $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$
or from open set $U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}^n$

- (3) How to generalize to multivariable function?

then tangent hyperplane:

$$f(\underline{a}_0) + [Df(\underline{a}_0)](\underline{x} - \underline{a}_0) \stackrel{!}{=} \underline{0}$$

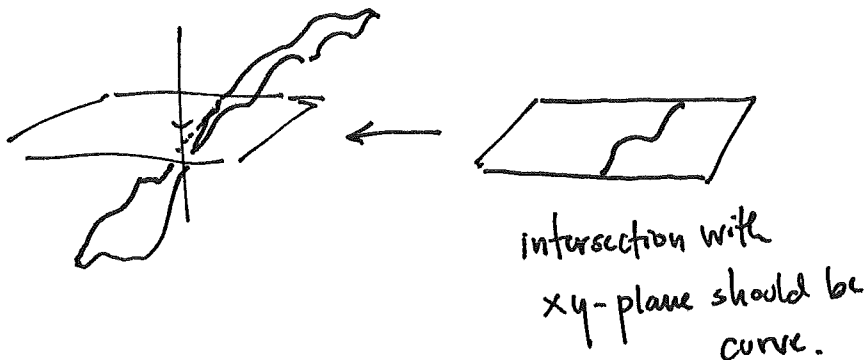
Solve linear system. for $\underline{x} - \underline{a}_0$, then add \underline{a}_0 to find \underline{x}

- (4) Possible bad situations. — initial choices a_0 which don't converge to a root.

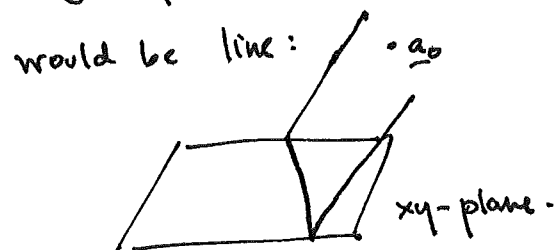
For most $Df(\underline{a}_0)$, its row reduction is I_n , so soln is unique.

Why $\mathbb{R}^n \rightarrow \mathbb{R}^n$? Zeros (i.e. places where $f(x) = 0$) should be sparse (special)

If $\mathbb{R}^2 \rightarrow \mathbb{R}$, then geometrically, asking where graph $(x, y, f(x, y))$ meets the xy -plane.



Indeed if we tried Newton's method we'd get tangent plane. Zeros would be line:



If you think about $\mathbb{R} \rightarrow \mathbb{R}^2$ get tangent line ~~expected~~ to pass through $(0,0)$ required

Iterations always giving line, not a curve.

(linear system with 2 equations, 1 unknown)

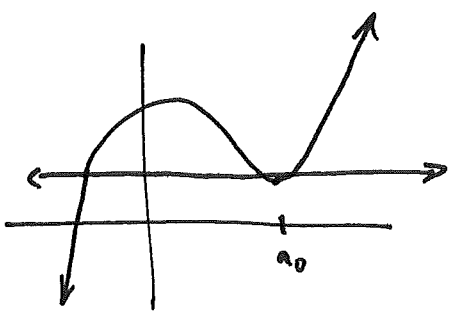
$$\begin{bmatrix} f_1(t_0) \\ f_2(t_0) \end{bmatrix} + \begin{bmatrix} f_1'(t_0) \\ f_2'(t_0) \end{bmatrix} (t - t_0) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

(1) What to pick for a_0 ? Often best to get as close to 0 with $f(a_0)$ as possible.

(use any extra info about where a 0 might be.)

(4) Pitfalls. - illustrate these in 1-var case.

(4a)



No solns to tangent line.

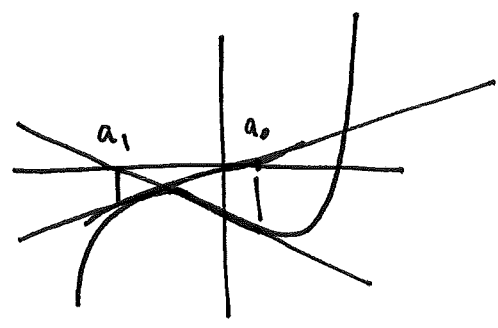
i.e. 1×1 matrix $f'(a_0)$ is not invertible (i.e. not reducing to identity in echelon form.)

Resolution: Pick another a_0 .

(4b) Periodicity

$$a_0 = a_2 = \dots \quad a_1 = a_3 = \dots$$

never converge to 0 of function.



Book gives well chosen example of this.

$$f(x) = x^3 - x + \frac{\sqrt{2}}{2} \quad \text{with } a_0 = 0, a_1 = \frac{\sqrt{2}}{2}$$

in fact $a_0 = \epsilon$, small pos. $\epsilon > 0$ no better.

(2) When can we certify that $\{a_n\} \rightarrow$ root of f as $n \rightarrow \infty$?

Book has nice metaphor: if I show you pictures of a plane in flight, can you tell me when it will crash (i.e. height is function. When = 0)

a_2, a_4, \dots sequence tending to ~~0~~ 0
 a_1, a_3, \dots sequence tending to ~~0~~ $\frac{\sqrt{2}}{2}$
 (i.e. heading toward "death spiral" of periodicity)

Ans: Yes. Know position. First derivative from angle of plane in picture.

And: second derivative — plane is limited in how fast it can reverse change in height.

In multivariable setting, don't have second derivative as #. Stand in: (size of)

Bound secants in all directions: $\frac{|Df(x) - Df(y)|}{|x - y|} \leq M = \max.$

Remember $Df(x)$ is in $\text{Mat}_{n \times n} \approx \mathbb{R}^{n^2}$, so

$|Df(x) - Df(y)|$ is size of $n \times n$ matrix: $\sqrt{a_{11}^2 + \dots + a_{1n}^2 + \dots + a_{nn}^2}$
if $(a_{ij}) = (Df(x) - Df(y))$

Easiest examples: Quadratic functions

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\text{then } Df(\underline{x}) = \begin{bmatrix} 6x_1 & -1 \\ -1 & 2x_2 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \mapsto \begin{bmatrix} 3x_1^2 - x_2 \\ x_2^2 - x_1 \end{bmatrix}$$

$$\text{so } Df(\underline{x}) - Df(\underline{y}) = \begin{bmatrix} 6(x_1 - y_1) & 0 \\ 0 & 2(x_2 - y_2) \end{bmatrix} \quad \text{and}$$

$$|Df(\underline{x}) - Df(\underline{y})| = \sqrt{36(x_1 - y_1)^2 + 4(x_2 - y_2)^2}$$

While $|\underline{x} - \underline{y}| = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2}$. Want M s.t.

$$\frac{|Df(\underline{x}) - Df(\underline{y})|}{|\underline{x} - \underline{y}|} \leq M$$

What should M be?

One answer: $M = 6$ since

$$|Df(\underline{x}) - Df(\underline{y})| \leq 6 |\underline{x} - \underline{y}|.$$

Generally, only prove such an inequality holds on some restricted set.

Definition: We say Df satisfies the "Lipschitz condition" on a set

$V \subset \mathbb{R}^n$ if $\exists M$ for all $\underline{x}, \underline{y} \in V$ s.t.

$M = \text{Lipschitz ratio.}$

$$|Df(\underline{x}) - Df(\underline{y})| \leq M |\underline{x} - \underline{y}|$$