

Review for exam -

Statements of Inverse function theorem, Implicit Function Theorem.

Quantitative versions not covered on exam. Applications: compute derivatives of inverse, implicitly defined functions

Also: check whether conditions are satisfied

(Is $Df(x_0)$ invertible? Is $Df(x_0)$ onto?)

2x2 example of Inverse Function Thm.

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x^2 \\ y \end{pmatrix}$$

$$Df(x_0, y_0) = \begin{pmatrix} 2x_0 & 0 \\ 0 & 1 \end{pmatrix} \text{ invertible if } x_0 \neq 0.$$

Compute $Df^{-1} \begin{pmatrix} 4 \\ 1 \end{pmatrix}$: $f \circ f^{-1} = \text{Id}$

f^{-1} exists and diff. since

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} 4 \\ 1 \end{pmatrix}$$

so $D(f \circ f^{-1}) \begin{pmatrix} 4 \\ 1 \end{pmatrix} = \text{Id}$.

By chain rule: $Df(f^{-1}(y)) \cdot Df^{-1}(y)$

$$\text{so } Df^{-1} \begin{pmatrix} 4 \\ 1 \end{pmatrix} = [Df(f^{-1} \begin{pmatrix} 4 \\ 1 \end{pmatrix})]^{-1}$$

$$= [Df \begin{pmatrix} 2 \\ 1 \end{pmatrix}]^{-1}$$

$$= \begin{pmatrix} 4 & 0 \\ 0 & 1 \end{pmatrix}^{-1}$$

$$= \begin{pmatrix} 1/4 & 0 \\ 0 & 1 \end{pmatrix}$$

By hand $f^{-1} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} y_1^{1/2} \\ y_2 \end{pmatrix}$

with $Df^{-1} = \begin{pmatrix} 1/2 y_1^{-1/2} & 0 \\ 0 & 1 \end{pmatrix}$

$4^{-1/2} = 1/2 \checkmark$

For Implicit Function Theorem

If we're given $F: U \subseteq \mathbb{R}^{n+m} \rightarrow \mathbb{R}^n$ with $F(\underline{c}) = \underline{0}$
 $DF(\underline{c})$ onto
 (so has n pivots!)

write vector in \mathbb{R}^{n+m} so that first

n variables are pivot variables. ($\underline{x} \in \mathbb{R}^n$)

last m variables are independent (non-pivot variables) ($\underline{y} \in \mathbb{R}^m$)

(so rearranging columns in $DF(\underline{c})$ corresponding to this)

Example: $F: \mathbb{R}^4 \rightarrow \mathbb{R}^2$ $DF(\underline{c})$ reduces to

$$\begin{bmatrix} 1 & 3 & 0 & 1 \\ 0 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$$

\uparrow \uparrow pivot vars
 x_1 x_3

Consider new function $f: \mathbb{R}^{n+m} \rightarrow \mathbb{R}^{n+m}$

$$f \left(\begin{bmatrix} \underline{x} \\ \underline{y} \end{bmatrix} \right) = \begin{bmatrix} \text{scribble} \\ \text{scribble} \\ \text{scribble} \\ F \left(\begin{bmatrix} \underline{x} \\ \underline{y} \end{bmatrix} \right) \\ \underline{y} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 3 & 1 \\ 0 & 1 & 0 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_3 \\ x_2 \\ x_4 \end{bmatrix}$$

\uparrow \uparrow
 $D_1 F(\underline{c})$ $D_3 F(\underline{c})$
 in original matrix $DF(\underline{c})$

$\left. \begin{matrix} x_1 \\ x_3 \end{matrix} \right\}$ pivot vars. \underline{x}
 $\left. \begin{matrix} x_2 \\ x_4 \end{matrix} \right\}$ non-pivot vars \underline{y}

if $\underline{c} = \begin{pmatrix} \underline{x}_0 \\ \underline{y}_0 \end{pmatrix}$ then $f \left(\begin{bmatrix} \underline{x}_0 \\ \underline{y}_0 \end{bmatrix} \right) = \begin{bmatrix} F \left(\begin{bmatrix} \underline{x}_0 \\ \underline{y}_0 \end{bmatrix} \right) = F(\underline{c}) \\ \underline{y}_0 \end{bmatrix} = \begin{bmatrix} \underline{0} \\ \underline{y}_0 \end{bmatrix}$

Inverse function theorem says have inverse from nbhd of $\begin{bmatrix} \underline{0} \\ \underline{y}_0 \end{bmatrix}$ ~~scribble~~ In particular,
 for $\begin{bmatrix} \underline{0} \\ \underline{y} \end{bmatrix}$ in nbhd, $f^{-1} \begin{bmatrix} \underline{0} \\ \underline{y} \end{bmatrix} = \begin{bmatrix} \phi(\underline{y}) \\ \underline{y} \end{bmatrix}$ $\phi(\underline{y})$ desired implicit function.

Corollary: $[D\phi(y_0)] = - [D_{i_1} F(\underline{c}), \dots, D_{i_n} F(\underline{c})]^{-1}$

↑ pivot vars

$f \circ f^{-1} = \text{Id.}$
 $Df(f^{-1}(x_0)) Df^{-1}(x_0) = \text{Id.}$

work out block mult.

$[D_{i_{n+1}} F(\underline{c}), \dots, D_{i_{n+m}} F(\underline{c})]$

↑ non-pivot vars.

Example: For circle $\underline{c} = \begin{bmatrix} a \\ b \end{bmatrix}$

with $Df(\underline{c}) = [2a, 2b]$ since

$F\left(\begin{smallmatrix} x \\ y \end{smallmatrix}\right) = x^2 + y^2 - 1 : \mathbb{R}^2 \rightarrow \mathbb{R}^1$

e.g. at $(1, 0)$ then x is pivot var., y non-pivot. $Df\left(\begin{smallmatrix} 1 \\ 0 \end{smallmatrix}\right) = [2, 0]$

so x is implicit function of y there.

$[Dx(0)] = - [2]^{-1} \cdot [0] = 0.$

check: $x = \sqrt{1-y^2}$

$\frac{dx}{dy} = \frac{1}{2} (1-y^2)^{-1/2} \cdot (-2y)$
 $= \frac{-y}{\sqrt{1-y^2}}$

In general $\underline{c} = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix}$, then

$Df(\underline{c}) = [2\cos \theta, 2\sin \theta]$

if x pivot var., y non-pivot

$[Dx(\sin \theta)] = - [2\cos \theta]^{-1} \cdot [2\sin \theta]$

$= - \frac{1}{2} \frac{2\sin \theta}{\cos \theta} = - \frac{\sin \theta}{\cos \theta} = -\tan \theta$

$\frac{-\sin \theta}{\sqrt{1-\sin^2 \theta}}$
 $= \frac{-\sin \theta}{\cos \theta}$
 $= -\tan \theta$

✓

Example :

$$\begin{bmatrix} 1 & 2 & 0 & 3 \\ 1 & 2 & 1 & 4 \\ 2 & 4 & 1 & 7 \end{bmatrix} = A \quad \text{with} \quad \tilde{A} = \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

As linear transformation : $\mathbb{R}^4 \rightarrow \mathbb{R}^3$

rank : # pivot vars = 2

ker : # of non-pivot vars = 2

Basis for image : columns with pivot vars : $\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$.

if I asked you to
(prove from def'n these are linearly indep.,
how would you do it?)

column space
= image.

Basis for kernel :

$$x_1 + 2x_2 + 3x_4 = 0$$

$$x_3 + x_4 = 0$$

Related question:

Find basis for

$$\text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \\ 1 \end{bmatrix} \right\}$$

Write pivot vars in terms of non-pivot vars.

$$x_1 = -2x_2 - 3x_4$$

$$x_3 = -x_4$$

To find basis, just pick

solutions with non-pivot vars = $(1, 0, \dots, 1, 0)$
 $(0, 1, 0, \dots, 0, 0)$

guarantee linear independence.

$$\vdots$$

$$(0, 0, \dots, 1)$$

In our example. Sol'n's with $(x_2, x_4) = (1, 0)$
 $= (0, 1)$

$(x_2, x_4) = (1, 0)$ then

$$x_1 = -2, x_3 = 0 \rightsquigarrow \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

and $(x_2, x_4) = (0, 1)$ then

$$x_1 = -3, x_3 = 1 \rightsquigarrow \begin{bmatrix} -3 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$