

Last week, we explored local extrema for multivariable functions (or on a manifold):

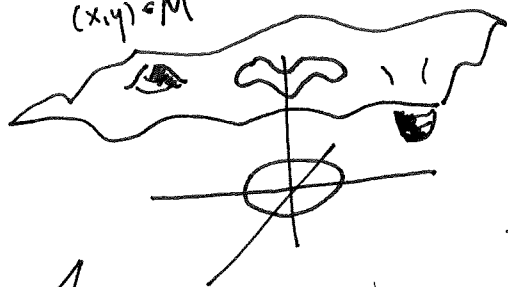
If  $f$  is in  $C^2(U)$ ,  $U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ , then find points  $\underline{a} \in U$  s.t.  $[Df(\underline{a})] = 1 \times n$  0-matrix. Examine quadratic form coming from  $p^2_{f,\underline{a}}$ . Check its signature.

This week: Optimize the function when constrained to submanifold  $M \subseteq \mathbb{R}^n$ .

In pictures:  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ .

$M$ : unit circle, 1-dim'l manifold given by  $x^2 + y^2 - 1 = 0$  in  $\mathbb{R}^2$

find max  $f(x,y)$  s.t.  $(x,y) \in M$ .



Problem: Max along  $M$  may not be local max on graph of  $f(x,y)$ .

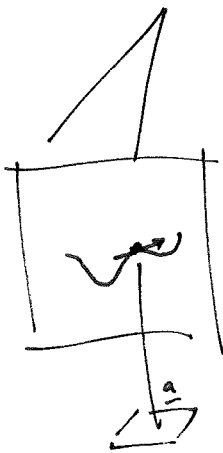
But, knowing it is a local extremum <sup>a</sup> on  $M$  means that along vectors  $\underline{v}$  tangent to  $M$ ,

it is true that  $[D_{\underline{v}}(\underline{a})] = [0]$ .

Rephrased: "derivative vanishes on tangent space to manifold" at <sup>constrained</sup> critical point  $\underline{a}$ .

Theorem:  $M \subseteq \mathbb{R}^n$  manifold.  $f: U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  is  $C^1$  function,  $\underline{c} \in M \cap U$  is a <sup>constrained</sup> local extremum of  $f|_M$ .

then  $T_{\underline{c}} M \subseteq \ker [Df(\underline{c})]$



$T_{\underline{c}} M =$  tangent space to manifold  $\stackrel{\text{def}}{=} \begin{matrix} \text{"slope" in tangent line,} \\ \text{viewed as linear trans.} \end{matrix}$  in that its graph is a subspace of  $\mathbb{R}^n$

Main result in § 3.2 was elegant characterization of  $T_{\underline{c}} M$  as

In general, graph of  $[D\phi(\underline{b})]$

where  $\underline{c} = \begin{bmatrix} \underline{a} \\ \underline{b} \end{bmatrix}$  with  $\underline{b}$  indep. vars.

$\ker [DF(\underline{c})]$  where  $M$  is

$\phi$  implicitly defined with  $\underline{a} = \phi(\underline{b})$ .

zero locus of  $F$ . (Don't be confused here:

$F(\underline{z}) = 0$  defines manifold, locally written as explicit function  $\phi$ .)

so equivalently, the theorem says at constrained critical point.

$$\ker [DF(\underline{c})] \subseteq \ker [D\phi(\underline{c})]$$

$\uparrow$   
(n-k) x n  
if M is a k-manifold

$\uparrow$   
1 x n matrix

Do first example in book (3.7.3)

$f(x,y) = xy$  on unit circle with  $x,y > 0$ . (i.e. in first quadrant)

open quarter of circle is manifold.  
as is any open set of manifold

compute two kernels:  $F = x^2 + y^2 - 1$

$$DF(x_0, y_0) = [2x_0, 2y_0]$$

$$\ker [2x_0, 2y_0] = \begin{bmatrix} a \\ b \end{bmatrix} \text{ such that}$$

$$Df(x_0, y_0) = [y_0, x_0]$$

$$2x_0 a + 2y_0 b = 0.$$

$$(x_0 a + y_0 b) = 0.$$

$$\ker [y_0, x_0] = \begin{bmatrix} a \\ b \end{bmatrix} \text{ such that}$$

$$ay_0 + bx_0 = 0$$

Note: In this case, only possibility

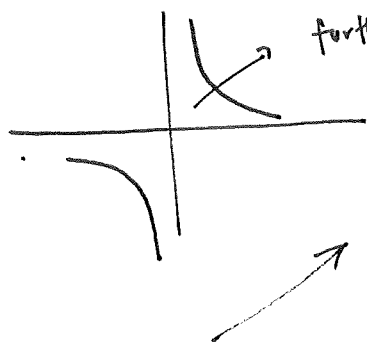
$$\text{is } \ker [DF(\underline{c})] = \ker [Df(\underline{c})]$$

these are lines in  $\mathbb{R}^2 = \{(a,b)\}$   
when are they the same?

We could have predicted this by thinking about when graph  $f(x,y) = xy = m$ .

$xy = m$  is level curve in  $xy$ -plane on which  $f(x,y) = m$ .

Hyperbola.



further we go from origin,  
larger function becomes.

When  $xy = m$  is tangent to unit circle,  
this should be max.

When does  $xy = m$  intersect

$x^2 + y^2 = 1$  in single point?

Substitute:  $x^2 + \left(\frac{m}{x}\right)^2 = 1$

Solve:  $x = \frac{\sqrt{2}}{2} = \cos \pi/4$ .

then  $y$ , on unit circle, is also  $\frac{\sqrt{2}}{2} = \sin \pi/4$ .

i.e.  $x_0 = y_0$  as predicted above.

Criterion seems good start, but seems it may be hard to figure out

what  $\underline{c}$  to choose to get  $\text{Ker}[Df(\underline{c})] \in \text{Ker}[Df(\underline{c})]$

(this is where Lagrange multipliers come in. Give us a checkable condition for when this occurs)

pf. of theorem:  $M$  is locally representable as  $\begin{bmatrix} g(\underline{y}) \\ \underline{y} \end{bmatrix}$   $\underline{y}$  indep. vars in  $\mathbb{R}^k$   
 Write  $\underline{c} = \begin{bmatrix} \underline{a} \\ \underline{b} \end{bmatrix}$  as usual with  $\underline{a} = g(\underline{b})$ .  
 $\tilde{g}: \mathbb{R}^k \rightarrow \mathbb{R}^n$   
 $g(\underline{y}) = \mathbb{R}^k \rightarrow \mathbb{R}^{n-k}$

then if  $\underline{c}$  is constrained critical point we have  $[D(f \circ \tilde{g})(\underline{b})] = [0]$ .

points of  $M$  are image( $\tilde{g}$ )

In other words,  $\underline{b}$  is honest local extremum for composition  $f \circ \tilde{g}$ .

On other hand, we compute  $D(f \circ \tilde{g})$  by chain rule:

$$= \left[ Df(\underbrace{\tilde{g}(\underline{b})}_{\underline{c}}) \right] \left[ D\tilde{g}(\underline{b}) \right] \quad \text{so if this } = 0,$$

$$\text{Ker} [ Df(\underline{c}) ] \supseteq \text{Im} [ D\tilde{g}(\underline{b}) ] = \text{graph of } [ Dg(\underline{b}) ] \\ = T_{\underline{c}}M. \quad //$$

Problem yet to be solved: Find  $\underline{c} \in U \cap M$   
 $\uparrow$  open set w/  $f$  defined  $\leftarrow$  smooth  $\beta$ -Manifold in  $\mathbb{R}^n$

such that  $\text{Ker} [ Df(\underline{c}) ] \supseteq \text{Ker} [ DF(\underline{c}) ]$ .

$\uparrow$   $f: U \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  function we're optimizing so  $Df(\underline{c})$  is  $1 \times n$   
 $\uparrow$   $F: \mathbb{R}^n \rightarrow \mathbb{R}^{n-k}$  so  $DF(\underline{c})$  is  $n-k \times n$ .

As linear transformations, when is  $\text{Ker} [\beta] \supseteq \text{Ker} [A]$   $\beta: 1 \times n$  ?  
 $A: m \times n$ .

Think of  $A$  is  $m$   $1 \times n$  matrices  $\alpha_1, \dots, \alpha_m$

claim:  $\text{Ker} [\beta] \supseteq \text{Ker} [A] \Leftrightarrow \exists \lambda_1, \dots, \lambda_m \in \mathbb{R}$  s.t.  
 $\beta = \lambda_1 \alpha_1 + \dots + \lambda_m \alpha_m$

$(\Leftarrow)$  is immediate

$(\Rightarrow)$  next time...