

Stokes' theorem: $\int_{\partial M X} \varphi = \int_X d\varphi$. Need to understand $d\varphi$ - "exterior derivative" of φ .

$X \subseteq M$ "good"

$\varphi: (k-1)$ form (field) on X

Should generalize FTC: In our language, $X = [a, b] \subseteq \mathbb{R}$.

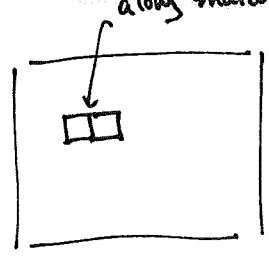
with $\partial_M X = \{a, b\}$ (orientation on b is $+$, on a is $-$)

and φ is 0-form, aka function, call it F .

then $\int_{\partial_M X} F = F(b) - F(a)$. $\int_{[a, b]} dF$ indicates $dF = \frac{d}{dx} F$ (exterior deriv. on F is derivative)

Also want Stokes' theorem to be true, so how to define $d\varphi$ so that it holds? along shared boundary have opposite orientation.

$$\lim_{h \rightarrow 0} \frac{1}{h} (F(x+h) - F(x))$$



define $d\varphi(x)(v_1, \dots, v_k) = \lim_{h \rightarrow 0} \frac{1}{h^k} \int_{\partial P_x(hv_1, \dots, hv_k)} \varphi$

Concept this in a way makes Stokes' theorem believable.

boundary of a k -//ogram is an almost everywhere $(k-1)$ -manifold.

Trouble is: can we compute $d\varphi$ for φ a k -form with $k > 0$.

Amazingly, YES!

Big theorem on computing $d\varphi$, φ a k -form.

① the limit exists if φ is nice:

$$\varphi = \sum_{i_1, \dots, i_k} a_{i_1, \dots, i_k}(x) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

C^2 -functions
on nbhd U

② linearity: φ, ψ k -forms, a, b constants in \mathbb{R} ,

then $d(a\varphi + b\psi) = a d\varphi + b d\psi$.

③ constants: ~~constant forms~~

$$\varphi = \sum_{i_1, \dots, i_k} c_{i_1, \dots, i_k} dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

c_{i_1, \dots, i_k}
constant

"constant form"
since coeffs.
don't depend on

then $d\varphi = 0$

(special case of ⑤ so skippable)

④ df , f : function (aka 0-form):

$$df = [Df] = \sum_{i=1}^n (D_i f) dx_i$$

⑤ Given f , $d(f dx_{i_1} \wedge \dots \wedge dx_{i_k}) = df \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k}$.

All you need:

$$d(e^x \cdot y dx \wedge dz + 2x dy \wedge dz)$$

② $d(e^x y dx \wedge dz) + d(2x dy \wedge dz)$

⑤ $d(\underbrace{e^x y}_{\dots}) \wedge dx \wedge dz + \underbrace{d(2x)}_{2 dx} \wedge dy \wedge dz$

$$d(e^x y) = \underbrace{D_x(e^x y)}_{e^x y} dx + \underbrace{D_y(e^x y)}_{e^x} dy + \underbrace{D_z(e^x y)}_{=0} dz$$

$$\text{so } d(e^x y) \wedge dx \wedge dz = (e^x y dx + e^x dy) \wedge dx \wedge dz$$

$$= \underbrace{e^x y dx \wedge dx \wedge dz}_{=0} + e^x dy \wedge dx \wedge dz$$

(earlier property of wedge product)

$-e^x dx \wedge dy \wedge dz$

Two useful corollaries (both of which follow from big theorem by computation)

Thm 6.7.7 in H-H: φ nice, then $d(d\varphi) = 0$.

Thm. 6.7.9 in H-H: $d(\varphi \wedge \psi) = d\varphi \wedge \psi + (-1)^k \varphi \wedge d\psi$.

(φ, ψ nice, φ a k -form
 ψ an l -form)

0-form field f so df is 1-form.

$$df(x)(v) \stackrel{\text{def}}{=} \lim_{h \rightarrow 0} \frac{1}{h} \int_{\partial P_x(hv)} f = \lim_{h \rightarrow 0} \frac{f(\underline{x} + hv) - f(\underline{x})}{h}$$

$$= [Df(x)]v$$

$$\text{i.e.} = (D_1 f)v_1 + \dots + (D_n f)v_n$$

Harder:

$$d(f dx_{i_1} \wedge \dots \wedge dx_{i_n}) = df \wedge dx_{i_1} \wedge \dots \wedge dx_{i_n}.$$

Translate form to origin. to find value at any particular pt.

Use Taylor expansion for f . $f = f(\underline{0}) + D_1 f(\underline{0})x_1 + \dots + D_n f(\underline{0})x_n$

show that linear term is what contributes to limit.

$$[Df(\underline{0})] \underline{x}$$

+ remainder.

$$\leq C \cdot |\underline{x}|^2 \text{ for some } C$$

Integrate over faces of parallelograms
 $2 \binom{k+1}{k}$ of them.

parametrize them and integrate:

pairs with one vector fixed at $0 \cdot v_i$ or $h \cdot v_i$

other vectors free to roam: $(t_1, \dots, t_k) \mapsto 0 \cdot v_i + t_1 v_1 + \dots + t_k v_{k+1}$

consider orientation.

pairs have cancelling constant terms. Work out linear term.

$$t_j \in [0,1]$$

linear terms of opposing faces:

(need to sum over all indices ~~v_1, \dots, v_{k+1}~~ , let's just pick one, later sum up...)
 omitted indices

$$\int_{[0,1]^k} \phi_i(f) (\gamma_{1,i}(\underline{t}) - \gamma_{0,i}(\underline{t})) dx_{i_1} \wedge \dots \wedge dx_{i_k} (v_1, \dots, \hat{v}_i, \dots, v_{k+1})$$

↑ ↗
params of opposing faces

$|d\underline{t}|$

$$[Df(\underline{0})] (\underbrace{h v_i + \gamma_{0,i}(\underline{t})}_{\gamma_{1,i}(\underline{t})}) - [Df(\underline{0})] \gamma_{0,i}(\underline{t})$$

constant indep. of \underline{t} !

$$= h \cdot [Df(\underline{0})] v_i$$

So summing over all:

$$= \sum_{i=1}^{k+1} (-1)^{i-1} \frac{h^{k+1}}{h^{k+1}} [Df(\underline{0})] v_i (dx_{i_1} \wedge \dots \wedge dx_{i_k}) (v_1, \dots, \hat{v}_i, \dots, v_{k+1})$$

wedge prod formula

$$df \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k} (\underline{0}) (v_1, \dots, \hat{v}_i, \dots, v_{k+1}) \quad \checkmark$$

Easier about this: normally $D\gamma_{i,1}, D\gamma_{i,0}$ inserted into form
 change depending on \underline{t} . Not here since
 program is linear.