

(March 13, 2013)

Smoothing distributions

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[This document is http://www.math.umn.edu/~garrett/m/fun/smoothing_distributions.pdf]

Every locally integrable function f gives a distribution by *integrating against* it, as in

$$\varphi \longrightarrow \int_{\mathbb{R}^n} \varphi(x) f(x) dx \quad (\text{for } \varphi \in C_c^\infty(\mathbb{R}^n))$$

Conversely, we prove here that any distribution u can be approximated arbitrarily well in the weak- $*$ -topology by (integration against) smooth functions. [1] Further, a *sequence* of such smooth functions approaching u can be exhibited in terms of *smoothing* or *mollifying* u .

Let $g \rightarrow T_g$ be the *right regular representation* of \mathbb{R}^n on test functions $f \in C_c^\infty(\mathbb{R}^n)$ by

$$(T_g f)(x) = f(x + g) \quad (\text{for } x, g \in \mathbb{R}^n)$$

One should verify that $x \times f \rightarrow T_x f$ gives a continuous map

$$\mathbb{R}^n \times C_c^\infty(\mathbb{R}^n) \longrightarrow C_c^\infty(\mathbb{R}^n)$$

At various moments, to lighten the notation we suppress the T and write $g \cdot f$ for $T_g f$. The corresponding *adjoint* action of \mathbb{R}^n on distributions u is

$$(T_g^* u)(f) = u(T_g^{-1} f)$$

One should verify that $x \times u \rightarrow x \cdot u = T_x^* u$ is a continuous map

$$\mathbb{R}^n \times C_c^\infty(\mathbb{R}^n)^* \longrightarrow C_c^\infty(\mathbb{R}^n)^*$$

Suppress the T^* and write $g \cdot u$ for $T_g^* u$ whenever this helps readability. The usual action of a function $\varphi \in C_c^\infty(\mathbb{R}^n)$ on distributions u is by *integrating* the group action [2]

$$T_\varphi^* u = \int_{\mathbb{R}^n} \varphi(x) T_x^* u dx \in C_c^\infty(G)^*$$

Suppressing the T^* , this is

$$\varphi \cdot u = \int_{\mathbb{R}^n} \varphi(x) x \cdot u dx \in C_c^\infty(G)^*$$

A **smooth approximate identity** on \mathbb{R}^n is a sequence ψ_i of test functions on \mathbb{R}^n such that

$$\left\{ \begin{array}{l} \int_{\mathbb{R}^n} \psi_i(x) dx = 1 \\ \psi_i(x) \geq 0 \\ \text{supports of the } \psi_i \text{ shrink to } 0 \end{array} \right.$$

[1] It is also true that the smooth functions can be chosen to have *compact support*, but this is not the main point.

[2] The Gelfand-Pettis/weak distribution-valued integral exists because the space of distributions is *quasi-complete* and *locally convex* and the function $x \rightarrow x \cdot u$ is a continuous compactly-supported $C_c^\infty(\mathbb{R}^n)^*$ -valued function.

The last requirement has the meaning that, for every neighborhood N of 0, there is i_o sufficiently large such that for $i \geq i_o$ the support of ψ_i is inside N .

[0.0.1] **Theorem:** For an approximate identity $\{\psi_i\}$ and distribution u , the distributions $\psi_i \cdot u$ go to u in the weak- $*$ -topology on $C_c^\infty(\mathbb{R}^n)^*$, and are (integration against) the functions $x \rightarrow u(T_x^{-1}\psi_i)$, which are *smooth functions*.

Proof: First, we prove that $\psi_i \cdot u \rightarrow u$ as distributions. Let U be any *convex*^[3] open neighborhood of 0 in $C_c^\infty(\mathbb{R}^n)^*$. Let N be a sufficiently small neighborhood of 0 in \mathbb{R}^n such that under

$$\mathbb{R}^n \times C_c^\infty(\mathbb{R}^n)^* \longrightarrow C_c^\infty(\mathbb{R}^n)^*$$

we have

$$N \times u \longrightarrow N \cdot u \subset u + \frac{1}{2}U$$

For i sufficiently large so that the support of ψ_i is inside N , the measure $\psi_i(x) dx$ is a probability measure supported in N , so by Gelfand-Pettis

$$\psi_i \cdot u \in \text{closure of convex hull of image of } \psi_i(x) x \cdot u$$

Since $u + U' + \frac{1}{2}U$ contains the closure of the convex set $u + \frac{1}{2}U$ for any open U' containing 0 (in $C_c^\infty(\mathbb{R}^n)^*$), this shows that

$$\psi_i \cdot u \in u + U$$

This holds for all open neighborhoods U of 0, so $\psi_i \cdot u \rightarrow u$.

To prove that every $f \cdot u$ for $f \in C_c^\infty(\mathbb{R}^n)$ is (integration against) a *continuous* or *smooth* function, we first guess what that continuous function is, by telling its point-wise values. Indeed, if $u = u_\varphi$ were known to be integration against a continuous function φ , then with an approximate identity $\{\psi_i\}$

$$\lim_i u_\varphi(\psi_i) = \lim_i \int_{\mathbb{R}^n} \varphi(x) \psi_i(x) dx = \varphi(0)$$

Thus, we anticipate determining values of the alleged continuous function $f \cdot u$ by computing

$$\text{alleged value } (f \cdot u)(0) = \lim_i (f \cdot u)(\psi_i)$$

For a continuous function F on \mathbb{R}^n , let

$$F^\vee(x) = F(-x)$$

For for f and ψ in $C_c^\infty(\mathbb{R}^n)$, using the fundamental fact that Gelfand-Pettis integrals commute with continuous linear maps, compute

$$\begin{aligned} (f \cdot u)(\psi) &= \left(\int_{\mathbb{R}^n} f(x) x \cdot u dx \right) (\psi) = \int_{\mathbb{R}^n} f(x) (x \cdot u)(\psi) dx \\ &= \int_{\mathbb{R}^n} f(x) u(T_x^{-1} \cdot \psi) dx = u \left(\int_{\mathbb{R}^n} f(x) (T_x^{-1} \cdot \psi) dx \right) = u \left(\int_{\mathbb{R}^n} f(-x) (x \cdot \psi) dx \right) = u(f^\vee \cdot \psi) \end{aligned}$$

Note that at one point we used the fuller notation to avoid the confusing notation $-x \cdot \psi$. The function $f^\vee \cdot \psi$ admits a rewriting that reverses the roles of f and ψ , namely

[3] The fact that 0 has a local basis of *convex* open neighborhoods is the local convexity of the space of distributions.

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$$\begin{aligned} (f^\vee \cdot \psi)(y) &= \int_{\mathbb{R}^n} f(-x) \psi(y+x) dx = \int_{\mathbb{R}^n} f(y-x) \psi(x) dx \\ &= \int_{\mathbb{R}^n} f(y+x) \psi(-x) dx = \int_{\mathbb{R}^n} f(y+x) \psi^\vee(x) dx = (\psi^\vee \cdot f)(y) \end{aligned}$$

Thus,

$$(f \cdot u)(\psi) = u(f^\vee \cdot \psi) = u(\psi^\vee \cdot f) = (\psi \cdot u)(f)$$

We already know that $\psi_i \cdot u \rightarrow u$ for an approximate identity ψ_i , so the limit exists, and has an understandable value:

$$(f \cdot u)(\psi_i) = (\psi_i \cdot u)(f) \rightarrow u(f) = \text{supposed value of } f \cdot u \text{ at } 0$$

Thus, we would guess that $f \cdot u$ should be a function with value $u(f)$ at 0. More generally, for the distribution u_φ given by integration against φ , we have

$$(T_z^* u_\varphi)(\psi_i) = u_\varphi(T_z^{-1} \psi_i) = \int_{\mathbb{R}^n} \varphi(x) \psi_i(x-z) dx = \int_{\mathbb{R}^n} \varphi(x+z) \psi_i(x) dx \rightarrow \varphi(z)$$

Then do the analogous computation to guess the values of the function $f \cdot u$ at z . First, a more elaborate version of the identity reverses the roles of test functions f and φ , namely

$$\begin{aligned} (f^\vee \cdot T_z^{-1} \psi)(y) &= \int_{\mathbb{R}^n} f(-x) \psi(y+x-z) dx = \int_{\mathbb{R}^n} f(y-x-z) \psi(x) dx \\ &= \int_{\mathbb{R}^n} f(y+x-z) \psi(-x) dx = \int_{\mathbb{R}^n} (T_z^{-1} f)(y+x) \psi^\vee(x) dx = (\psi^\vee \cdot T_z^{-1} f)(y) \end{aligned}$$

The same sort of computation gives

$$\begin{aligned} (T_y^*(f \cdot u))(\psi_i) &= (f \cdot u)(T_y^{-1} \psi_i) = u(f^\vee \cdot T_y^{-1} \psi_i) = u(\psi_i^\vee \cdot T_y^{-1} f) \\ &= (T_y^*(\psi_i \cdot u))(f) \rightarrow (T_y^* u)(f) = u(T_y^{-1} f) = \text{supposed value of } f \cdot u \text{ at } y \end{aligned}$$

Since $\mathbb{R}^n \times C_c^\infty(\mathbb{R}^n) \rightarrow C_c^\infty(\mathbb{R}^n)$ is continuous, and u is continuous, the composition

$$y \times f \longrightarrow T_y^{-1} f \longrightarrow u(T_y^{-1} f)$$

is indeed *continuous* as a function of $y \in \mathbb{R}^n$.

Now we check that the distribution $f \cdot u$ is truly given by integration against the continuous function

$$\varphi(y) = u(T_y^{-1} f)$$

that apparently gives the pointwise values of $f \cdot u$. Letting $h \in C_c^\infty(\mathbb{R}^n)$,

$$\int_{\mathbb{R}^n} \varphi(x) h(x) dx = \int_{\mathbb{R}^n} u(T_x^{-1} f) h(x) dx = \left(\int_{\mathbb{R}^n} h(x) x \cdot u dx \right) (f) = (h \cdot u)(f)$$

We already computed directly that

$$(h \cdot u)(f) = u(h^\vee \cdot f) = u(f^\vee \cdot h) = (f \cdot u)(h)$$

which shows that integration against the continuous function $\varphi(y) = u(T_y^{-1} f)$ gives the distribution $f \cdot u$.

Smoothness of $\varphi(y) = u(T_y^{-1} f)$ would follow from the assertion that $y \rightarrow T_y^{-1} f$ is a smooth, $C_c^\infty(\mathbb{R}^n)$ -valued function. The latter assertion is existence of the limit

$$\lim_{t \rightarrow 0} \frac{T_{y+tX}^{-1} f - T_y^{-1} f}{t} \quad (\text{for } X \in \mathbb{R}^n \text{ and } y \in \mathbb{R}^n)$$

in $C_c^\infty(\mathbb{R}^n)$ for each $X \in \mathbb{R}^n$. Clearly it suffices to consider $y = 0$. Then the fact that, by design, differentiation is a continuous map of $C_c^\infty(\mathbb{R}^n)$ to itself, is the requisite *smoothness*. ///

[0.0.2] Remark: Note that the proof of the fact that $\psi_i \cdot u \rightarrow u$ did not use the specifics of the situation: the same argument applies to representations of Lie groups.

[0.0.3] Remark: Although we could have verified that the distribution $f \cdot u$ is given by integration against $u(T_x^{-1}f)$, it is worthwhile to see that one can *infer* this. That is, given the idea that $f \cdot u$ has been *smoothed*, determination of it as a classical function is straightforward.
