Rehg, CVPR13 Prabhaker, ECCV12 Prabhakar, CVPR12 Patron-Perez, BMVC10



Lan, CVPR12 Ding, ECCV10
Ramanathan, CVPR13 Choi, ECCV12, CVPR14
Antic, ECCV14 Direkoglu, ECCV12



Rodriguez, ICCV11a, ICCVb Mehran, CVPR09 Alahi, CVPR14



Yang, CVPR12 Hoai, CVPR14



Choi, ECCV14 Park, NIPS12, ICCV13

Cristani, BMVC11
Park, CVPR15
Arey, SIGGRAPH1

Wang, ECCV10 Gallagher, CVPR09

Dyadic interaction

Crowd interaction

Number of group members







Mehran, CVPR09





Dyadic interaction

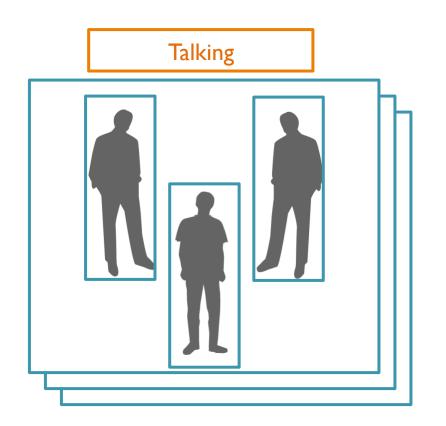
Crowd interaction

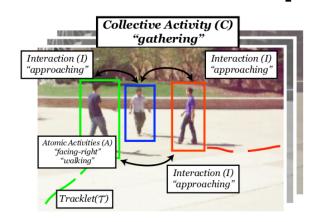
Number of group members

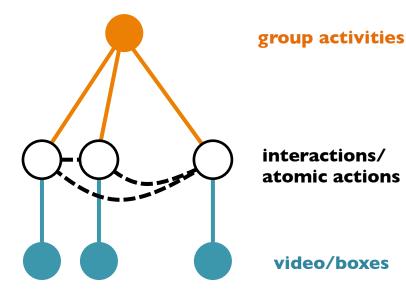
Group Activities in Videos

[Choi VSWS09, CVPR I I, ECCV I 2, Lan WSGA09, NIPS I 0, Khamis CVPR I 2, ECCV I 2]

Input: video and box tracks
Output: group activity labels in time







Collective Activities

Definition:

Activities that are defined or reinforced by the existence of a coherent behavior of a group of individuals in time and space.

Waiting



Queuing



Talking



Individual Appearance





 Individual appearance/motion does not provide an important social signal to recognize collective activities.

Crowd Context



• Contextual relationship among people is the key signal to recognize collective activities.

Challenges

- Large intra-class variation.
 - View point variation.
 - Number of group participants.
- Multiple groups in the scene.
- Activities changes over time.

Key Modules

- Crowd Context and the Representation.
 - Individual posture representation.
 - Encoding the context with posture representation.

- Exploit spatial-temporal correlations.
 - Utilize the structure in group activities.

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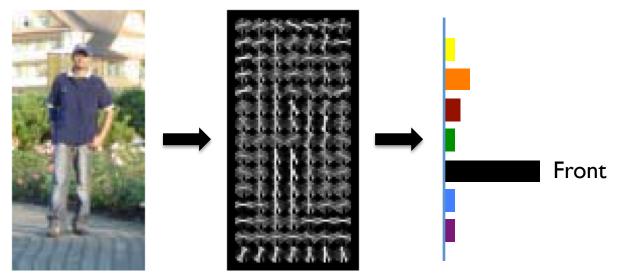
Crowd Context: How-to

- Given trajectories (boxes over time) of people.
- Represent each individual box with a posture description:
 - Combination of view point and velocity.
 - Finite set of activity labels.
 - A bag of mid-level discriminative parts.
- Encode the context using a spatio-temporal descriptor.



Individual Posture Representation

- Extract a feature (e.g. HoG) in a bounding box.
- Represent the box in a posture space (e.g. SVM).



Dalal and Triggs, CVPR 2005

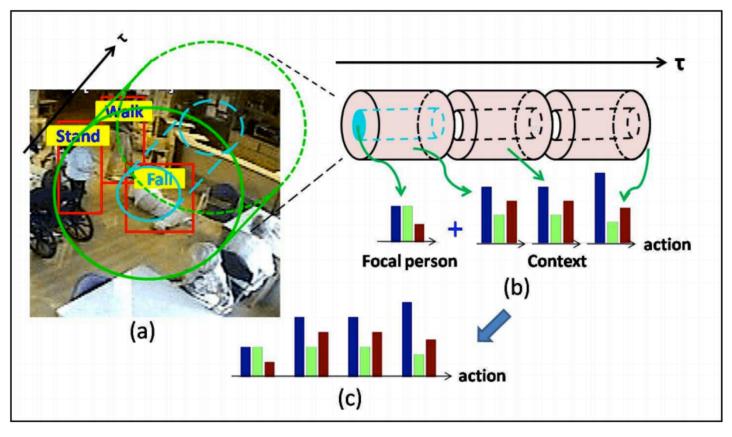
Simple and well-studied.

Require the definition and annotation of the posture space.

Encoding the Context

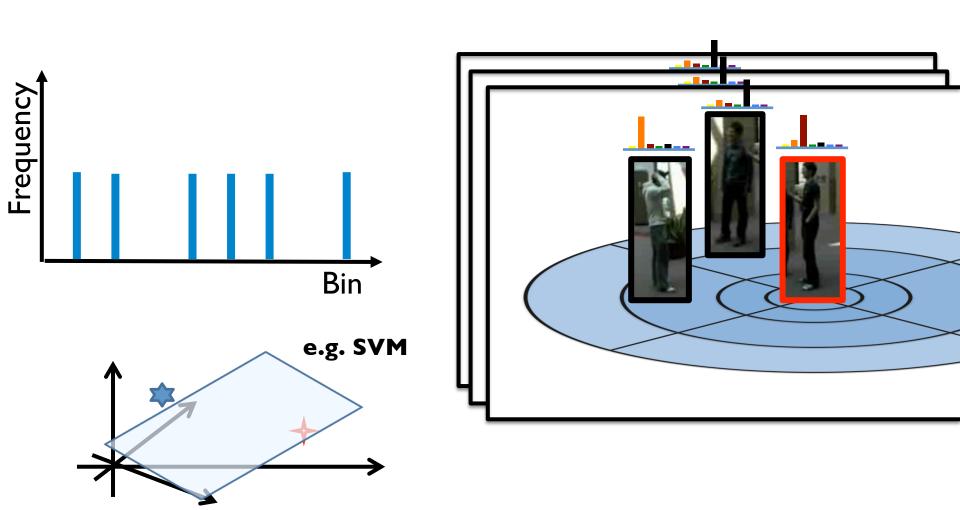
- Given a person of interest (anchor), aggregate the posture information of the others around the anchor person.
- Common ideas:
 - Define spatio-temporal support regions.
 - Pull the features in the space.

Encoding Context: Action Context

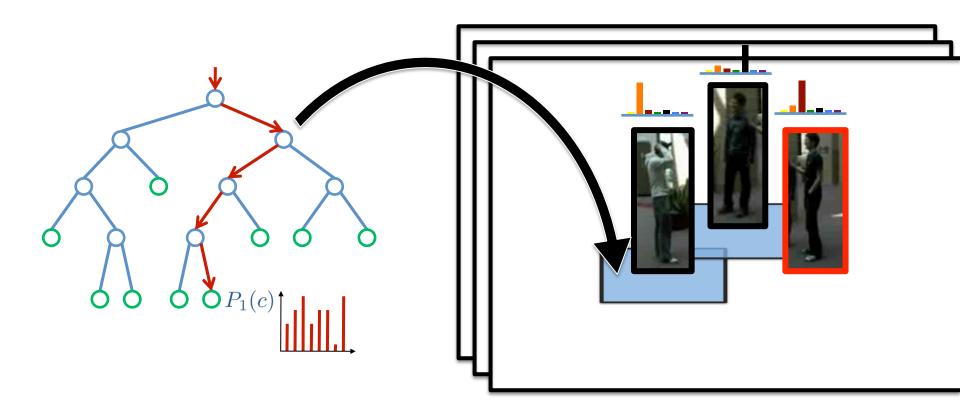


$$C_i = \left[\max_{j \in \mathcal{N}_1(i)} S_{1j}, \dots, \max_{j \in \mathcal{N}_1(i)} S_{Kj}, \dots, \max_{j \in \mathcal{N}_M(i)} S_{1j}, \dots, \max_{j \in \mathcal{N}_M(i)} S_{Kj} \right]$$

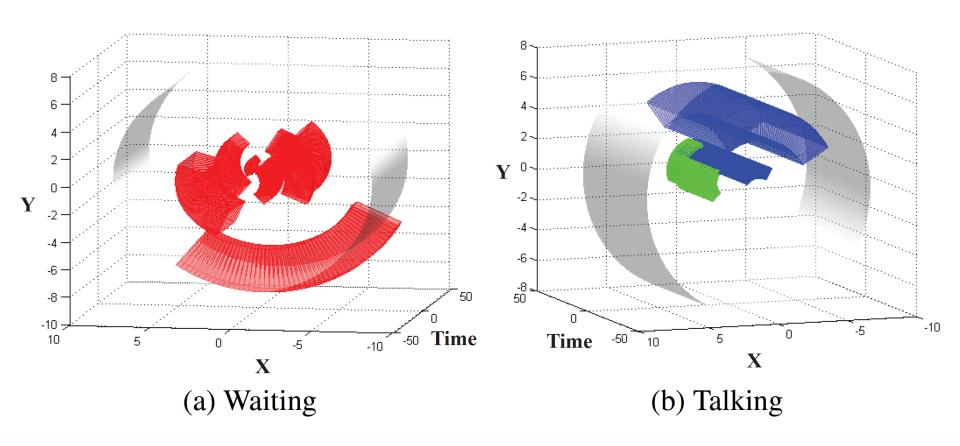
Encoding Context: Spatio-Temporal Local (STL) Descriptor



Encoding Context: Learning the Contextual Model



Learning the Contextual Model





Red: Facing forward, Blue: Facing down, Green: Facing right

Collective Activity Dataset

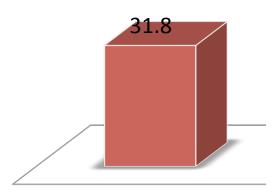
- 44 videos with multiple people.
- Crossing, Waiting, Queuing, Walking, Talking.
- Leave-One-Video-Out.

Atomic Activity Feature v.s. Crowd Context

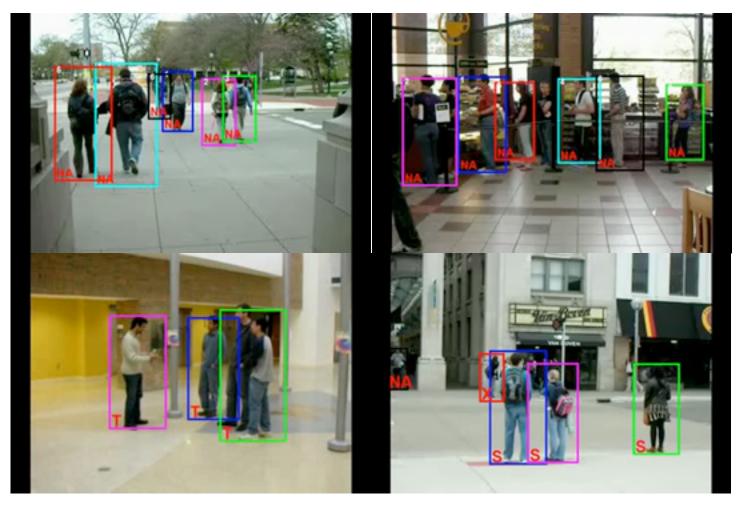
Classification Accuracy

■ STIP (Baseline)





Qualitative Examples



X: Crossing, S: Waiting, Q: Queuing, W: Walking, T: Talking

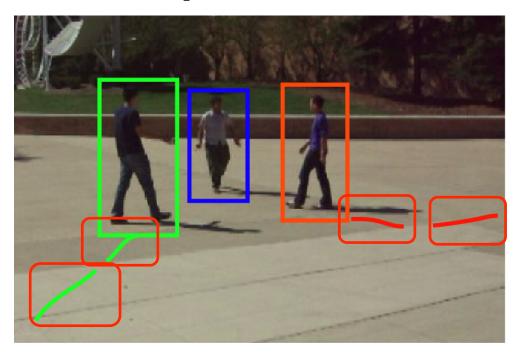
Key Modules

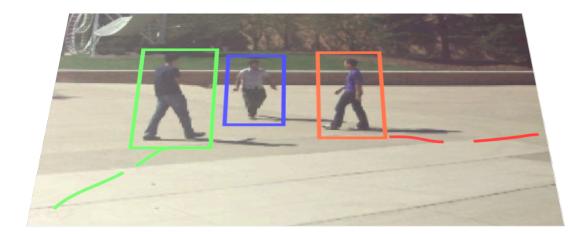
- Crowd Context and the Representation.
 - Individual posture representation.
 - Encoding the context with posture representation.

- Exploit spatial-temporal correlations.
 - Utilize the structure in group activities.

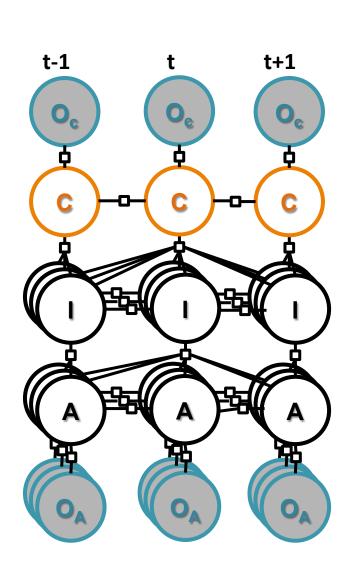
Hierarchical Activity Model

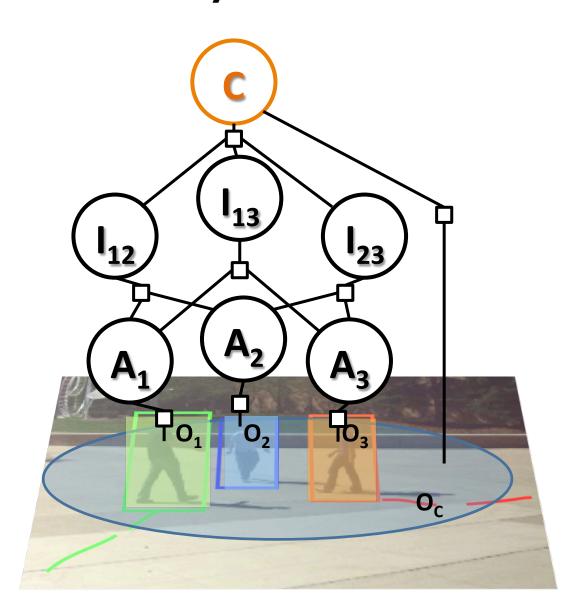
Input: video with tracklets



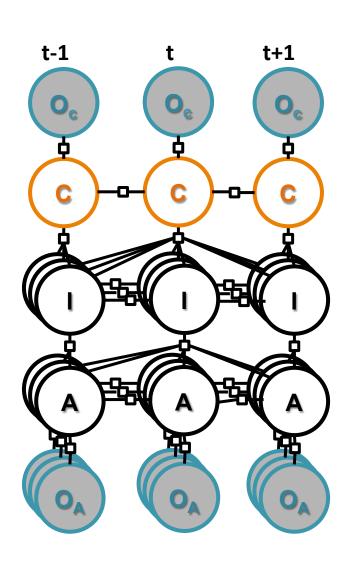


Hierarchical Activity Model





Hierarchical Activity Model

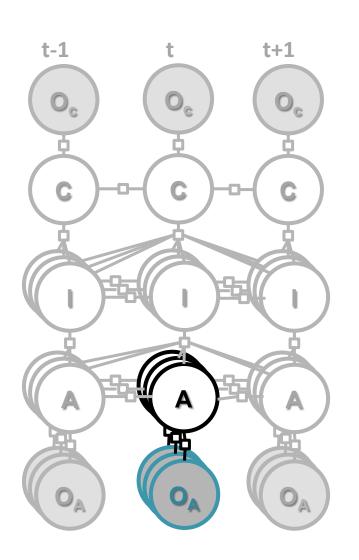


$$Ψ(C, I, A, O, f) =$$

$$Ψ(A, O) + Ψ(I, A, f) + Ψ(C, I) + Ψ(C, O) +$$

$$Ψ(C) + Ψ(I) + Ψ(A) - cTf, f ∈ S$$

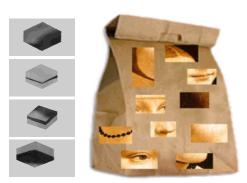
Atomic-Observation Potential



$$\Psi(C, I, A, O, f) =
\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +
\overline{\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f}, f \in S$$

Atomic Activity Models

- Action: BoW with STIP
- Pose: HoG

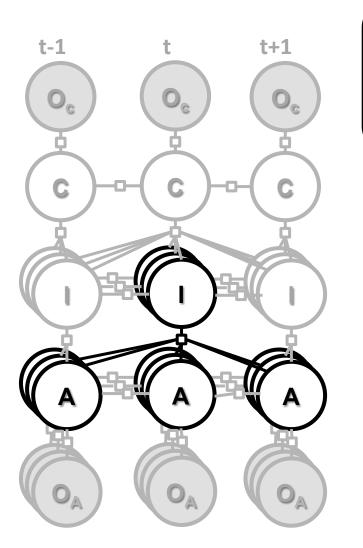


Dollar et al, 06; Niebles et al, 07



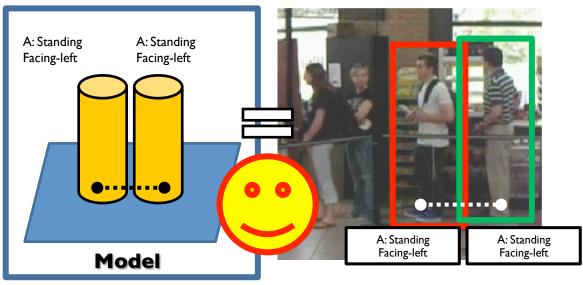
Dalal and Triggs, 05

Interaction-Atomic Potential

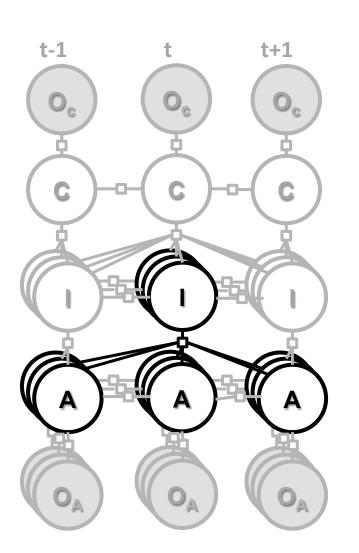


$$\Psi(C, I, A, O, f) =
\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +
\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f, f \in S$$

I: Standing-in-a-line

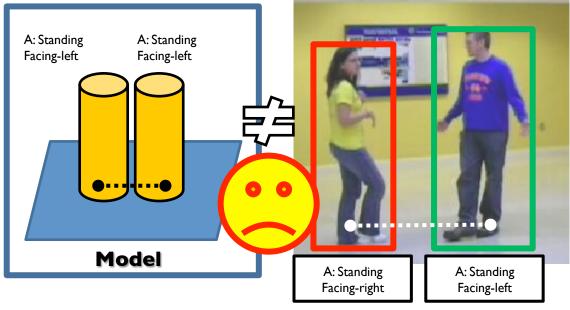


Interaction-Atomic Potential

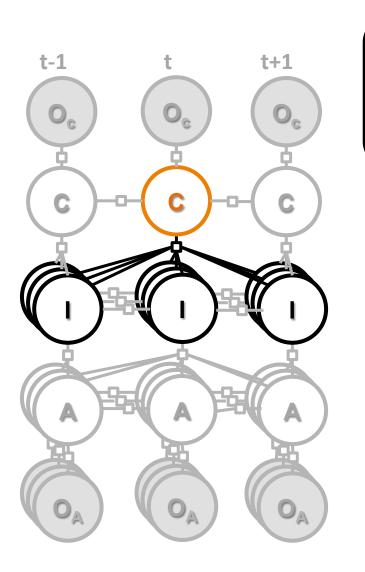


$$\Psi(C, I, A, O, f) =
\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +
\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f, f \in S$$

I: Standing-in-a-line

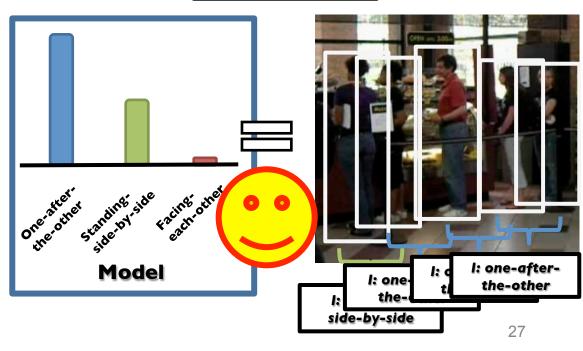


Collective-Interaction Potential

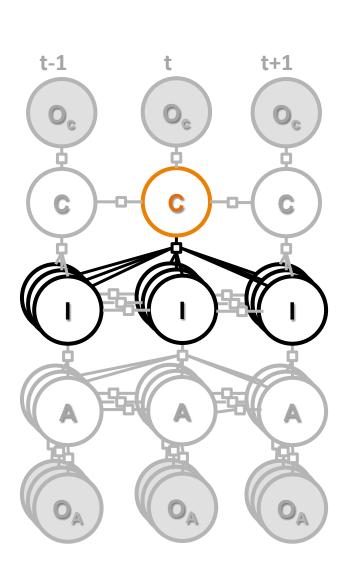


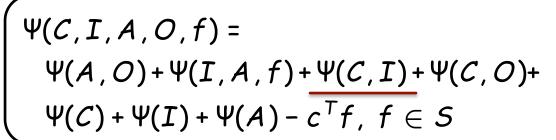
$$\Psi(C, I, A, O, f) =
\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +
\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f, f \in S$$

C: Queuing

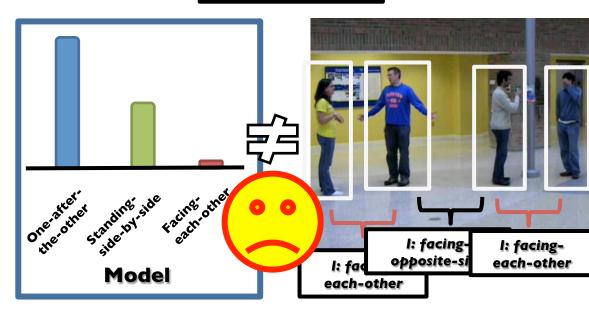


Collective-Interaction Potential

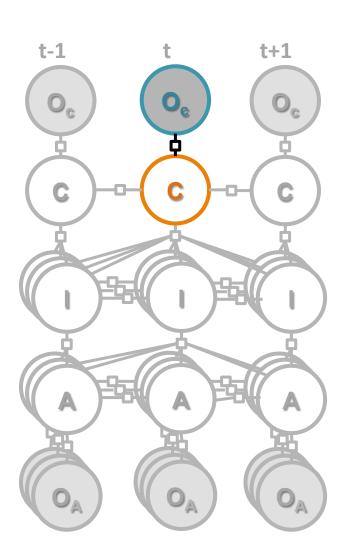




C: Queuing



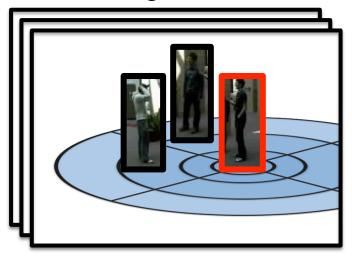
Collective-Observation Potential



$$\Psi(C, I, A, O, f) =
\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +
\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f, f \in S$$

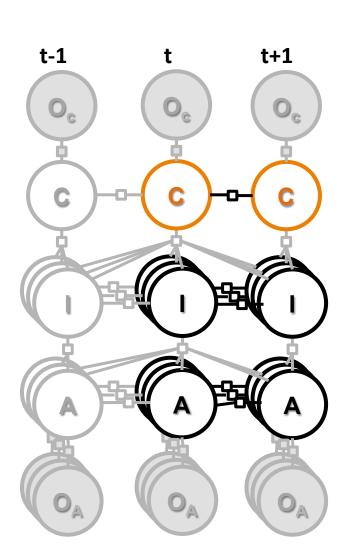
Collective Activity

STL of all targets



Choi et al, 09

Activity Transition Potential



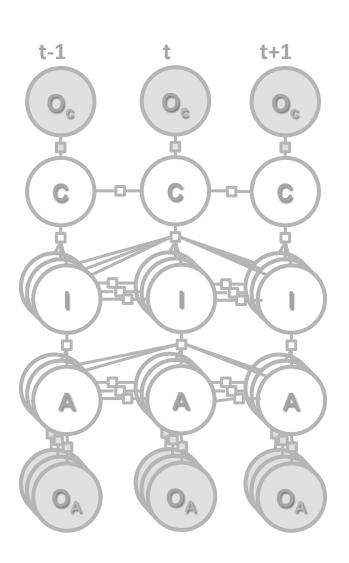
$$Ψ(C, I, A, O, f) =$$

$$Ψ(A, O) + Ψ(I, A, f) + Ψ(C, I) + Ψ(C, O) +$$

$$Ψ(C) + Ψ(I) + Ψ(A) - cTf, f ∈ S$$

Smooth activity transition

Trajectory Estimation



$$\Psi(C, I, A, O, f) =$$

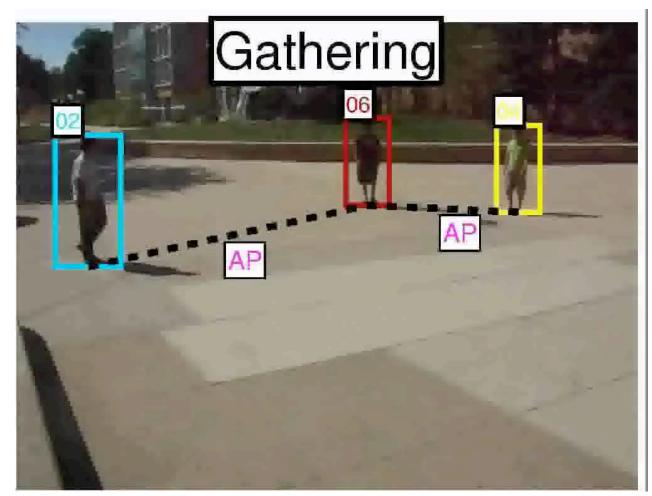
$$\Psi(A, O) + \Psi(I, A, f) + \Psi(C, I) + \Psi(C, O) +$$

$$\Psi(C) + \Psi(I) + \Psi(A) - c^{T}f, f \in S$$

Training the Graphical Model

 Model weights can be learned in a Max-Margin framework using Structural SVM.

$$\begin{aligned} & \min_{\mathbf{w}, \boldsymbol{\xi}} & \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C}{n} \sum_{i=1}^n \xi_i, \text{ s.t. } \forall i, \xi_i \geq 0 \\ & \forall i, \ \forall \mathbf{y} \in \mathcal{Y} \setminus \mathbf{y}_i : \ \langle \mathbf{w}, \delta \Psi_i(\mathbf{y}) \rangle \geq \triangle(\mathbf{y}_i, \mathbf{y}) - \xi_i \end{aligned}$$
Tsochantaridis et al, 2004



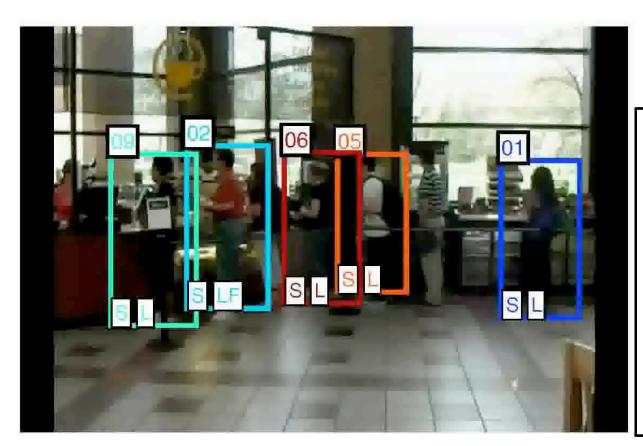
Interaction labels

AP: approaching

FE: facing-each-other

SR: standing-in-a-row

••



Atomic Activities

Action:

W - walking

S – standing

Pose (8 directions)

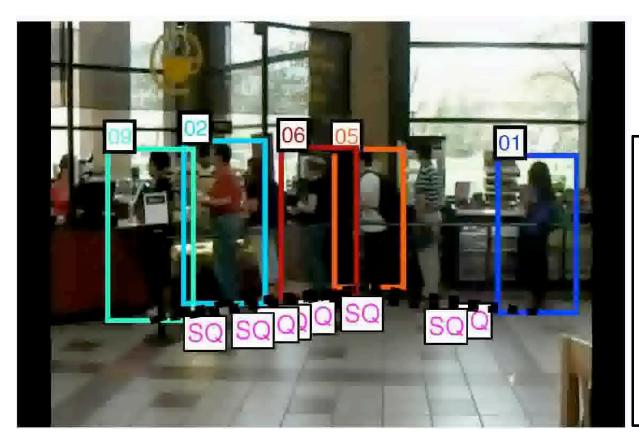
L - left

LF- left/front

F – front

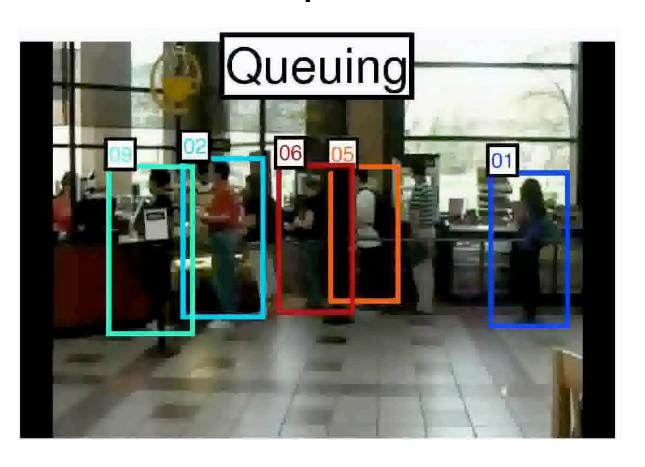
RF- right/front

etc.



Pair-Interactions

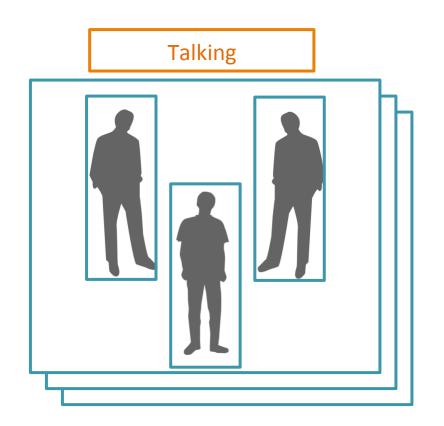
- AP: approaching
-
- FE: facing-each-other
- SS: standing-side-by-side
- SQ: standing-in-a-queue

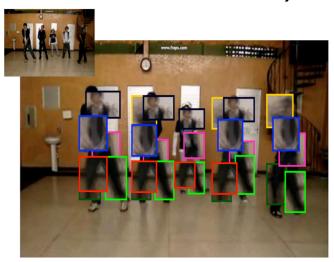


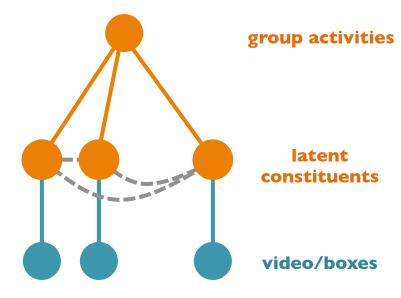
Learning Latent Constituents for Group Activity Recognition (Antic ECCV14)

Input: video and box tracks

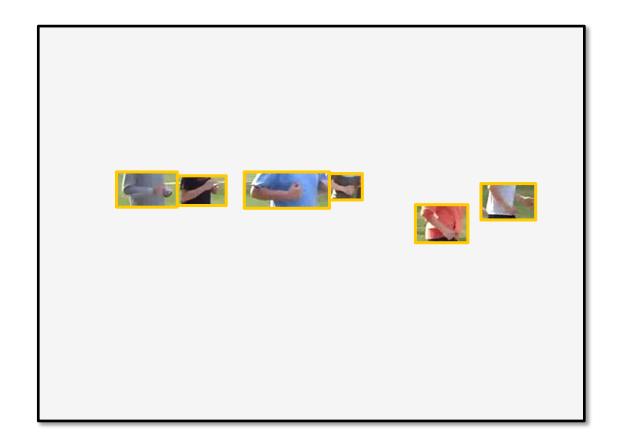
Output: group activity labels in time



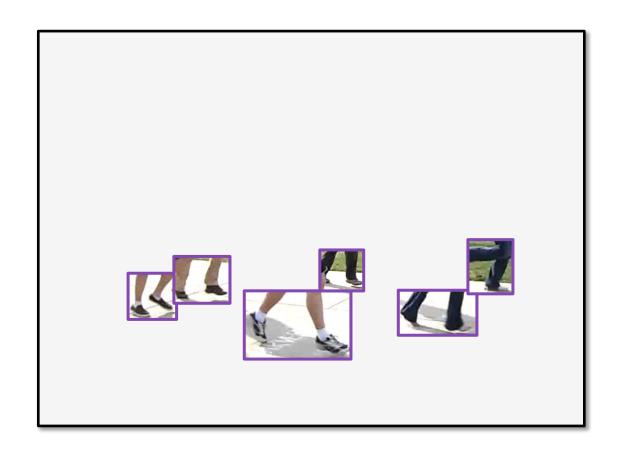




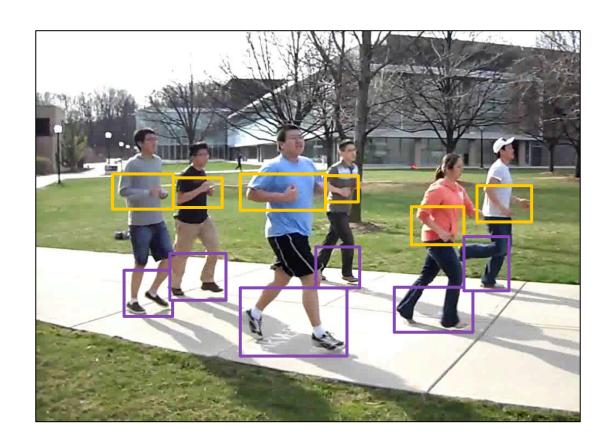
Meaningful Parts of Group Behavior



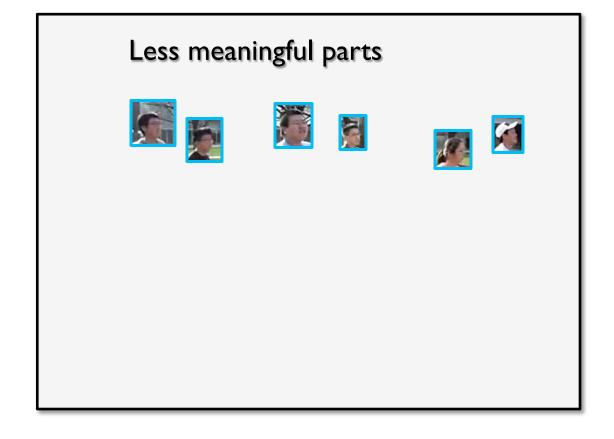
Meaningful Parts of Group Behavior



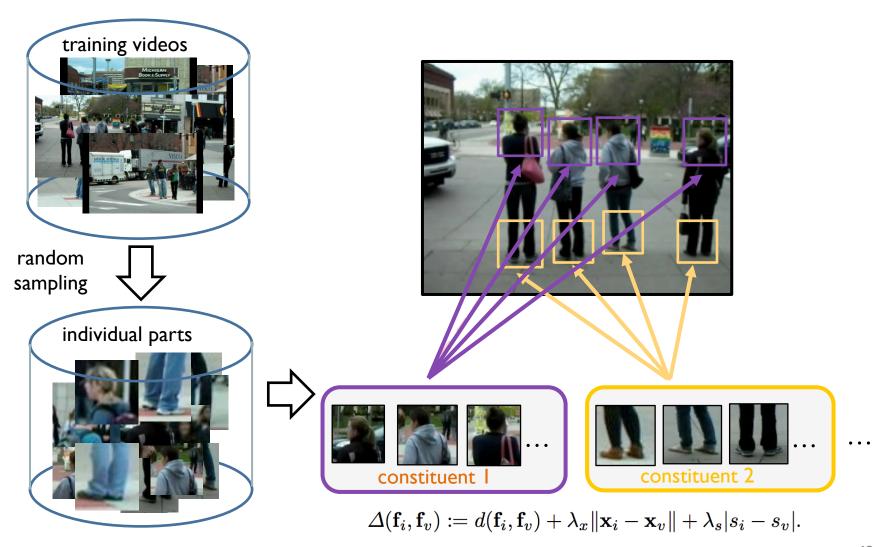
Meaningful Parts of Group Behavior



Less Meaningful Parts



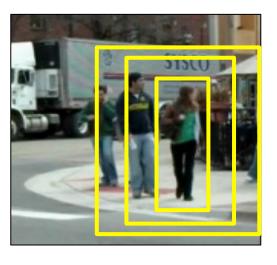
Learning Mid-level Constituents

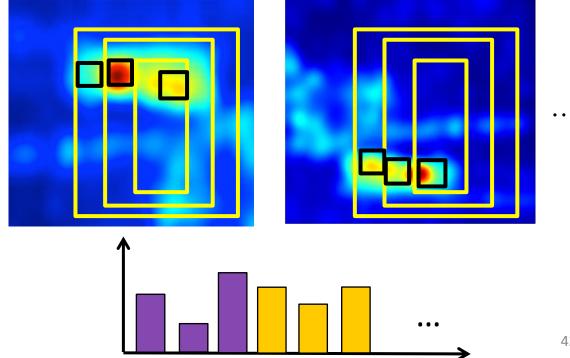


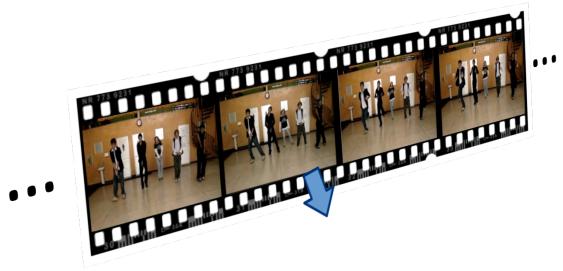
Encoding Social Signal with Latent Constituents

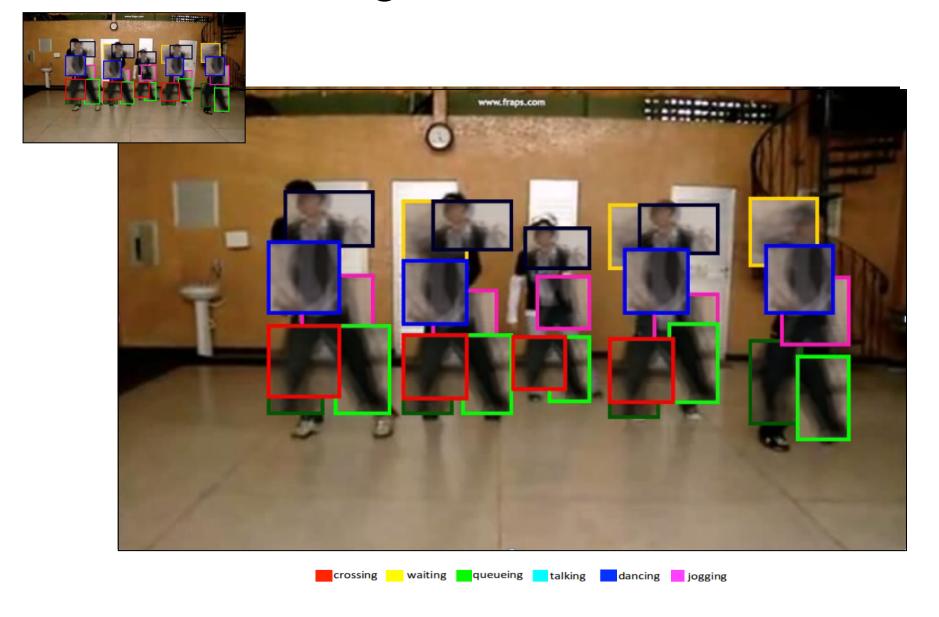


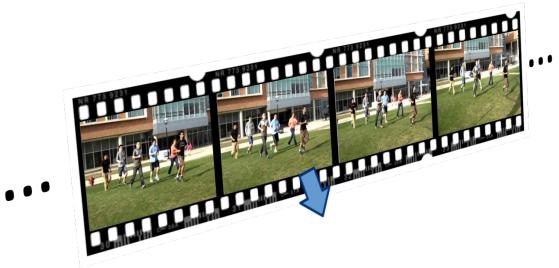


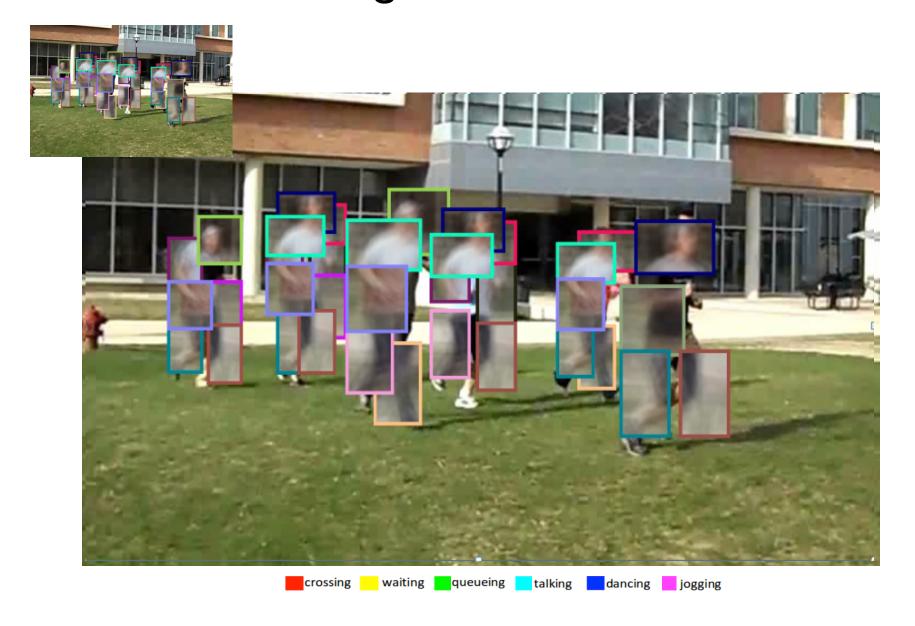




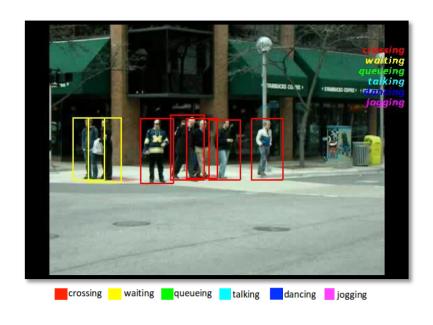








Quantitative Evaluation



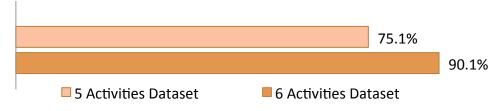
Holistic approach (full b-boxes):



70.4%

Latent constit's (functional grouping):





Social Role Discovery (Ramanathan CVPR 13)

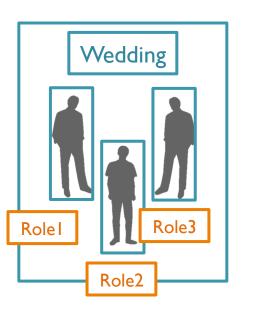
Input: videos with event labels, box tracks
Output: groups with activity label

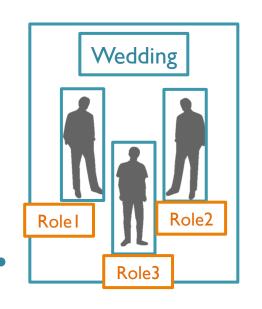


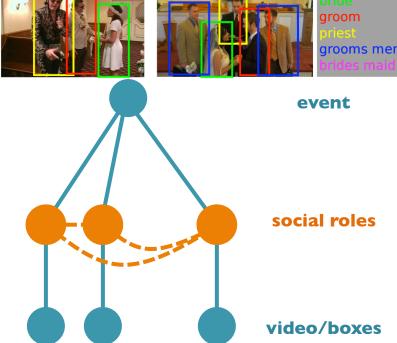


b'day person parents friends guests

WEDDING





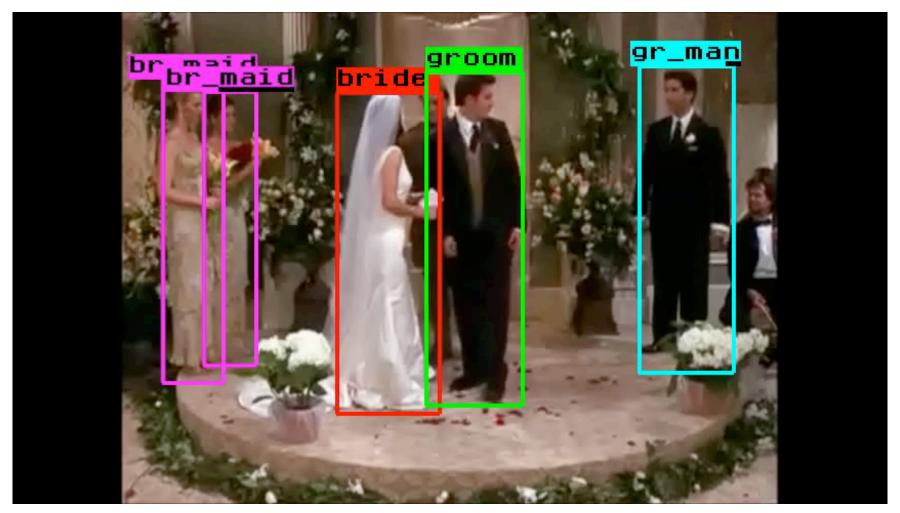


Humans in Social Setting



Slide from Ramanathan et al, 2013

Goal: Identify social roles

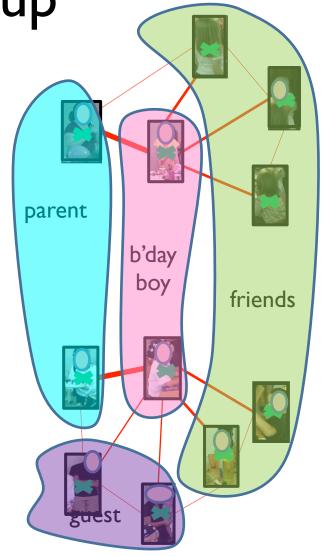


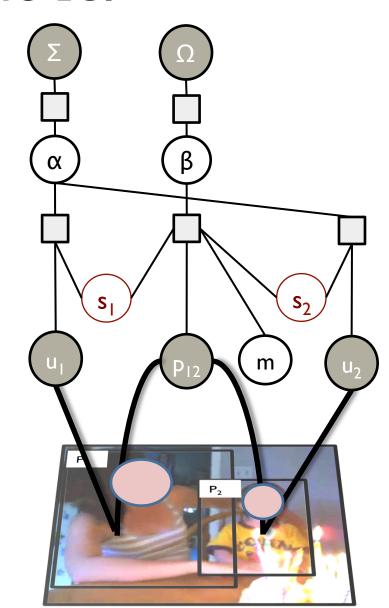
Problem setup



- lacktriangle

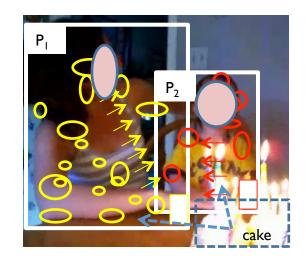


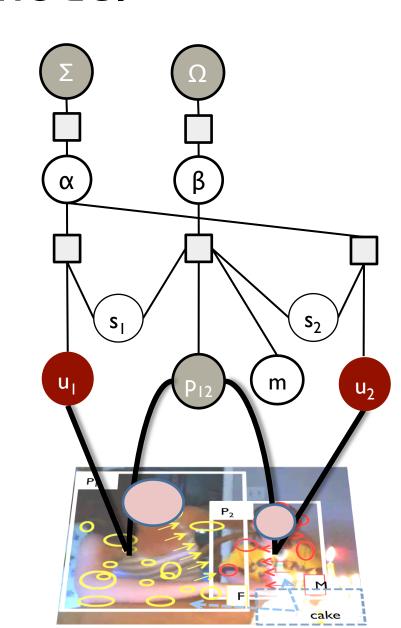




Person-specific features

- Role specific actions
 - **HOG3D** from person tube
 - Trajectory of person
- Color and Gender features
- Object interaction features

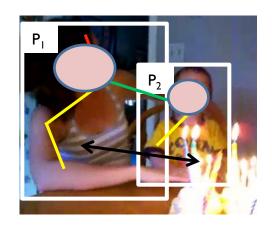


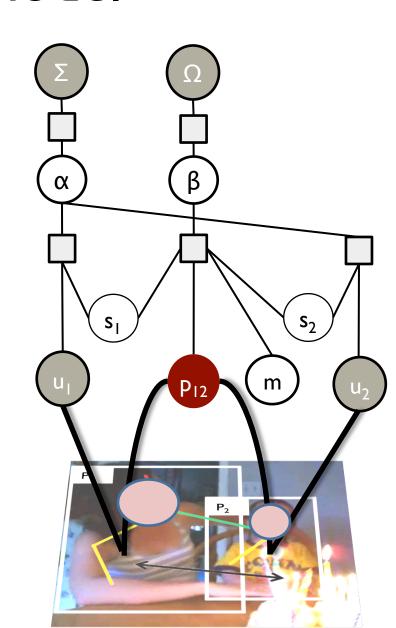


Person-specific features

Inter-role features

- Spatio-temporal features
- Proxemic features

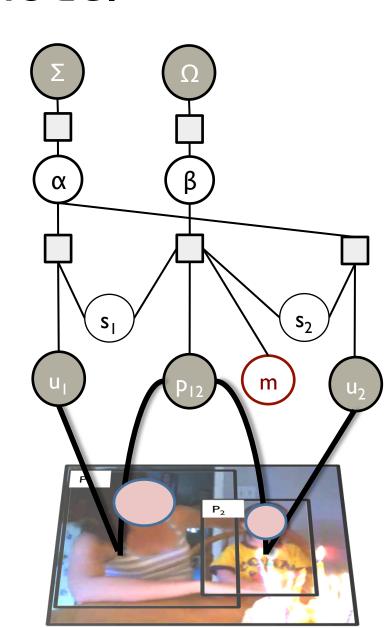




Person-specific features
Inter-role features

Reference role

only interactions with reference considered for tractable inference



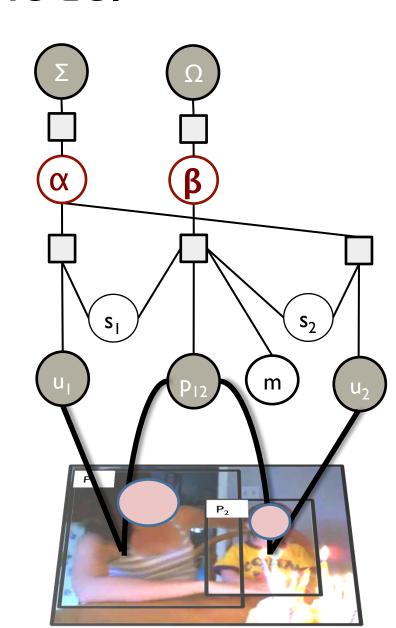
Person-specific features
Inter-role features

Reference role

Model parameters

 α is the person-specific feature weight

(eta) is the inter-role feature weight



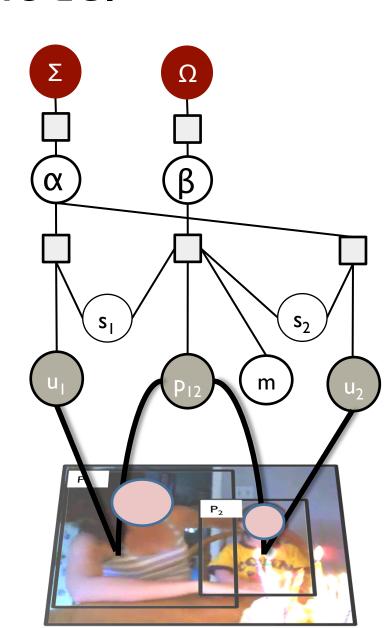
Person-specific features
Inter-role features
Reference role

Model parameters

 (α) is the person-specific feature weight

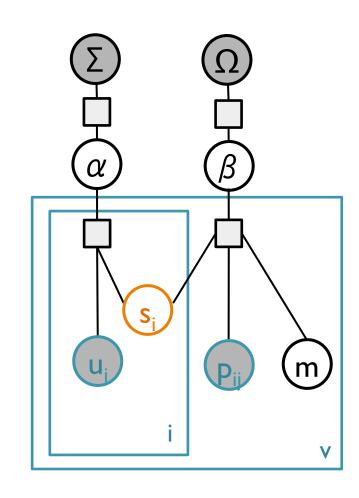
 β is the inter-role feature weight

Gaussian priors for regularization



Variational Inference

Jointly Learn model parameters.
Assign social roles.



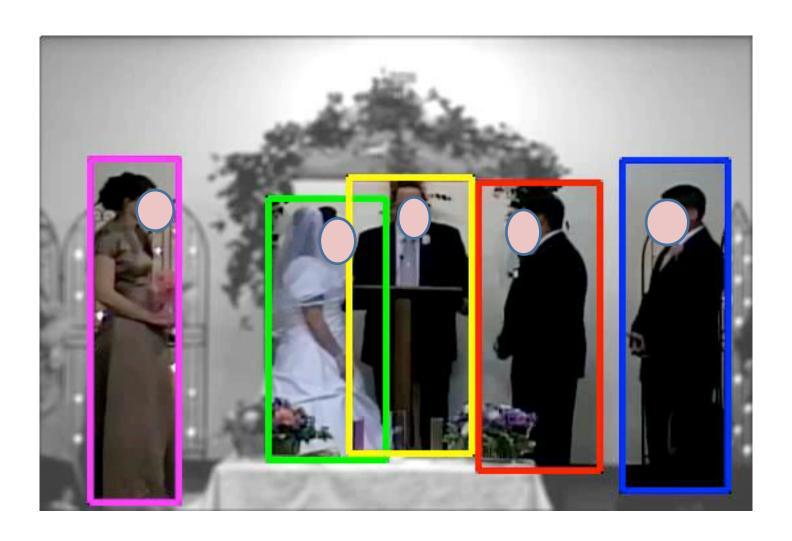
Dataset

- Youtube Social Role Dataset
 - Available at http://vision.stanford.edu/vigneshr release data/
 youtube CVPRI3 social.tar.gz
 - Only the event type is provided.
 - Social roles are discovered in unsupervised fashion.

Results: role clusters



Results: role clusters



Results: role clusters



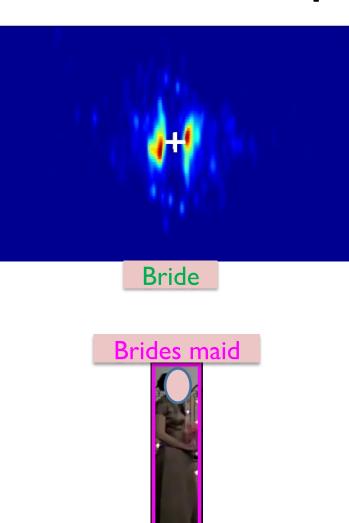






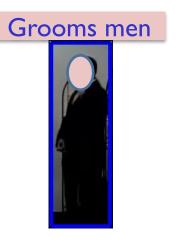


Spatial Relations

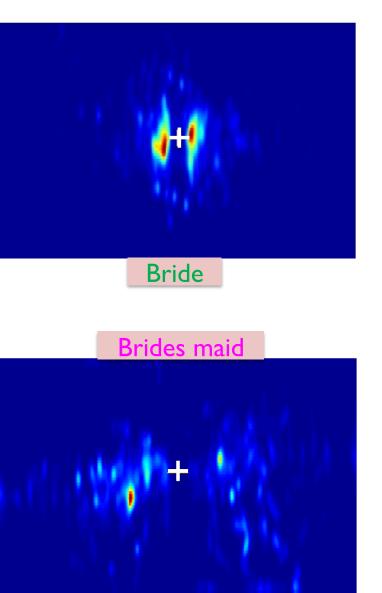




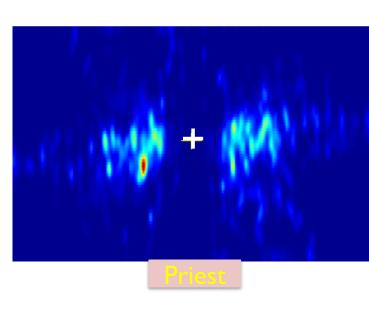


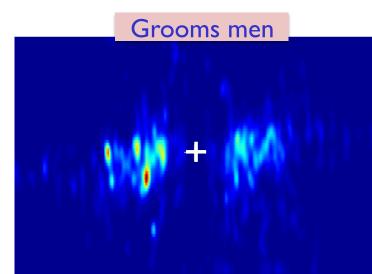


Spatial Relations



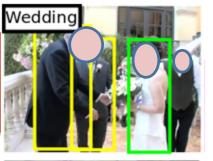


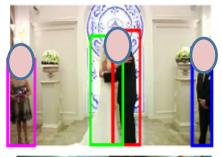




Results – Role clusters

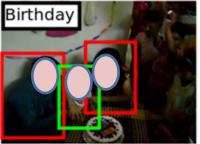
bride groom grooms men brides maid



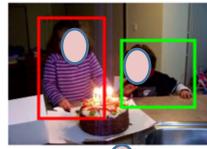




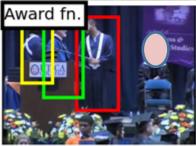
b'day person parent guest

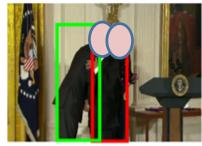


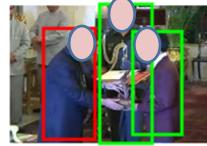




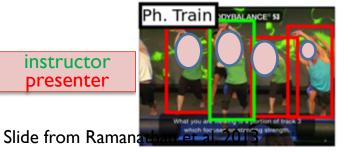
presenter recipient distributor

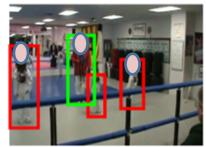






instructor presenter



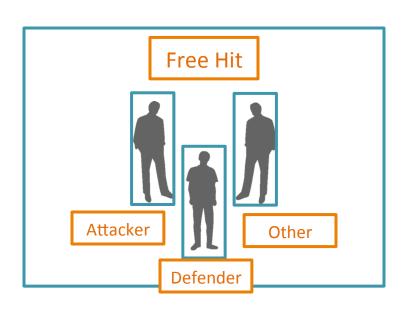


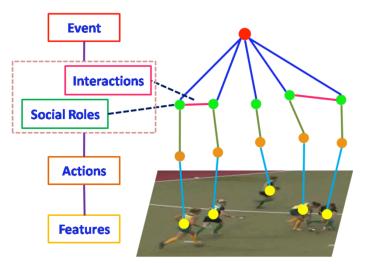


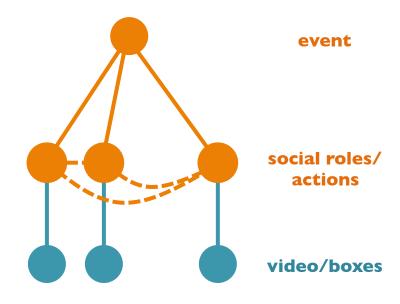
Social Role Discovery (Lan CVPR12)

Input: a video with box tracks

Output: social role and activity labels







Semantic Description of Videos



actions

walk run jog bend shoot dribble social roles

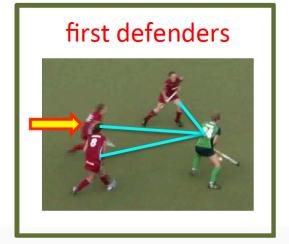
attacker first defender man-marking defend-space Teammate event

corner-hit free-hit attack play

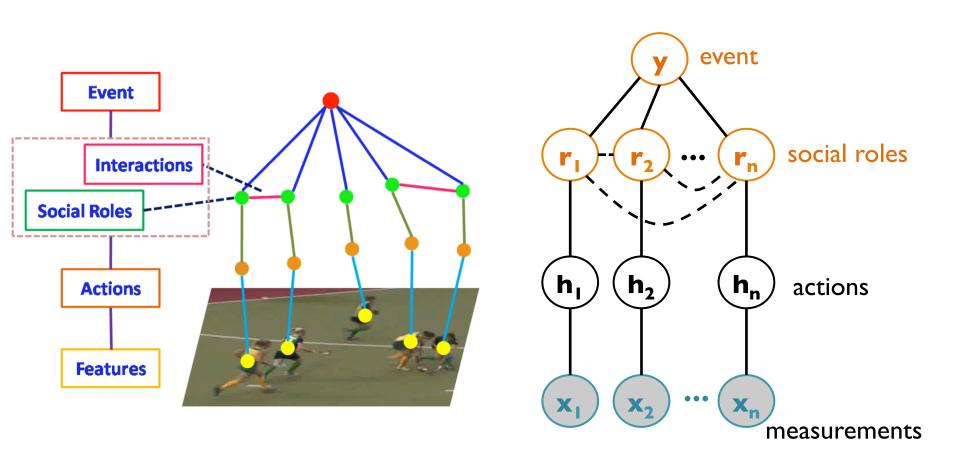
Social roles

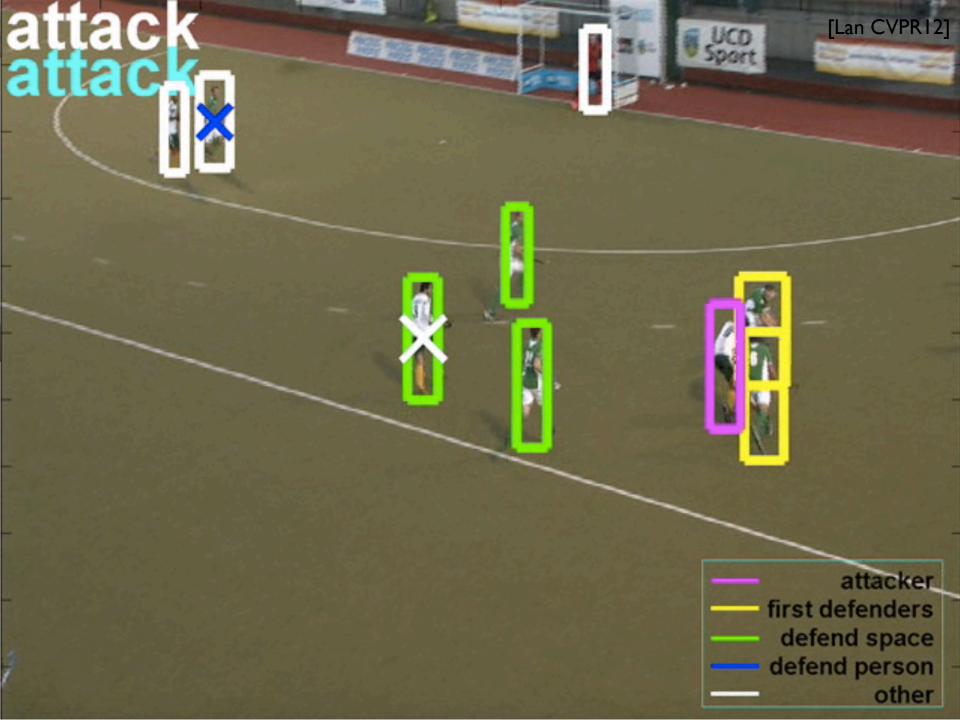
Mid-Level semantics that describe individual/group behaviors in the context of social interactions.

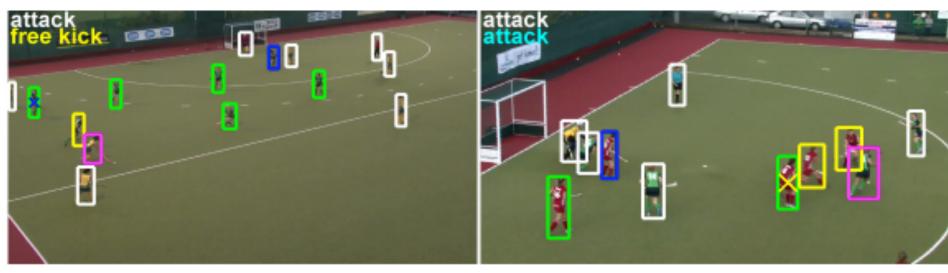


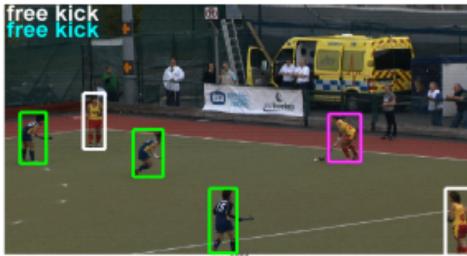


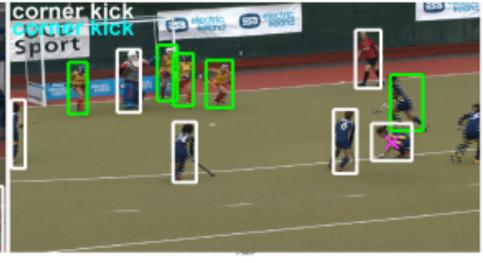
Hierarchical Model







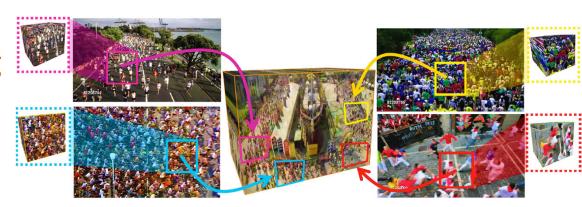




Data-driven Crowd Analysis (Rodriguez ICCVII)

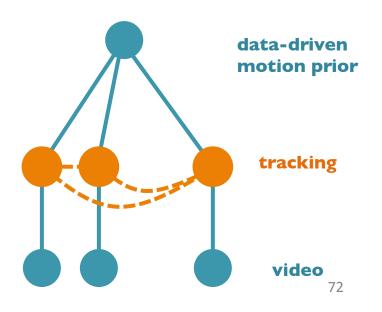
Input: a crowd video

Output: individual tracking



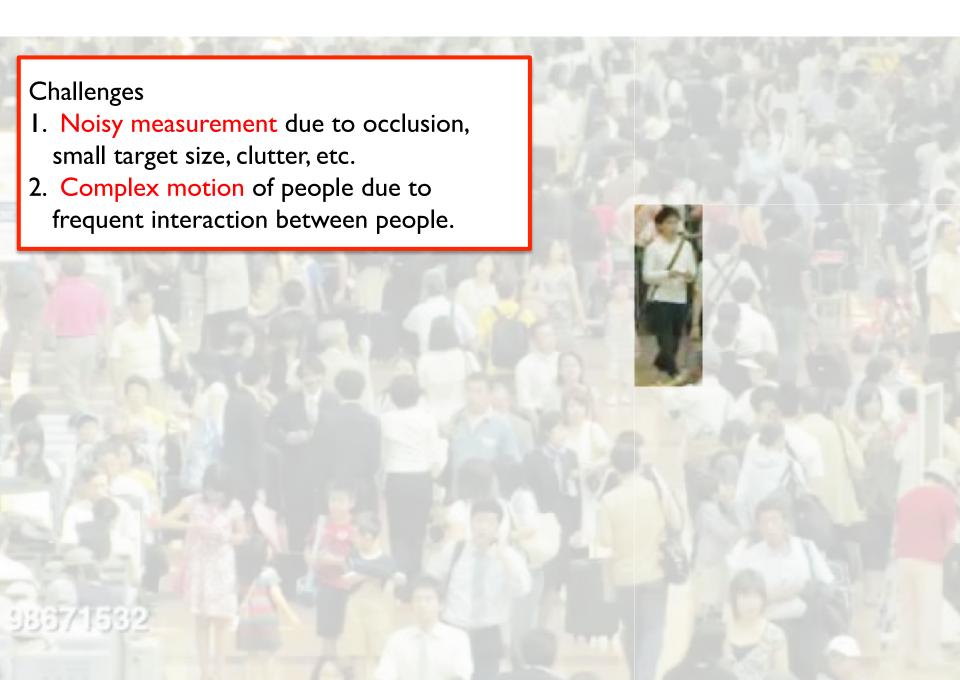
Crowd video











Challenges

- I. Noisy measurement due to occlusion, small target size, clutter, etc.
- 2. Complex motion of people due to frequent interaction between people.

Solution

I. See larger are to encode collective signal.

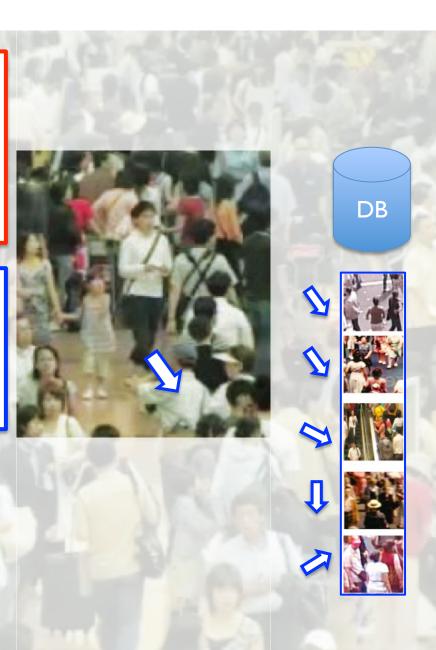


Challenges

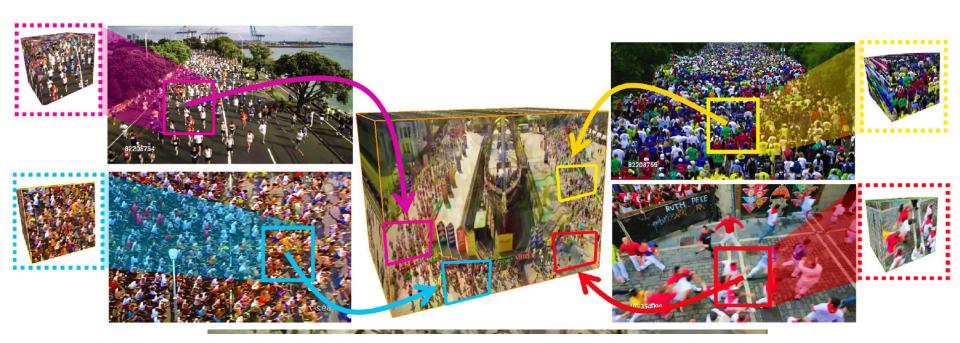
- I. Noisy measurement due to occlusion, small target size, clutter, etc.
- 2. Complex motion of people due to frequent interaction between people.

Solution

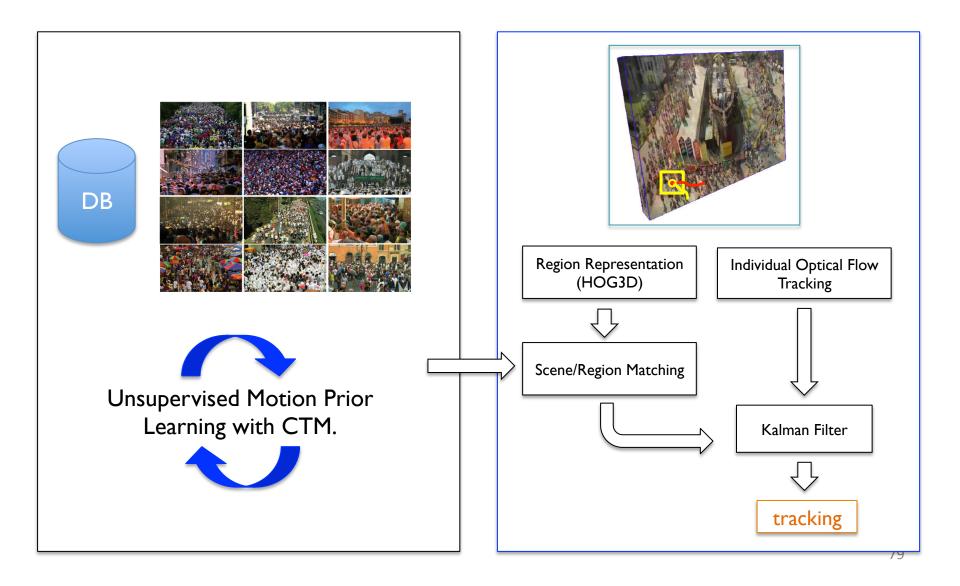
- I. See larger are to encode collective signal.
- 2. Transfer the motion prior of data with similar collective signal.



Mixture of Other Videos



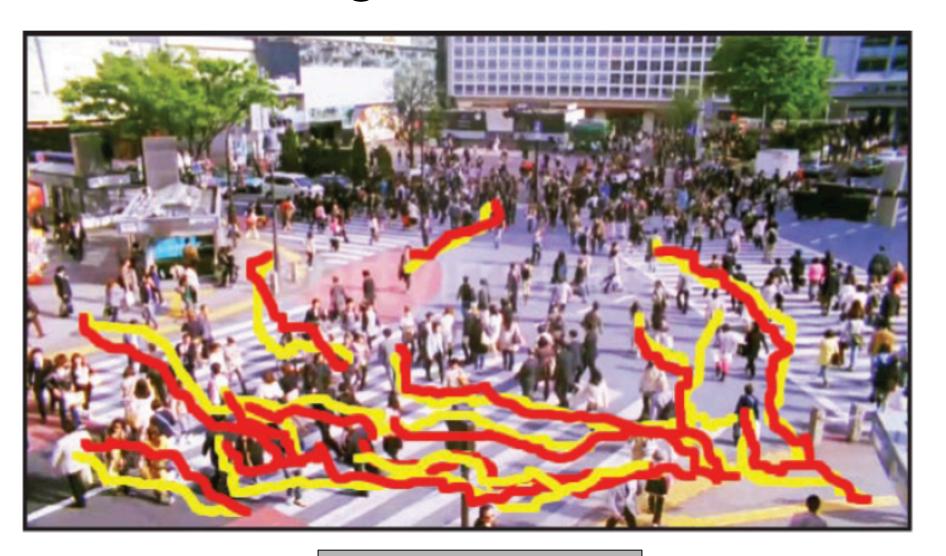
Framework



Tracking in Crowd Videos



Tracking in Crowd Videos



Tracking in Rare Event

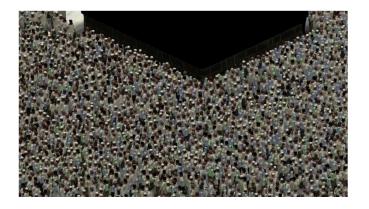


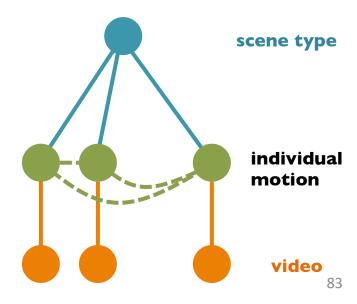
Application: Crowd Simulation [Curtis LCII]

Input: scene type

Output: video of a crowd

Model: Social force + FSM

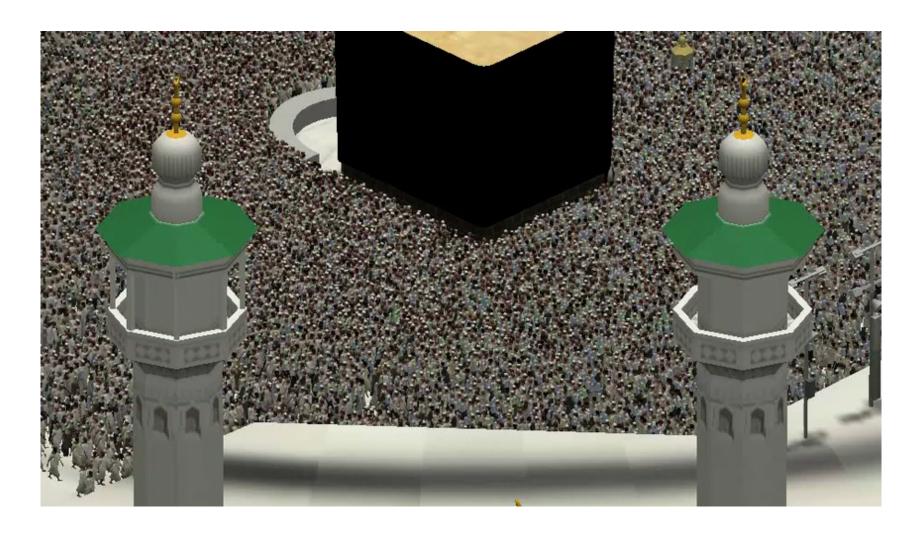




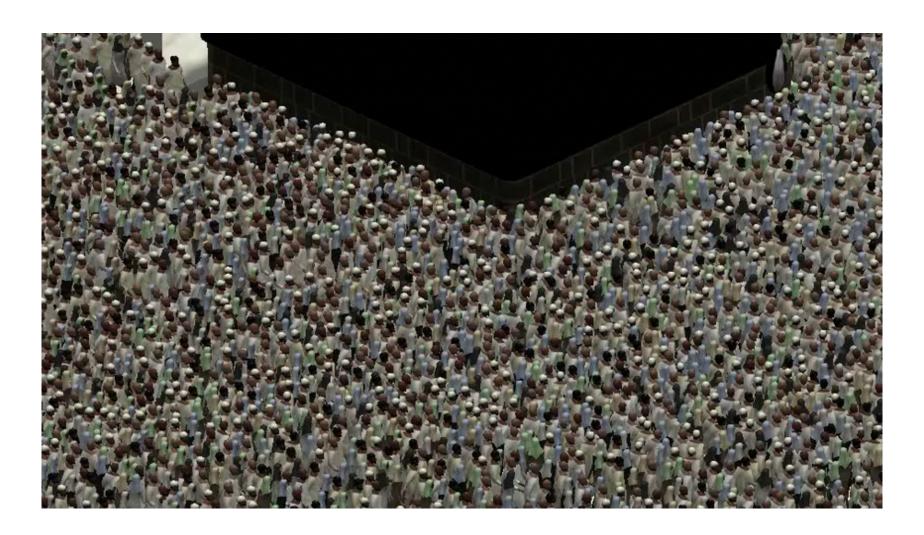
Real Video from Kaaba during Hajj



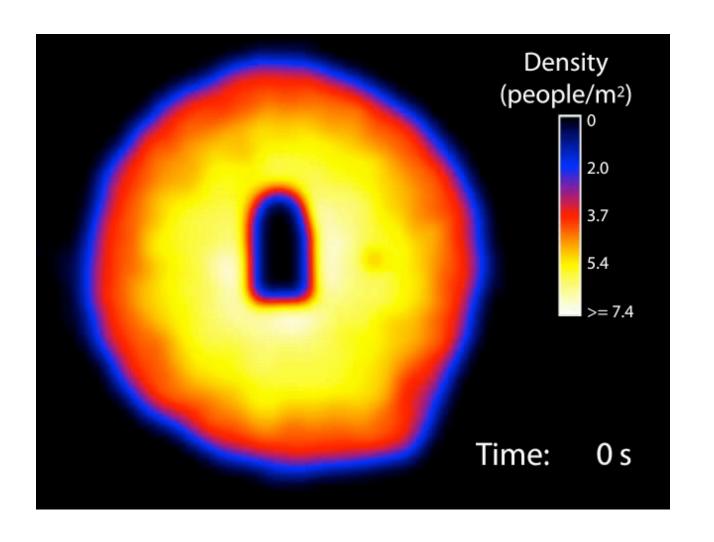
Simulation Results



Simulation Result - Zoomed



Density of People



Speed of People

