

Mathematics of Image and Data Analysis

Math 5467

Lecture 3: Linear Algebra & Python

Instructor: Jeff Calder

Email: jcalder@umn.edu

<http://www-users.math.umn.edu/~jwcalder/5467S21>

Last time

- Projection
- Introduction to Numpy

Today

- Reading images and audio in Python
- Diagonalization
- Some vector calculus

Images and audio in Python ([.ipynb](#))

Diagonalization

Every symmetric matrix A can be diagonalized. That is, there exists an orthogonal matrix Q and a diagonal matrix D such that

$$A = QDQ^T.$$

An orthogonal matrix is a square matrix whose columns are orthonormal vectors.

- The columns of Q are exactly the eigenvectors of the matrix A .
- The diagonal entries of D are the corresponding eigenvalues.
- An orthogonal matrix also has the property that all rows are orthonormal and thus

$$Q^T Q = I = Q Q^T.$$

- An orthogonal matrix is norm-preserving

$$\|Qx\| = \|x\|.$$

Optimization and eigenvalues

Exercise 1. Let A be a symmetric matrix, and consider the optimization problem

$$(1) \quad \min\{x^T A x : \|x\| = 1\}.$$

Show that every minimizer x^* is an eigenvector of A with smallest eigenvalue. What happens if we switch the min to a max in (1)? △

Write $y = Q^T x$, $A = Q \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & \dots & \lambda_n \end{bmatrix} Q^T$

$\|y\| = \|x\|$

$x^T A x = x^T Q D Q^T x$

$= y^T \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & \dots & \lambda_n \end{bmatrix} y = \sum_{i=1}^n \lambda_i y_i^2$

$\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$

$$\min \left\{ \sum_{i=1}^n \lambda_i y_i^2 : \|y\|^2 = \sum_{i=1}^n y_i^2 = 1 \right\}.$$

Minimized by $y_1 = 1, y_2 = y_3 = \dots = y_n = 0$

$$\text{Indeed, } \sum_{i=1}^n \lambda_i y_i^2 \geq \lambda_1 \sum_{i=1}^n y_i^2 = \lambda_1$$

Thus $y = e_1 = (1, 0, \dots, 0)$

Check $x = Qy = Qe_1 =$ first eigenvector
of A (smallest eigenvalue)

$$\rightarrow \boxed{Ax = \lambda_1 x}$$

And $x^T A x = x^T \lambda_1 x = \lambda_1 x^T x$
 $= \lambda_1 \|x\|^2 = \lambda_1$

$$\lambda_1 = x^T A x$$

Vector Calculus

We recall that for a differentiable function $f : \mathbb{R}^n \rightarrow \mathbb{R}$, the gradient ∇f is defined by

$$\nabla f = \left(\frac{\partial f}{\partial x(1)}, \frac{\partial f}{\partial x(2)}, \dots, \frac{\partial f}{\partial x(n)} \right).$$

Example 1. For the function $f(x) = x(1)^2 - x(2)^2$ on \mathbb{R}^2 , the gradient is

$$\nabla f(x) = (2x(1), -2x(2)).$$

△

Gradients of common functions

$$x_1, x_2, x_3, x_4 \in \mathbb{R}^n$$

$$\sum_{i=1}^n y(i) x(i)$$

Exercise 2. Show that

(i) For a linear function $f(x) = y^T x$, we clearly have $\nabla f(x) = y$.

(ii) For a quadratic function $f(x) = x^T A x$, where A is an $n \times n$ matrix, we have

$$\nabla f(x) = (A + A^T)x.$$

(iii) Assume A is a symmetric matrix. For the function $f(x) = \|Ax\|^2$, show that

$$\nabla f(x) = 2A^2x,$$

$$\text{Hw: } 0 = \nabla \left(\frac{x^T A x}{x^T x} \right) = \frac{x^T x \nabla(x^T A x) - x^T A x \nabla(x^T x)}{(x^T x)^2}$$

Note(ii) $f(x) = x^T A x = (x^T A x)^T = x^T A^T x$

$$f(x) = \frac{1}{2} x^T (A + A^T) x$$

Can assume A is symmetric and
show that for $f(x) = x^T A x$

$$\boxed{\nabla f(x) = 2Ax}$$

$$\frac{\partial}{\partial x(k)} (x^T A x) = \frac{\partial}{\partial x(k)} \sum_{i=1}^n \sum_{j=1}^n A(i,j) x(i) x(j)$$

$$= \sum_{i=1}^n \sum_{j=1}^n A(i,j) \frac{\partial}{\partial x(k)} (x(i) x(j))$$

$$= \sum_{i=1}^n \sum_{j=1}^n A(i,j) (\delta_{ik} x(j) + \delta_{jk} x(i))$$

where

$$\delta_{ij} = \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

$$= \sum_{j=1}^n A(k,j) x(j) + \sum_{i=1}^n A(i,k) x(i)$$

↓ since $A=A^T$

$$= (Ax)(k) + (Ax)(k)$$

$$= 2(Ax)(k)$$

$$\Rightarrow \nabla (x^T A x) = 2Ax$$

for symmetric matrices A

$$A = A^T.$$

