

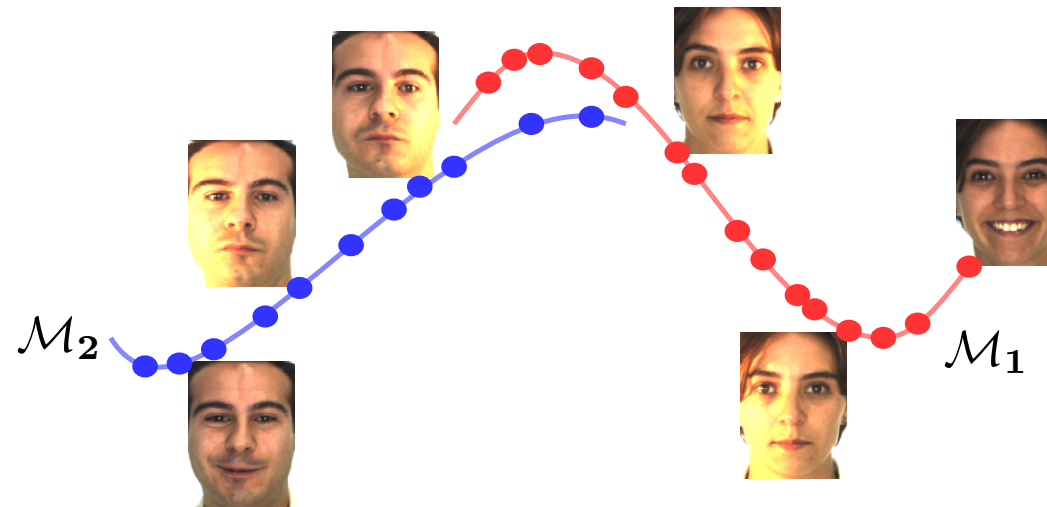
Learning All by Selecting A Few

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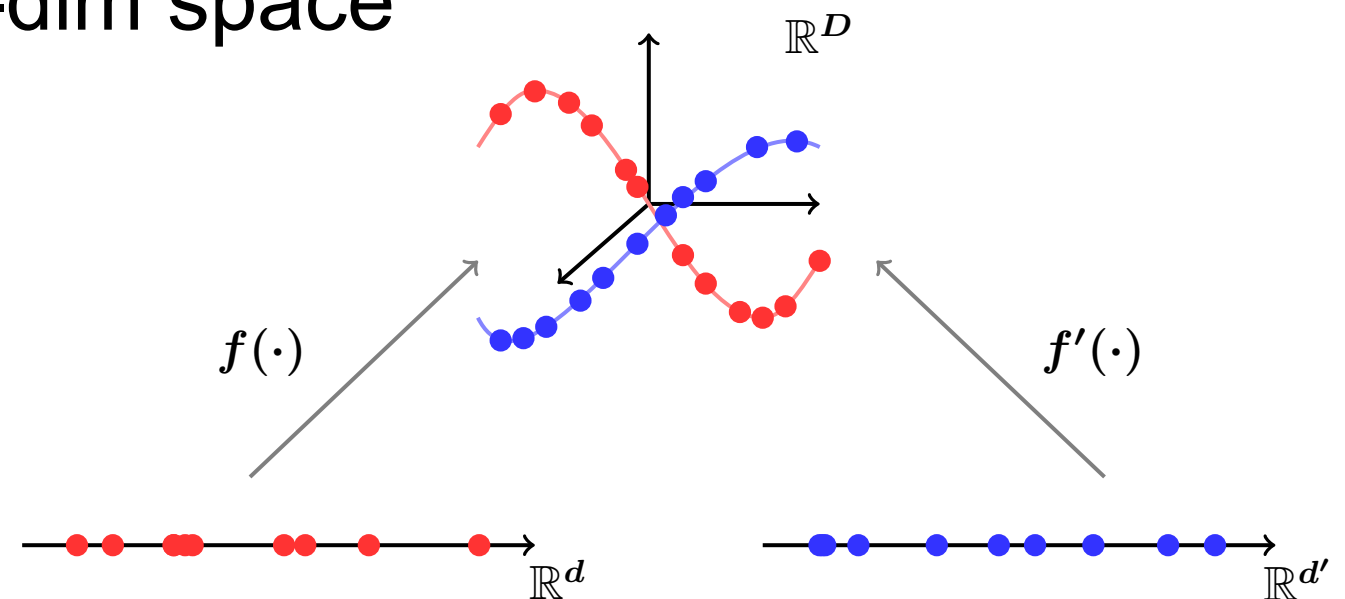
Intrinsic low-dimensionality

- Data concentrate around low-dimensional structures

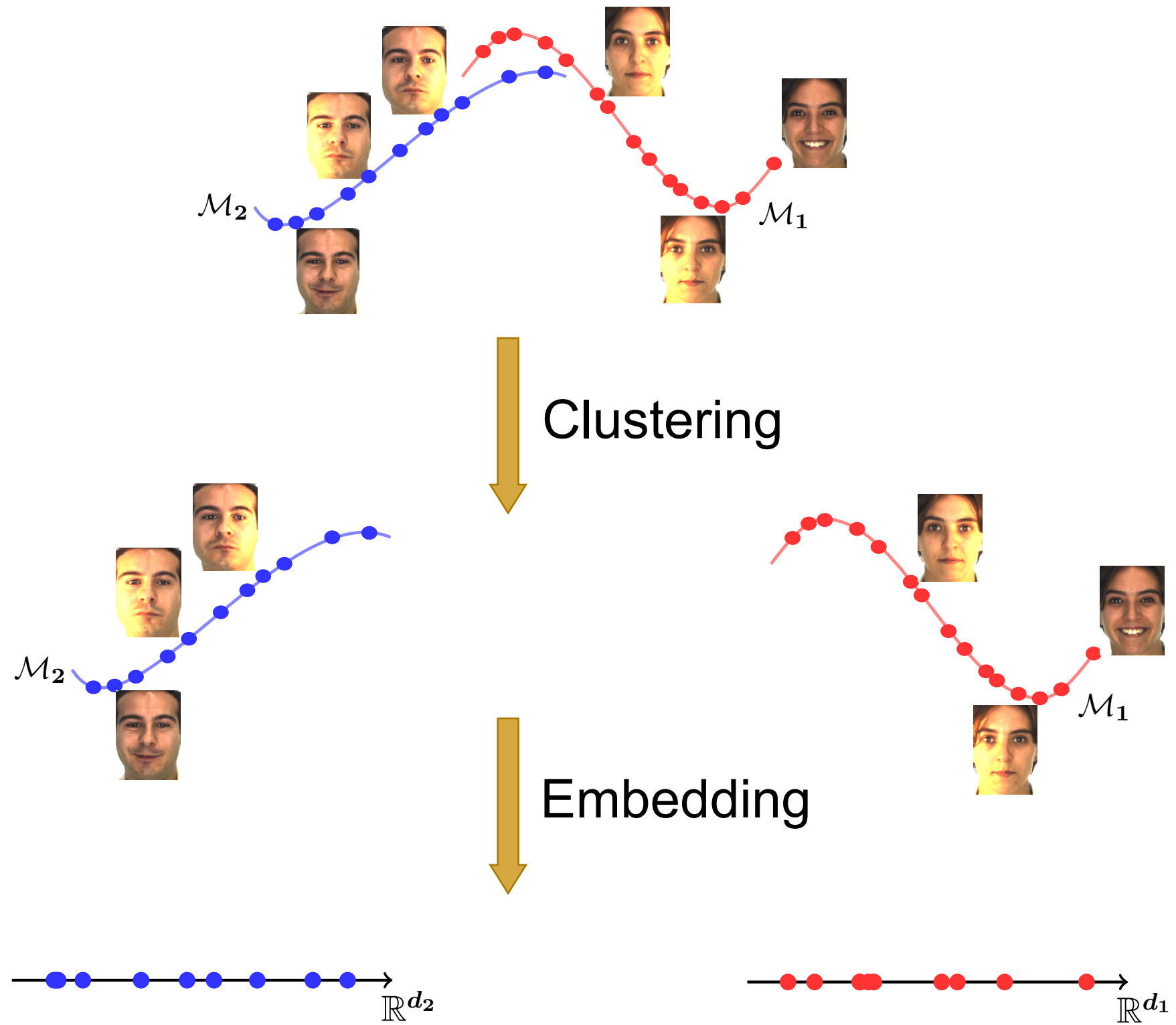


- Mapping from low-dim to high-dim space

- linear / nonlinear
- one / multiple



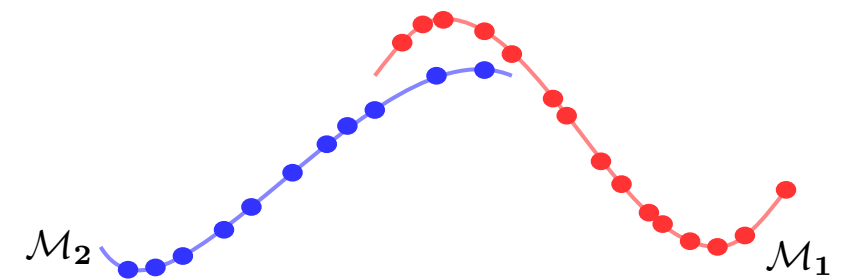
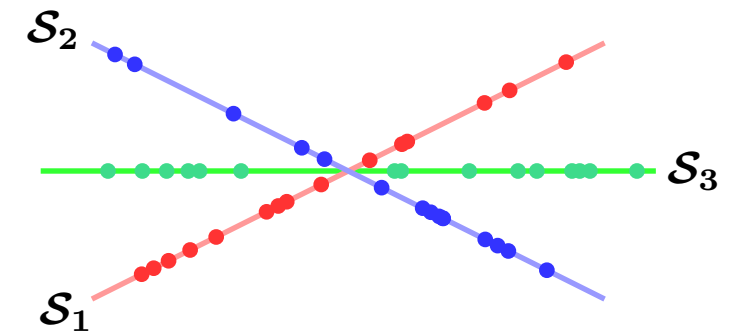
Two fundamental tasks



This talk

- Clustering and embedding on

- multiple subspaces
- multiple nonlinear manifolds



- Techniques from sparse representation theory

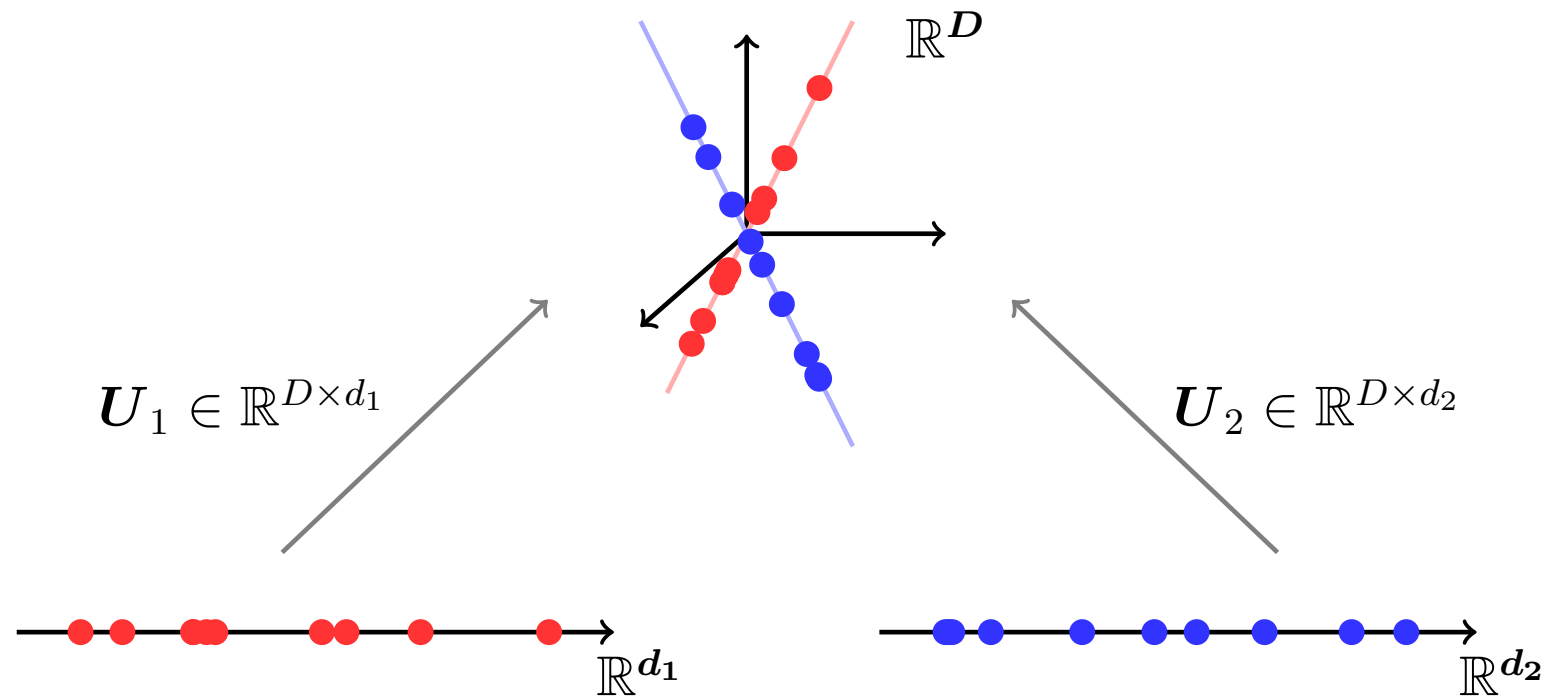
- well suited for high-dim data (blessing of dimensionality, Donoho`00)

Sparse Subspace Clustering

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Subspace clustering



- Linear mappings: flat manifolds
 - faces, digits, motions, text corpus, gene expression
- Tasks:
 - separate data into subspaces
 - find low-dimensional representations

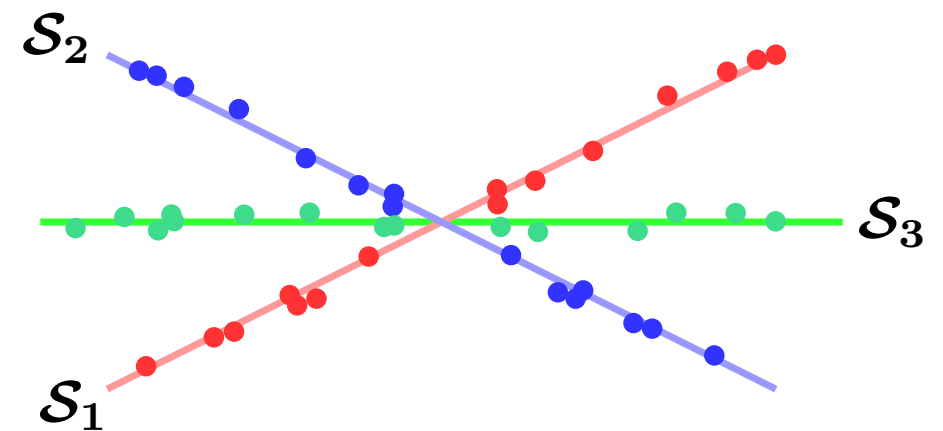
Subspace clustering

- Prior work:

- algebraic: Ksubspaces (Tseng`00), GPCA (Vidal-Ma`03), median Kflats (Zhang`09)
- statistical: RANSAC (Fischler`81), MPPCA (Tipping`99), ALC (Rao-Ma`09)
- spectral clustering: LSA (Yan`06), SCC (Chen-Lerman`09), LRR (Liu`09), SLBF (Zhang-Lerman`10)

- Challenges:

- intersecting subspaces
- noise, outliers, missing entries
- computational complexity
- knowledge of dimension/number of subspaces



Our approach

- Global sparse optimization
 - deal with intersection
 - deal with noise, outlying / missing entries
 - do not require dimension / number of subspaces
- Theoretical guarantees
- Achieves/outperforms state-of-the-art results in
 - segmentation of rigid-body motions
 - clustering of face images
 - temporal segmentation of videos

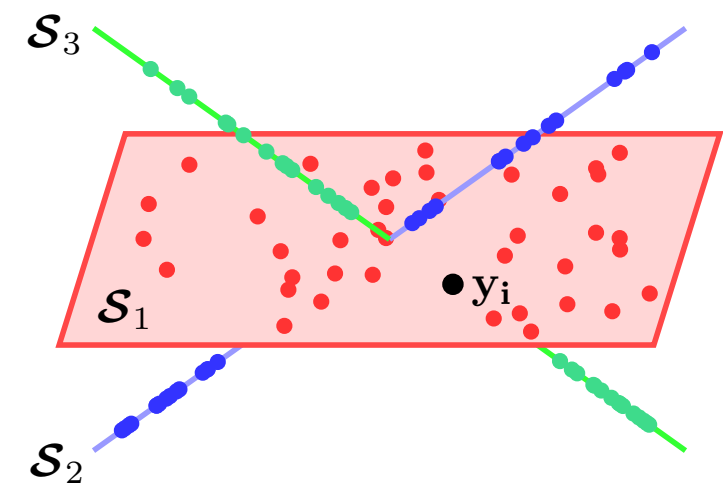
Sparse subspace clustering: idea

- Self-expressiveness property

- $\mathbf{y}_i = \mathbf{Y} \mathbf{c}_i$ \longrightarrow many solutions

- $\mathbf{Y} = [\mathbf{Y}_1 \quad \mathbf{Y}_2 \quad \cdots \quad \mathbf{Y}_n] \Gamma$

low column-rank



- In \mathcal{S}_i of dim d_i , each point can be reconstructed by d_i other points

- sparse representation comes from same subspace

$$\min \|\mathbf{c}_i\|_0 \quad \text{s. t.} \quad \mathbf{y}_i = \mathbf{Y} \mathbf{c}_i, \quad c_{ii} = 0$$



$$\min \|\mathbf{c}_i\|_1 \quad \text{s. t.} \quad \mathbf{y}_i = \mathbf{Y} \mathbf{c}_i, \quad c_{ii} = 0$$

Sparse subspace clustering

- SSC algorithm

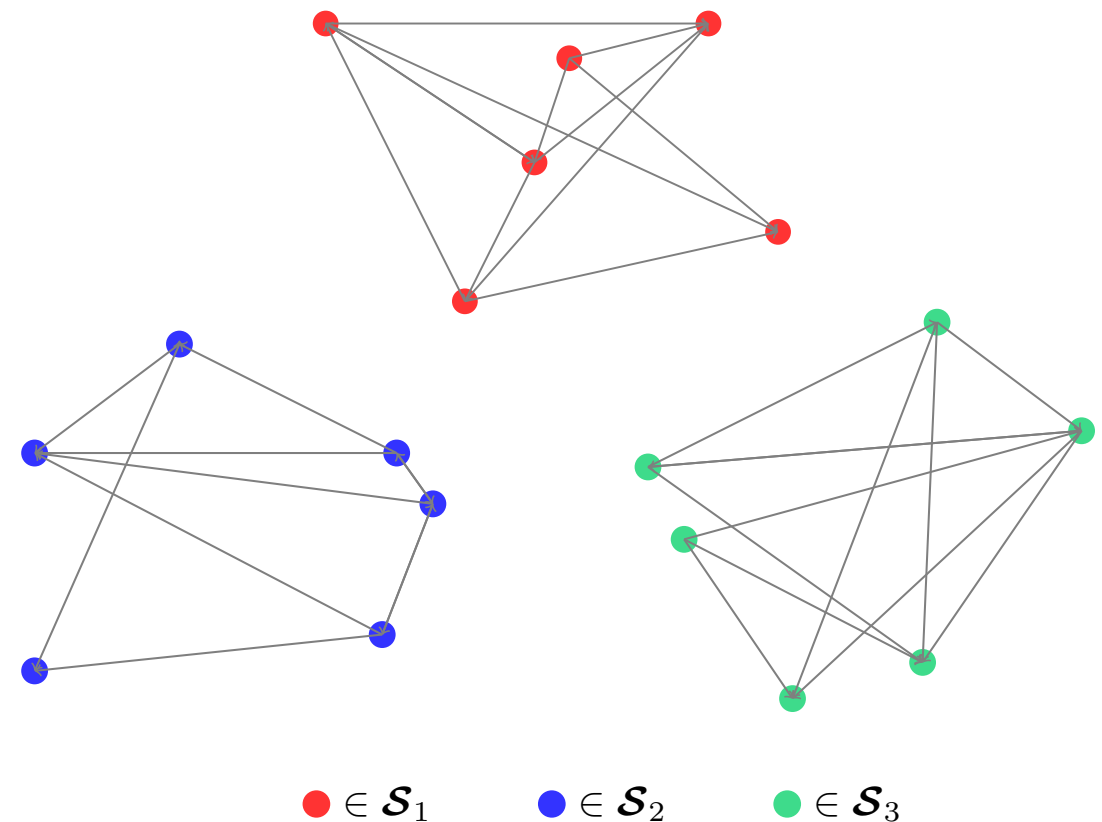
- 1: solve the sparse optimization

$$\min \|\mathbf{c}_i\|_1 \quad \text{s. t.} \quad \mathbf{y}_i = \mathbf{Y} \mathbf{c}_i, \quad c_{ii} = 0$$

$$\mathbf{c}_i = \begin{bmatrix} c_{i1} \\ c_{i2} \\ \vdots \\ c_{iN} \end{bmatrix}$$

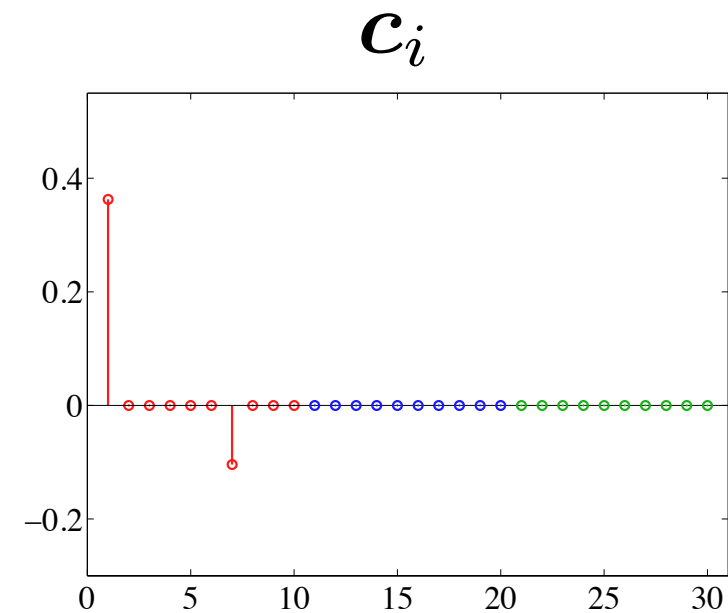
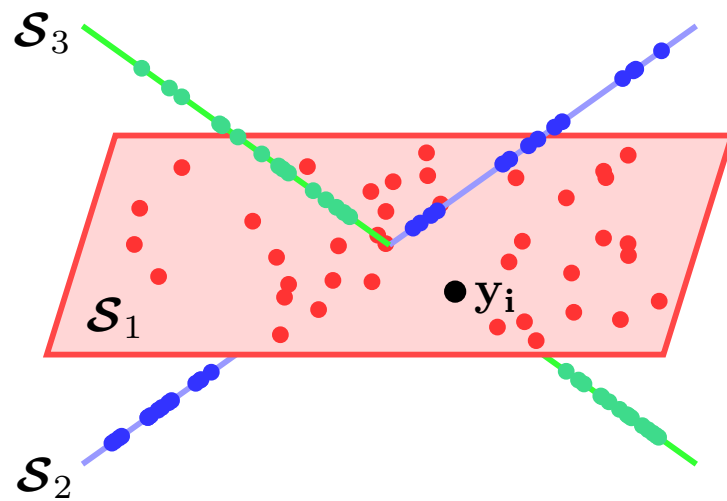
- 2: infer clustering from similarity graph

- connect points using sparse weights
- symmetrize the weights $w_{ij} = c_{ij} + c_{ji}$
- apply spectral clustering



SSC theory

- When does the algorithm succeed?
 - sparse representation from the correct subspace
 - subspace-sparse representation

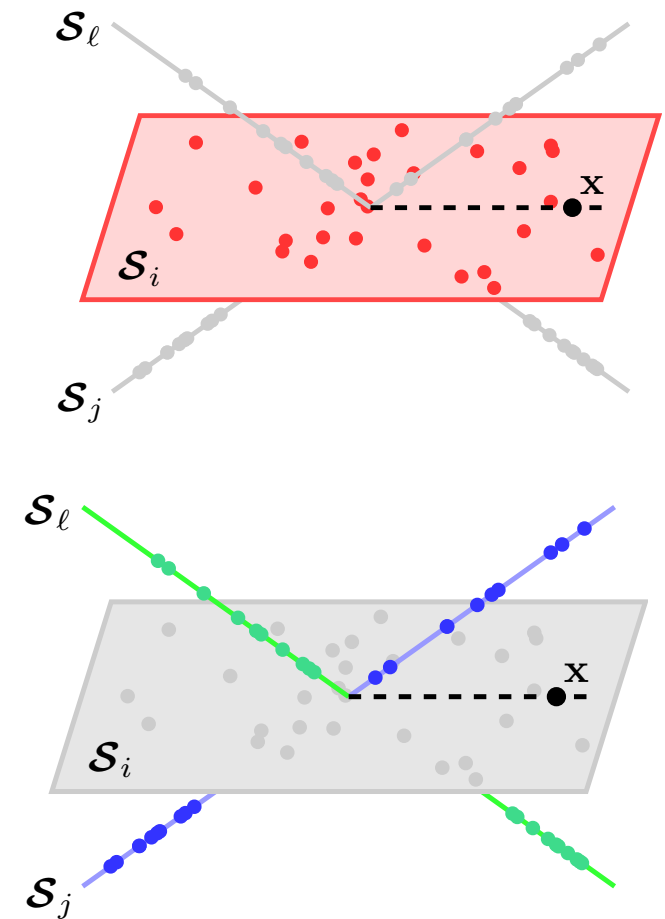


SSC theory

- Take any nonzero \mathbf{x} in the intersection of \mathcal{S}_i and $\bigoplus_{j \neq i} \mathcal{S}_j$

$$\mathbf{a}_i = \operatorname{argmin} \|\mathbf{a}\|_1 \quad \text{s. t.} \quad \mathbf{x} = \mathbf{Y}_i \mathbf{a}$$

$$\mathbf{a}_{-i} = \operatorname{argmin} \|\mathbf{a}\|_1 \quad \text{s. t.} \quad \mathbf{x} = \mathbf{Y}_{-i} \mathbf{a}$$



- Theorem:** SSC recovers a subspace-sparse representation for any \mathbf{y} in \mathcal{S}_i iff

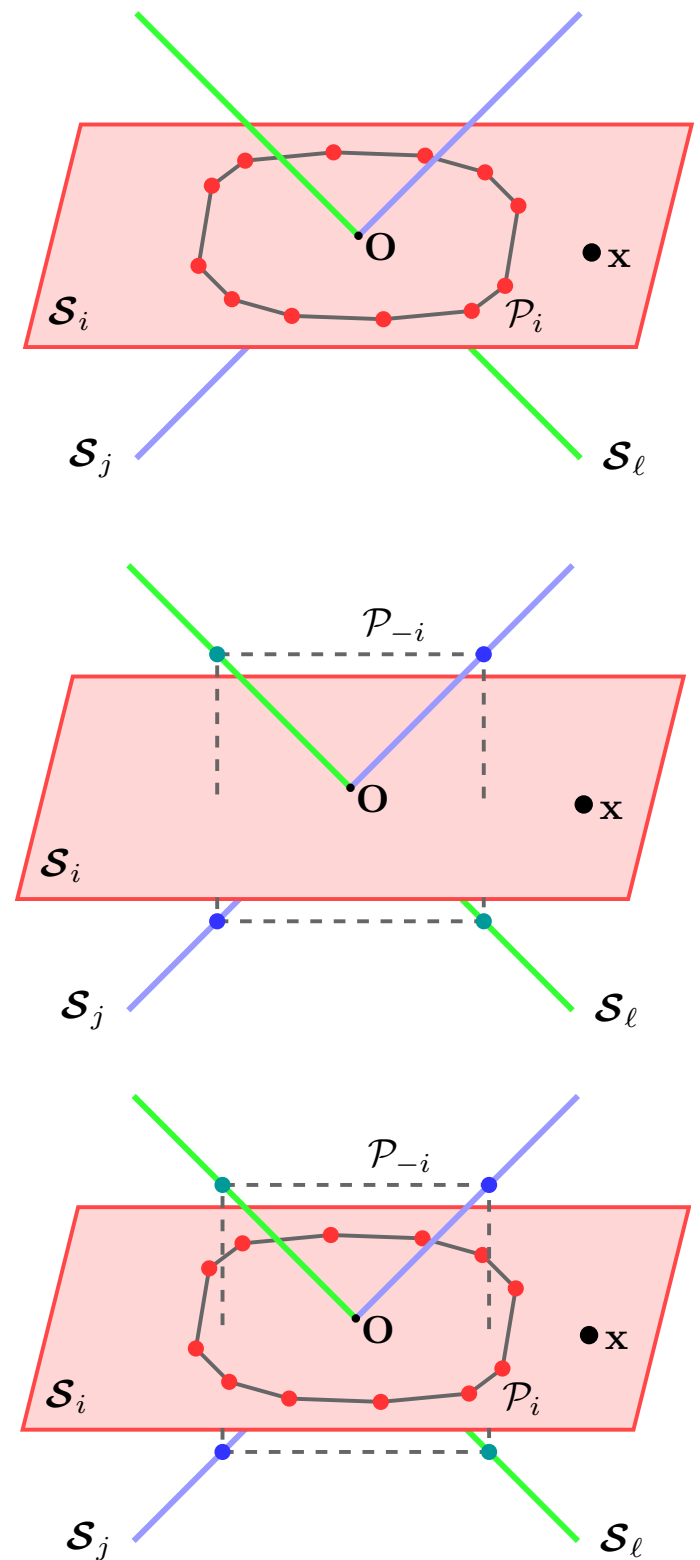
$$\forall \mathbf{x} \in \mathcal{S}_i \cap \left(\bigoplus_{j \neq i} \mathcal{S}_j \right), \mathbf{x} \neq \mathbf{0} \implies \|\mathbf{a}_i\|_1 < \|\mathbf{a}_{-i}\|_1$$

Geometric interpretation

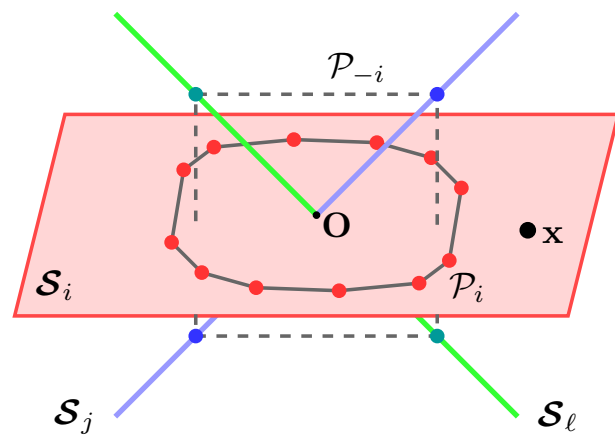
- $\min \|\mathbf{a}\|_1 \quad \text{s. t.} \quad \mathbf{x} = \mathbf{Y}_i \mathbf{a} \longrightarrow \mathbf{a}_i$

- $\min \|\mathbf{a}\|_1 \quad \text{s. t.} \quad \mathbf{x} = \mathbf{Y}_{-i} \mathbf{a} \longrightarrow \mathbf{a}_{-i}$

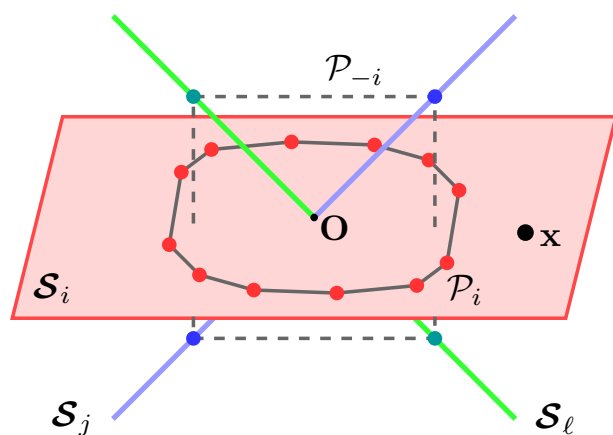
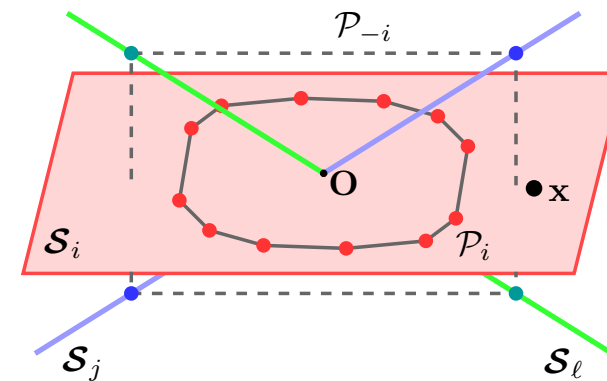
- $\|\mathbf{a}_i\|_1 < \|\mathbf{a}_{-i}\|_1$



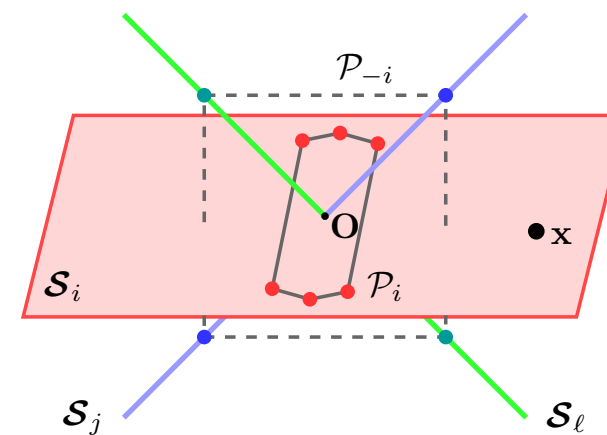
Geometric interpretation



subspace angle
 ↓
 decreases



data not
 ↓
 well-distributed

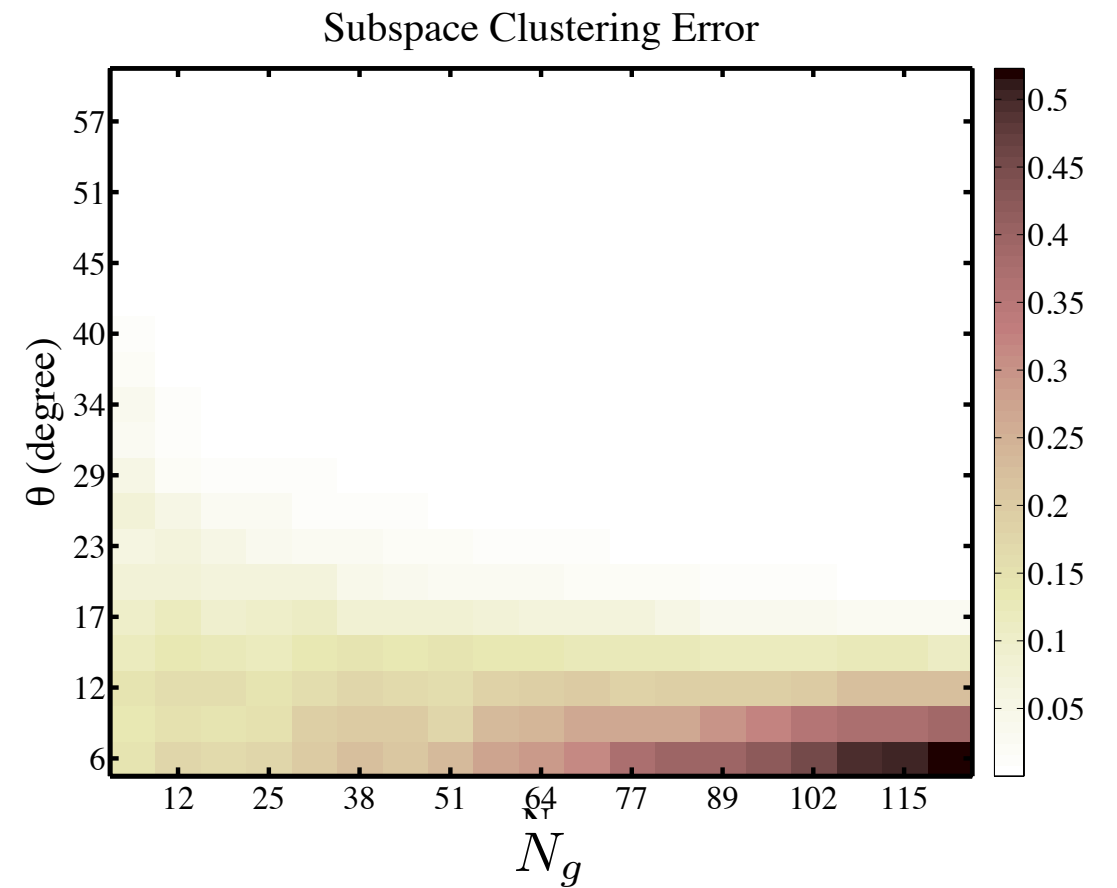
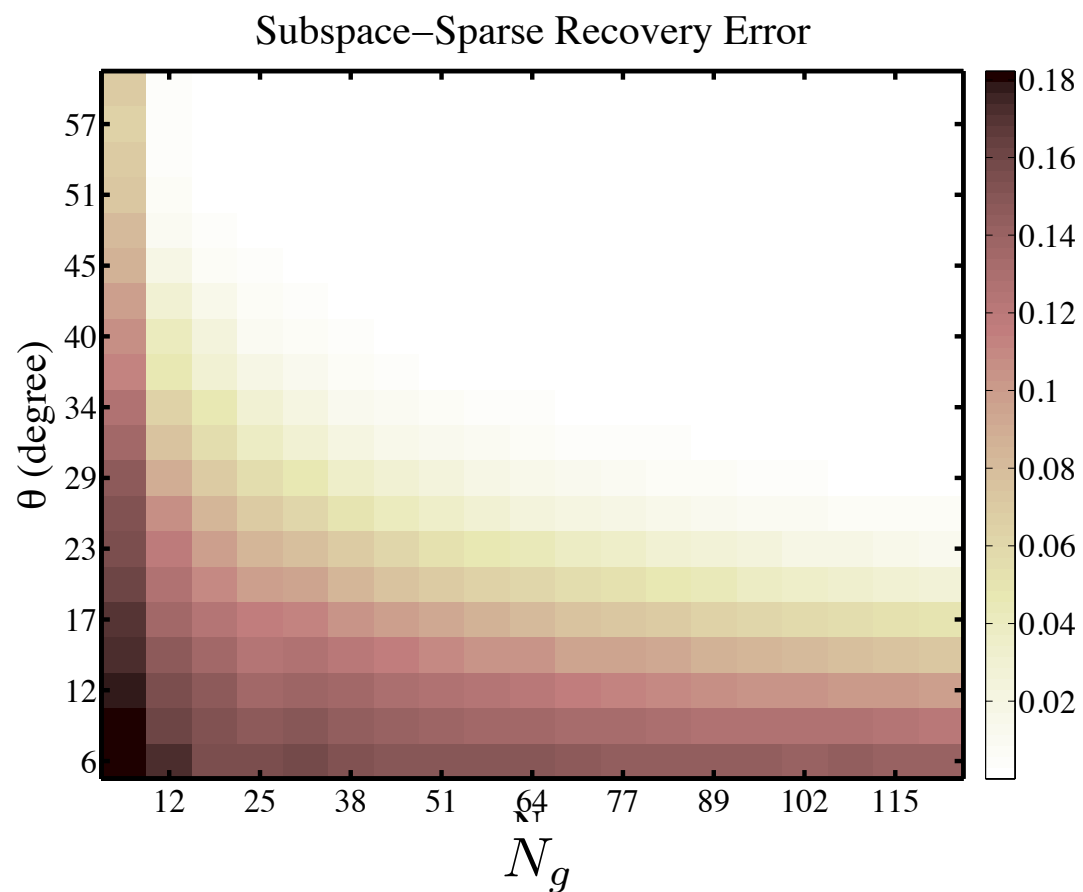


- **Theorem:** ℓ_1 optimization is successful if

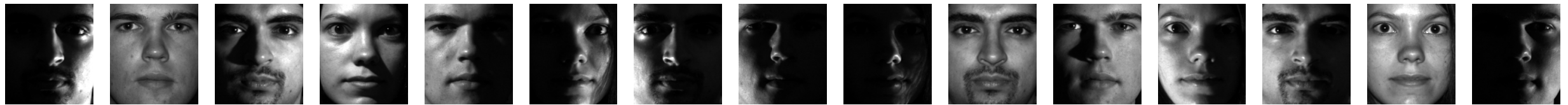
$$\max_{\tilde{\mathbf{Y}}_i \in \mathbb{W}_i} \sigma_{d_i}(\tilde{\mathbf{Y}}_i) > \sqrt{d_i} \max_{j \neq i} \cos(\theta_{ij})$$

Experiments: synthetic

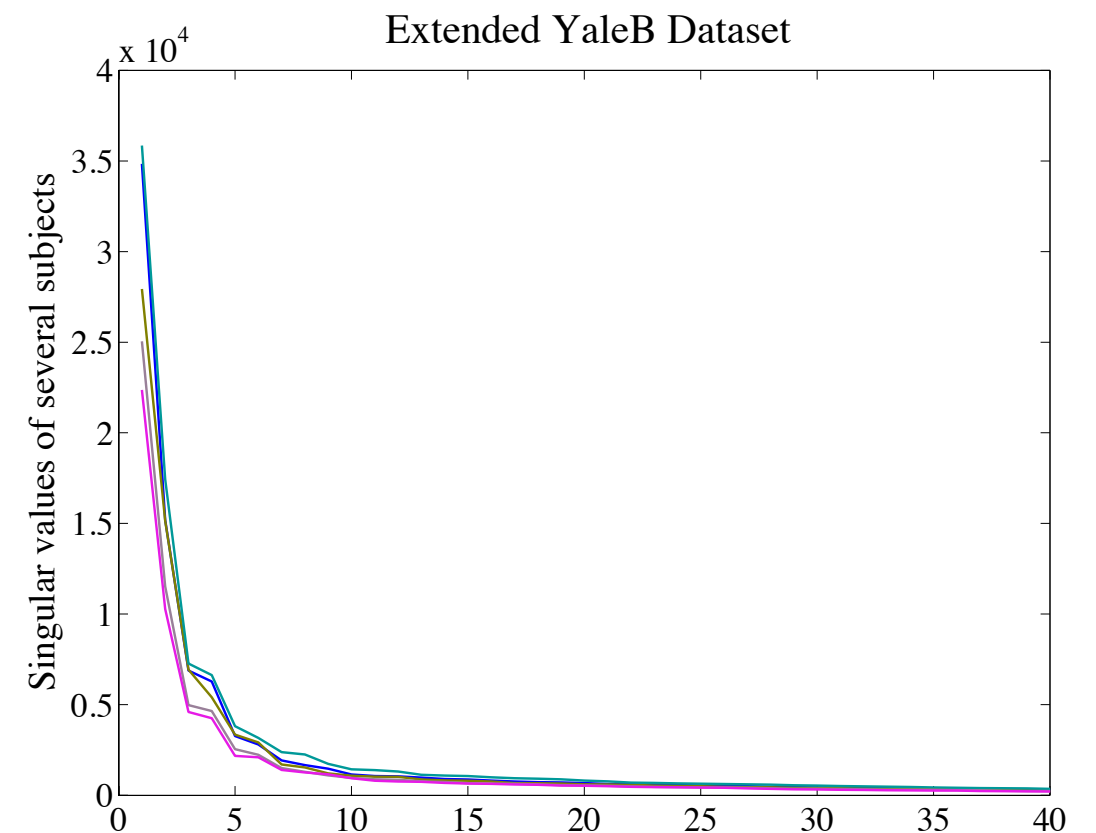
- Three subspaces of dimension $d = 4$
 - θ : subspace angle
 - N_g : # points in each subspace



Experiments: face clustering



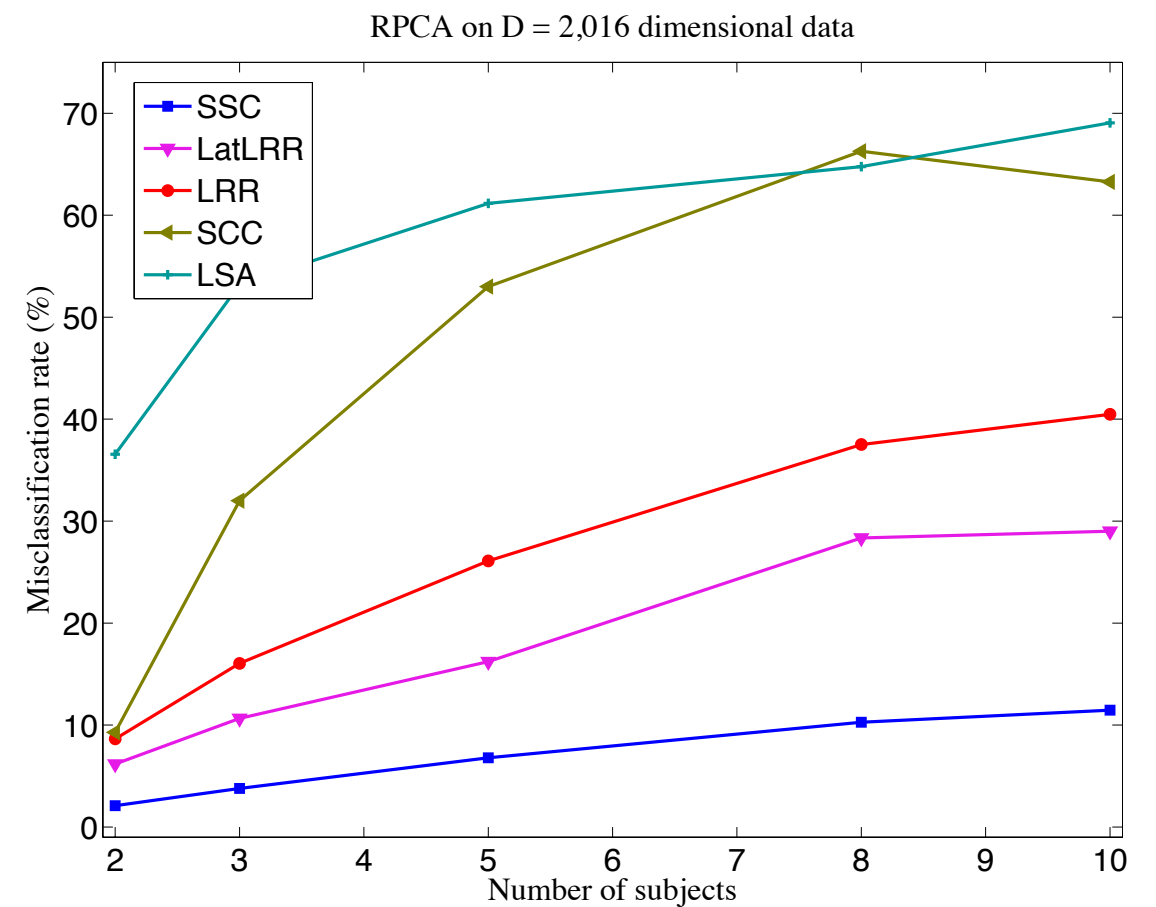
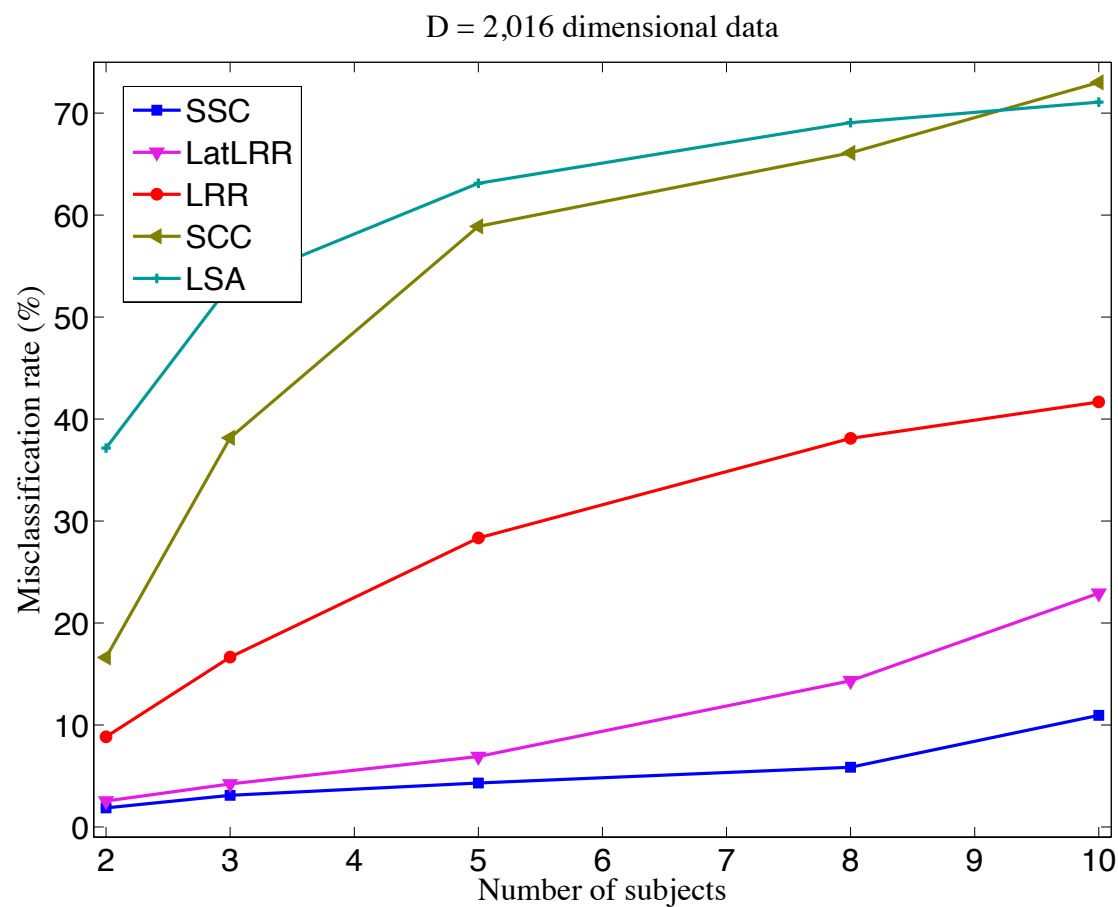
- Faces under varying illumination
 - lie in a 9-dim subspace
 - Extended Yale B dataset



Experiments: face clustering

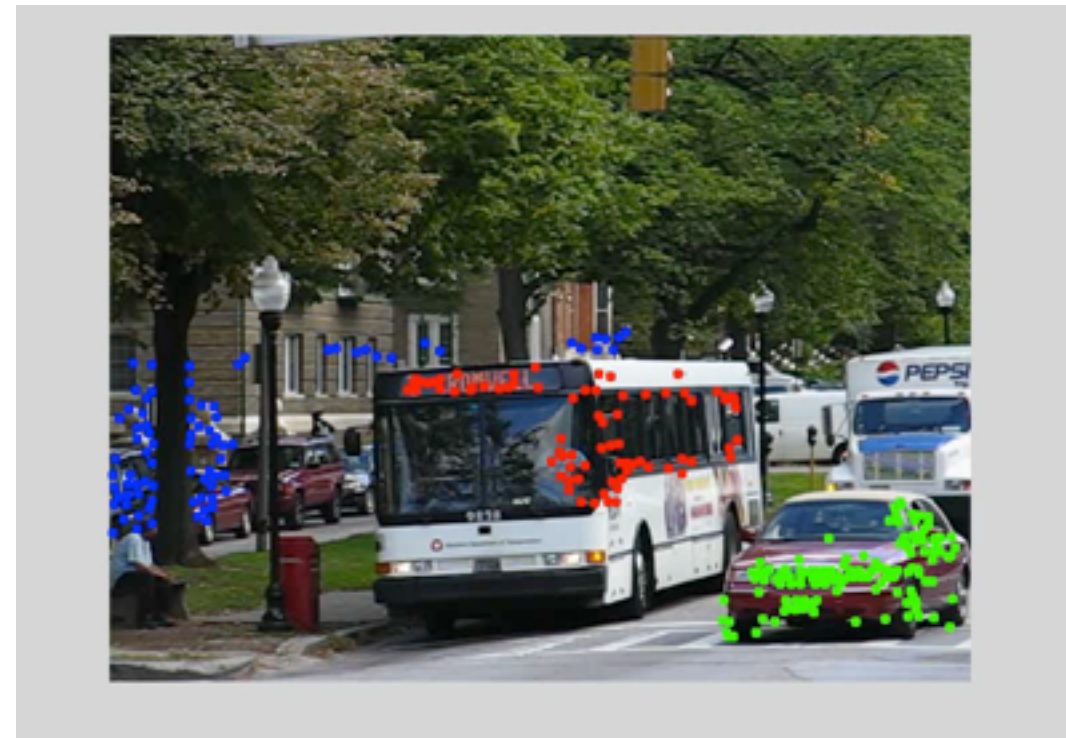
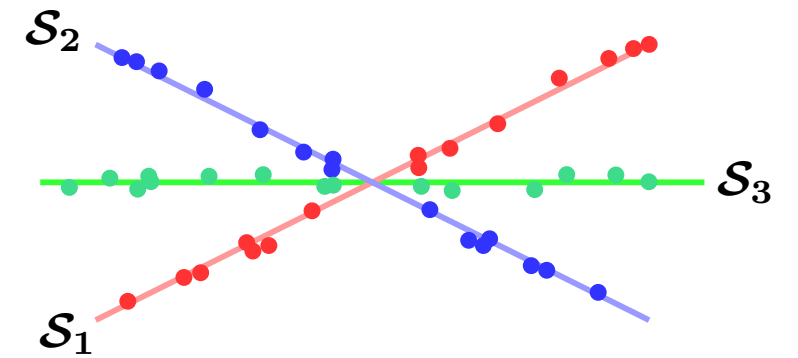
- SSC < 2.0% error for 2 subjects
- SSC < 11.0% error for 10 subjects

lower is better



Other problems

- Noisy data $y_i = \underbrace{y_i^0}_{\text{noise-free}} + \underbrace{z_i^0}_{\text{noise}}$
- Outlying, missing entries
- Motion segmentation

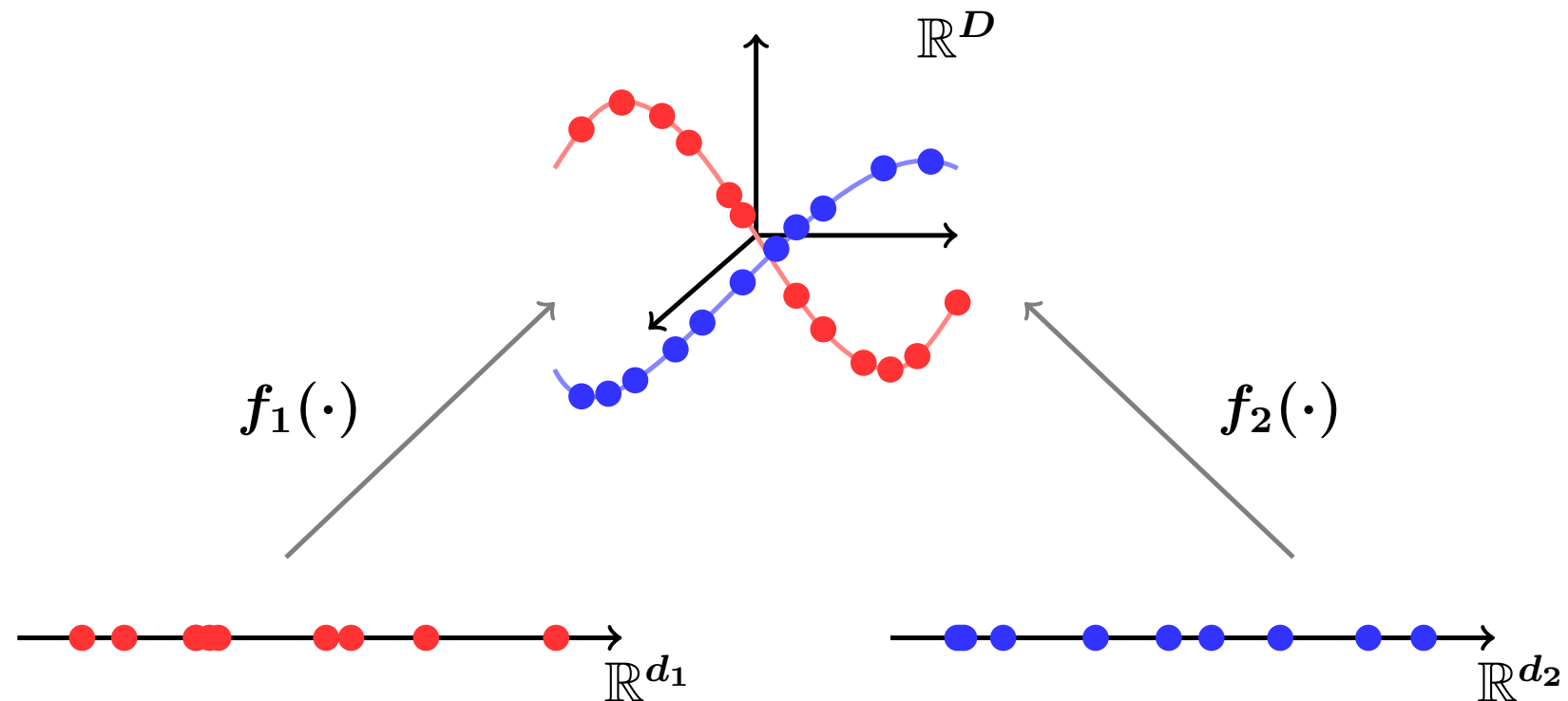


Sparse Manifold Clustering & Embedding

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Nonlinear manifolds

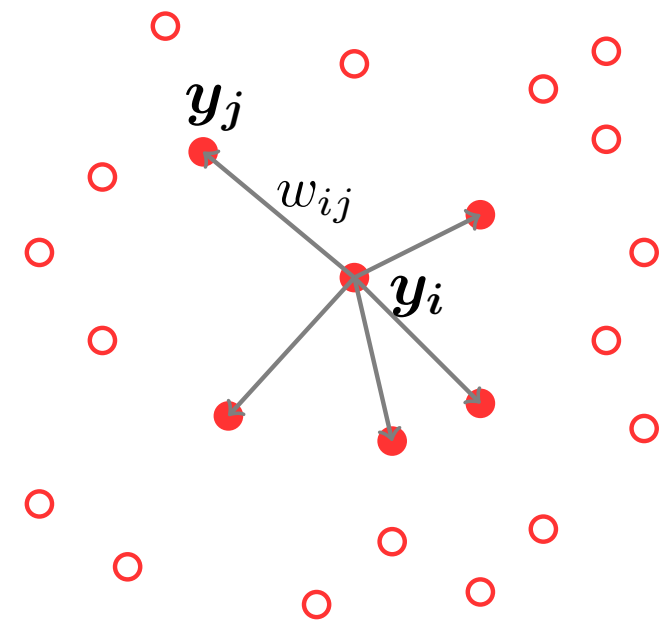


- Mappings are nonlinear
- Tasks:
 - cluster data into manifolds
 - find low-dimensional representations

Nonlinear dimensionality reduction

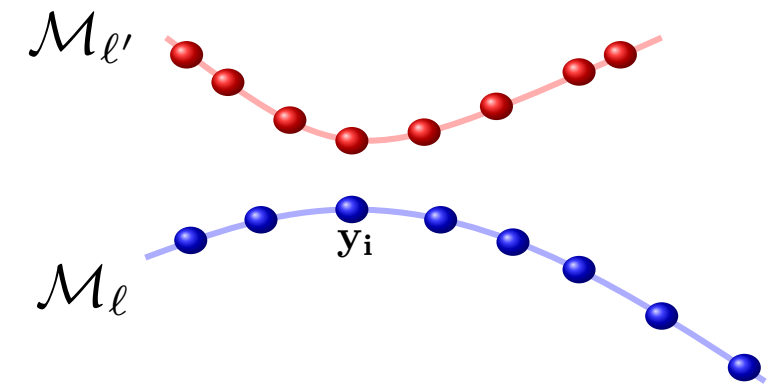
- **LLE** (Roweis`00), **ISOMap** (Tenenbaum`00), **HLLE** (Grimms`03), **LEM** (Belkin`02), **MVU** (Weinberger`04), **MVE** (Shaw`07), **SPE** (Jebara`09), ...
 - same in the first step
 - different in the second step

- Nonlinear dimension reduction
 - 1: build nearest neighbor graph
 - 2: learn weights
 - 3: find embedding from weights



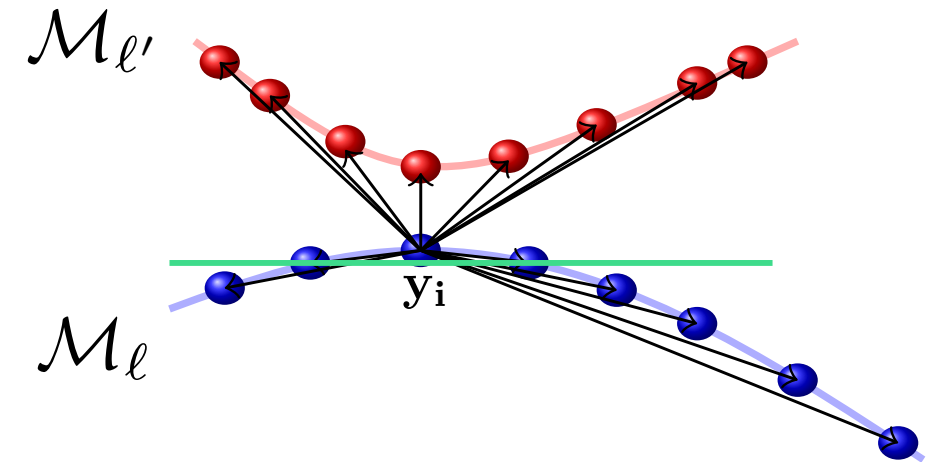
Sparse manifold clustering and embedding

- Our method (SMCE)
 - 1: learn the neighborhood graph and its weights
 - 2: find embedding from weights
- Weights encode information for both clustering and embedding
 - deal with manifolds close to each other
 - deal with manifolds of different dimensions
 - automatically pick the right number of neighbors



Sparse manifold clustering and embedding

- \mathcal{M}_ℓ of intrinsic dimension d_ℓ
- Affine span of $d_\ell + 1$ points from \mathcal{M}_ℓ is close to \mathbf{y}_i



- Optimization program

$$\min \|\mathbf{q}_i \odot \mathbf{c}_i\|_1 \quad \text{s. t.} \quad \left[\frac{\mathbf{y}_1 - \mathbf{y}_i}{\|\mathbf{y}_1 - \mathbf{y}_i\|_2} \cdots \frac{\mathbf{y}_N - \mathbf{y}_i}{\|\mathbf{y}_N - \mathbf{y}_i\|_2} \right] \mathbf{c}_i \approx \mathbf{0}, \quad \mathbf{1}^\top \mathbf{c}_i = 1$$

← few close points →

← span affine subspace →

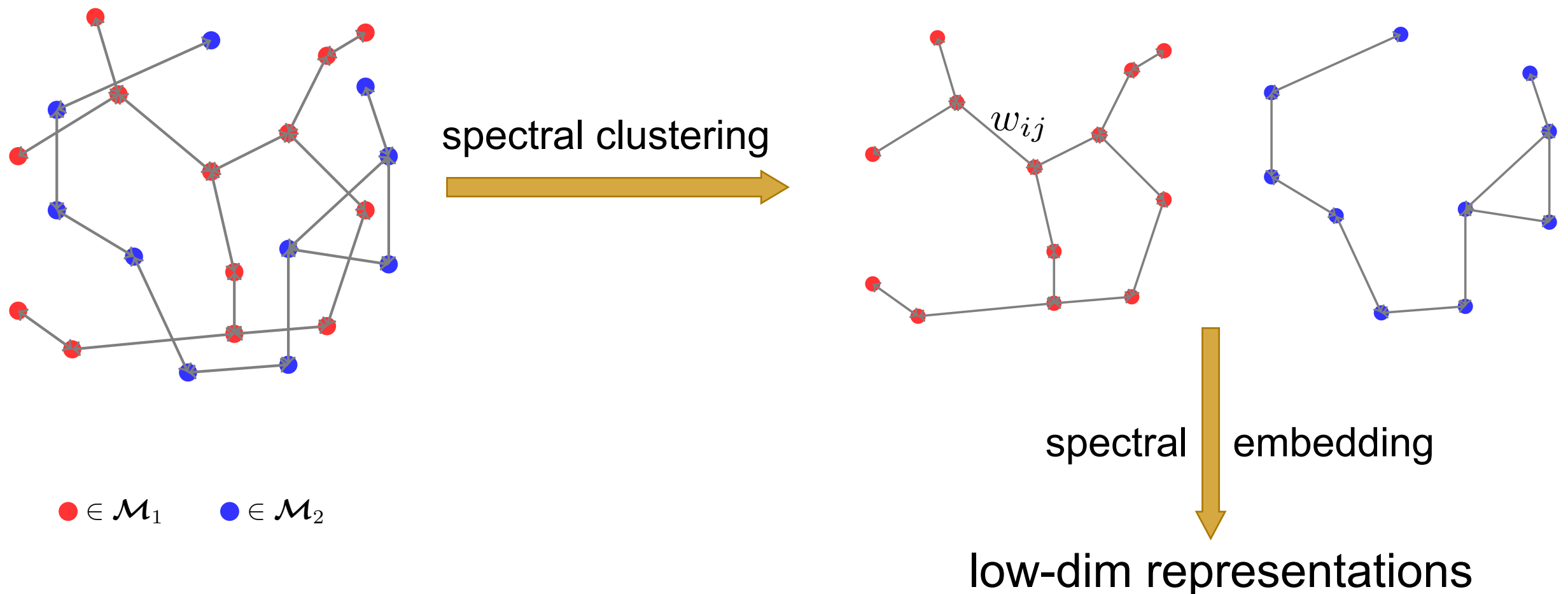
- proximity inducing vector: $\mathbf{q}_i \triangleq \left[\frac{\|\mathbf{y}_1 - \mathbf{y}_i\|_2}{\sum_{t \neq i} \|\mathbf{y}_t - \mathbf{y}_i\|_2} \cdots \frac{\|\mathbf{y}_N - \mathbf{y}_i\|_2}{\sum_{t \neq i} \|\mathbf{y}_t - \mathbf{y}_i\|_2} \right]^\top$

SMCE: algorithm

- For each data point solve

$$\min \lambda \| \mathbf{q}_i \odot \mathbf{c}_i \|_1 + \frac{1}{2} \left\| \left[\frac{\mathbf{y}_1 - \mathbf{y}_i}{\| \mathbf{y}_1 - \mathbf{y}_i \|_2} \cdots \frac{\mathbf{y}_N - \mathbf{y}_i}{\| \mathbf{y}_N - \mathbf{y}_i \|_2} \right] \mathbf{c}_i \right\|_2^2 \quad \text{s. t.} \quad \mathbf{1}^\top \mathbf{c}_i = 1$$

- Build a similarity graph

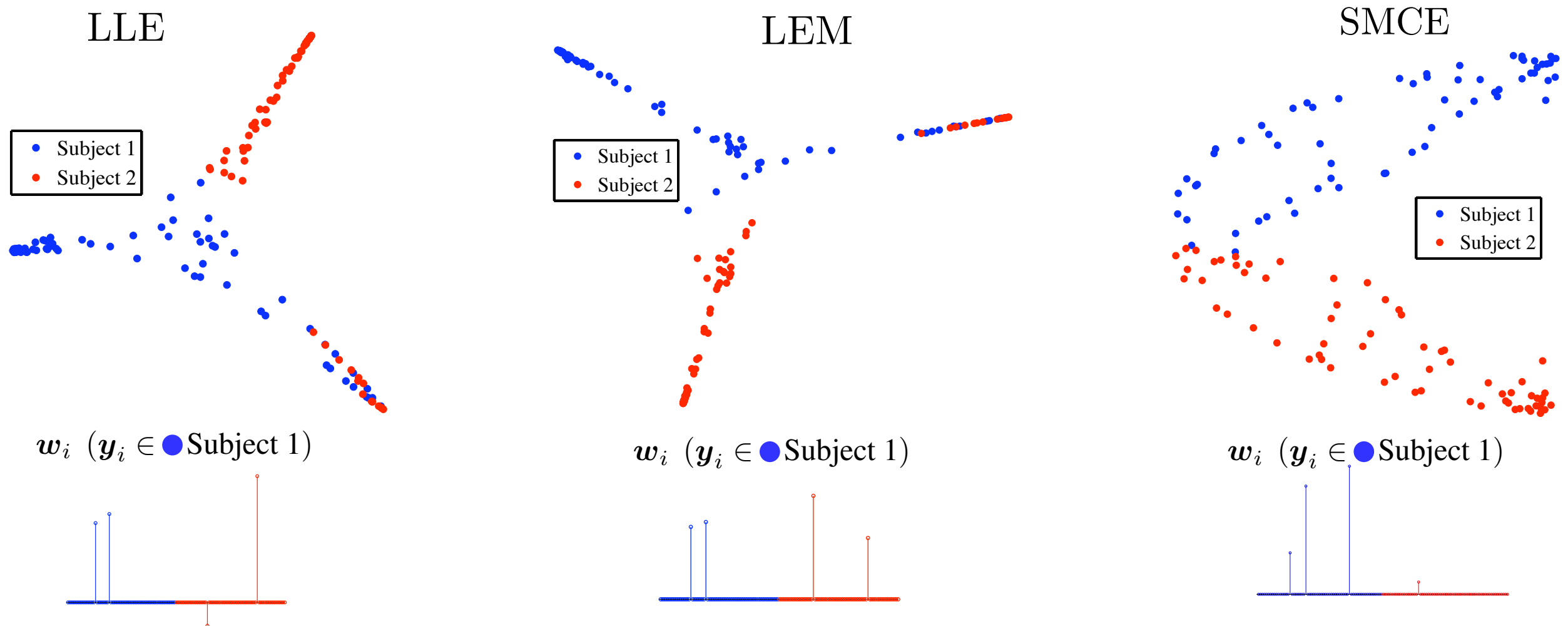


Experiments: real data

- Clustering and DR: faces

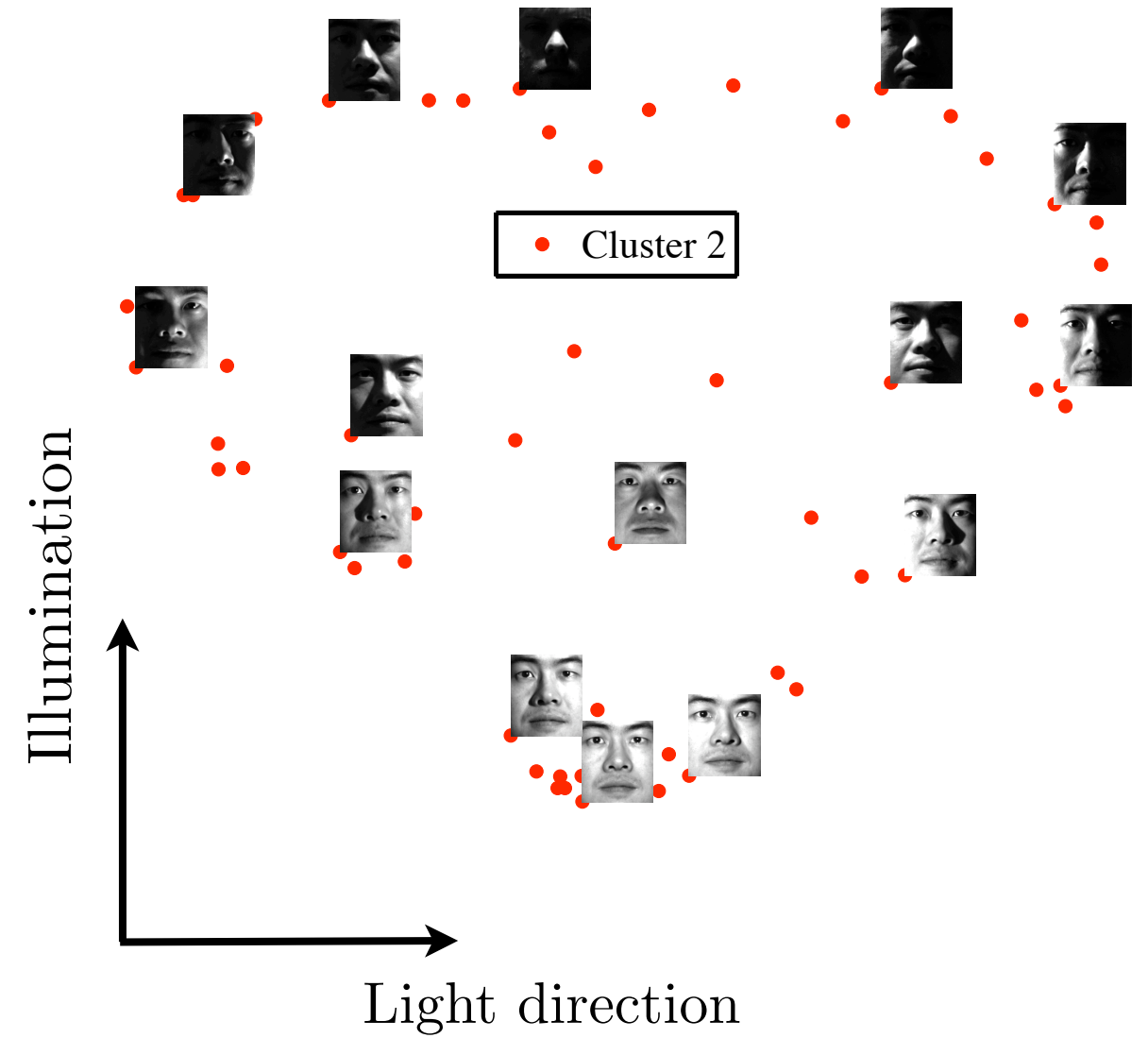
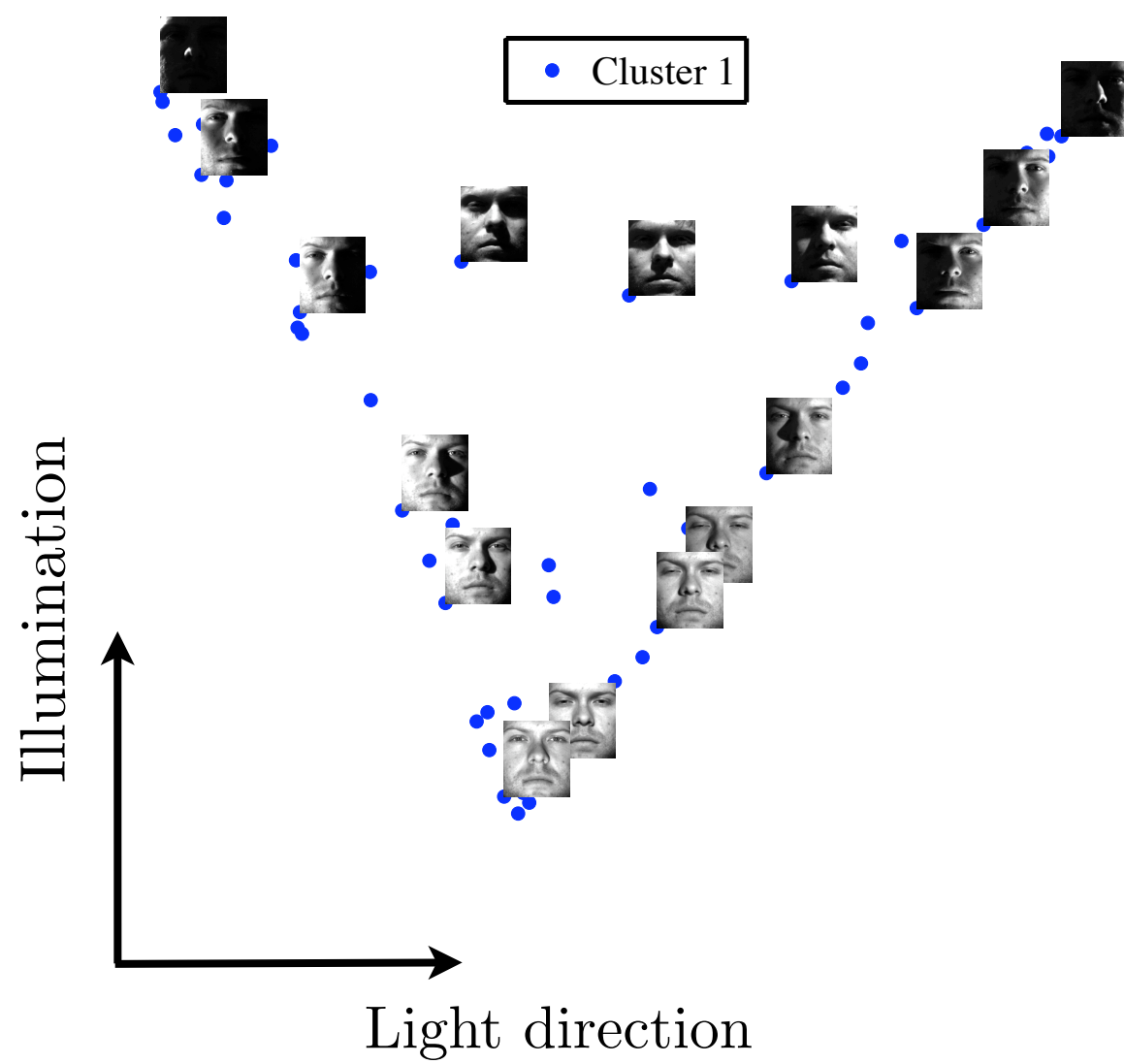
Table 1: Percentage of points whose K -NNs contain points from the other manifold.

K	1	2	3	4	7	10
	3.9%	10.2%	23.4%	35.2%	57.0%	64.8%



Experiments: real data

- Clustering and DR: faces



Conclusions

- Exploited the self-expressiveness property of the data for
 - clustering subspaces
 - clustering and embedding of nonlinear manifolds
 - Used sparse representation techniques
 - Developed theoretical guarantees
-

Thanks!

References:

- E. Elhamifar and R. Vidal, Sparse Subspace Clustering: Algorithm, Theory, and Applications, TPAMI.
 - E. Elhamifar and R. Vidal, Sparse Manifold Clustering and Embedding, NIPS 2011.
 - E. Elhamifar and R. Vidal, Sparse Subspace Clustering, CVPR 2009.
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