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# Recovery of Low-Rank Plus Compressed Sparse Matrices with Application to Unveiling Traffic Anomalies

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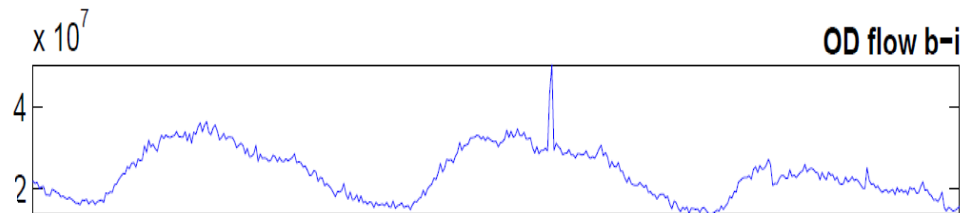
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# Context



- Backbone of IP networks
- **Traffic anomalies**: changes in origin-destination (OD) flows
  - Failures, transient congestions, DoS attacks, intrusions, flooding



- **Motivation**: Anomalies  $\rightarrow$  congestion  $\rightarrow$  limits end-user QoS provisioning

**Goal**: Measuring superimposed OD flows per link, identify anomalies by leveraging **sparsity** of anomalies and **low-rank** of traffic.

# Model

- Graph  $\mathcal{G}(\mathcal{N}, \mathcal{L})$  with  $N$  nodes,  $L$  links, and  $F$  flows ( $F \gg L$ )

(as) Single-path per OD flow  $x_{f,t}$

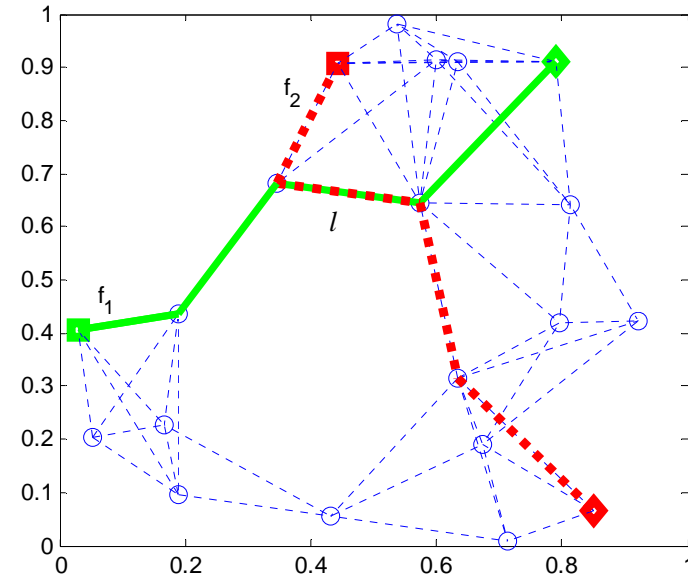
- Packet counts per link  $l$  and time slot  $t$

$$y_{l,t} = \sum_{f \in \mathcal{F}} r_{l,f} (x_{f,t} + a_{f,t}) + v_{l,t}$$

$\in \{0,1\}$

Anomaly

- Matrix model across  $T$  time slots



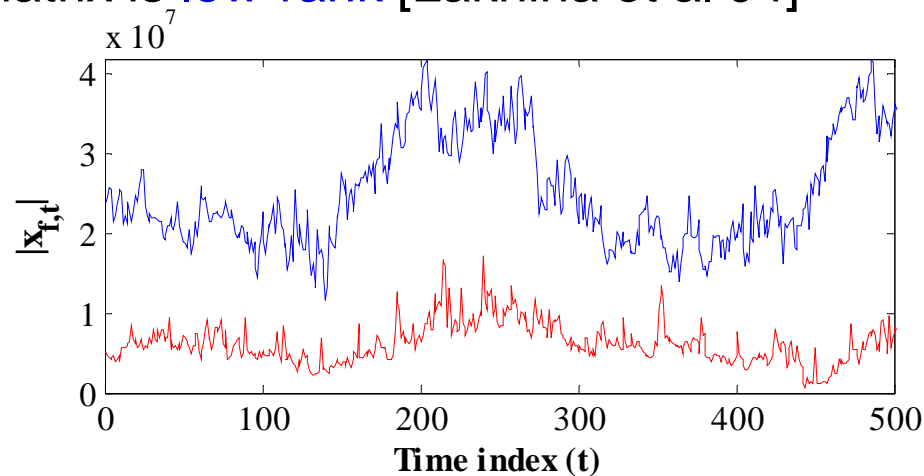
$$\mathbf{Y} = \mathbf{R}(\mathbf{X} + \mathbf{A}) + \mathbf{V}$$

$L \times T$        $L \times F$

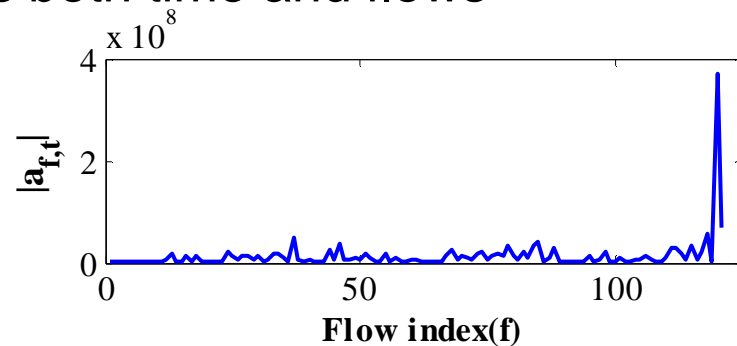
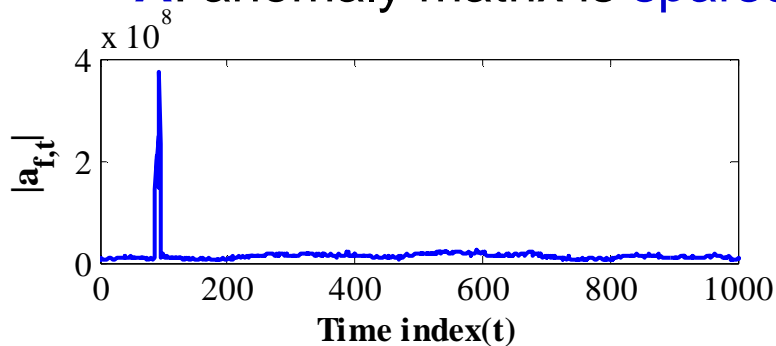
# Low rank and sparsity

$$\mathbf{Y} = \mathbf{R}(\mathbf{X} + \mathbf{A}) + \mathbf{V}$$

- **X**: traffic matrix is **low-rank** [Lakhina et al'04]



- **A**: anomaly matrix is **sparse** across both time and flows



# Objective and criterion

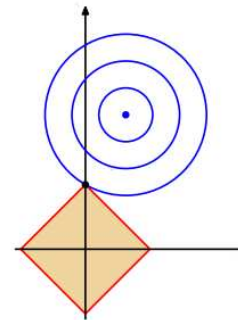
$$\mathbf{Y} = \underbrace{\mathbf{R}\mathbf{X}}_{:=\mathbf{X}_R} + \mathbf{R}\mathbf{A} + \mathbf{V}$$

- Given  $\mathbf{Y}$  and routing matrix  $\mathbf{R}$ , identify sparse  $\mathbf{A}$  when  $\mathbf{X}$  is low rank
  - $\mathbf{R}$  fat but  $\mathbf{X}_R$  still low rank
- Low-rank  $\rightarrow$  sparse vector of SVs  $\rightarrow$  nuclear norm  $\|\cdot\|_*$  and  $l_1$  norm

$$(\hat{\mathbf{X}}_R, \hat{\mathbf{A}}) = \arg \min_{(\mathbf{X}_R, \mathbf{A})} \frac{1}{2} \|\mathbf{Y} - \mathbf{X}_R - \mathbf{R}\mathbf{A}\|_F^2 + \lambda_* \|\mathbf{X}_R\|_* + \lambda_1 \|\mathbf{A}\|_1 \quad (\text{P1})$$



$$\sum_i \sigma_i(\mathbf{X}_R)$$



$$\sum_{i,j} |a_{i,j}|$$

# Prior art

- Anomaly identification (ID)
  - Change detection on per link time series [Brutlag'00], [Casas et al'10]
  - Spatial principal component analysis (PCA) [Lakhina et al'04]
  - Network anomography [Zhang et al'05]
- Suboptimal ID of anomalies across flows and time
- Rank minimization with the nuclear norm [Recht-Fazel-Parrilo'10]
  - Matrix decomposition [Candes et al'10], [Chandrasekaran et al'11]

$$\mathbf{M} = \mathbf{L}_0 + \mathbf{S}_0$$

$$\begin{aligned} \min_{\mathbf{L}, \mathbf{S}} \quad & \|\mathbf{L}\|_* + \lambda \|\mathbf{S}\|_1 \\ \text{s. to} \quad & \mathbf{M} = \mathbf{L} + \mathbf{S} \end{aligned}$$

- Principal Components Pursuit (PCP)

# Challenges and importance

$$\mathbf{Y} = \mathbf{X}_R + \mathbf{R}\mathbf{A} + \mathbf{V}$$

- $\mathbf{R}\mathbf{A}$  not necessarily sparse and  $\mathbf{R}$  fat  $\rightarrow$  PCP not applicable

- $$\underbrace{LT}_{\mathbf{X}_R} + \underbrace{FT}_{\mathbf{A}} \gg \underbrace{LT}_{\mathbf{Y}} \quad \text{Seriously underdetermined}$$

- Important special cases

- $\mathbf{R} = \mathbf{I}$ : matrix decomposition with PCP
- $\mathbf{X} = \mathbf{0}$ : compressive sampling with basis pursuit
- $\mathbf{R} = \mathbf{I}$  and  $\mathbf{A} = \mathbf{0}$ : PCA

# Exact recovery

- Noise-free model:  $\mathbf{Y} = \mathbf{X}_{R,0} + \mathbf{R}\mathbf{A}_0$

$$\begin{aligned} (\hat{\mathbf{X}}_R, \hat{\mathbf{A}}) = \arg \min_{(\mathbf{X}_R, \mathbf{A})} \quad & \|\mathbf{X}_R\|_* + \lambda \|\mathbf{A}\|_1 \\ \text{s.to} \quad & \mathbf{Y} = \mathbf{X}_R + \mathbf{R}\mathbf{A} \end{aligned}$$

**Q:** Can one recover sparse  $\mathbf{A}_0$  and low-rank  $\mathbf{X}_{R,0}$  exactly?

**A:** Yes! Under certain conditions on  $\{\mathbf{A}_0, \mathbf{X}_{R,0}, \mathbf{R}\}$

- Both  $\text{rank}(\mathbf{X}_{R,0})$  and support of  $\mathbf{A}_0$  generally unknown



# Identifiability

$$\mathbf{Y} = \mathbf{X}_{R,0} + \mathbf{R}\mathbf{A}_0 = \underbrace{\mathbf{X}_{R,0}}_{\mathbf{X}'_{R,0}} + \mathbf{R}\mathbf{H} + \underbrace{\mathbf{R}(\mathbf{A}_0 - \mathbf{H})}_{\mathbf{A}'_0}$$

- Problematic cases

- $\mathbf{R}\mathbf{H} \neq \mathbf{0}$  but  $\mathbf{X}'_{R,0}$  low-rank and  $\mathbf{A}'_0$  sparse
- $\mathbf{R}\mathbf{H} = \mathbf{0}, \mathbf{H} \neq \mathbf{0}$

- For  $\mathbf{X}_{R,0} = \mathbf{U}\mathbf{\Sigma}\mathbf{V}'$  and  $r = \text{rank}(\mathbf{X}_{R,0})$ , low-rank-preserving matrices  $\mathbf{R}\mathbf{H}$

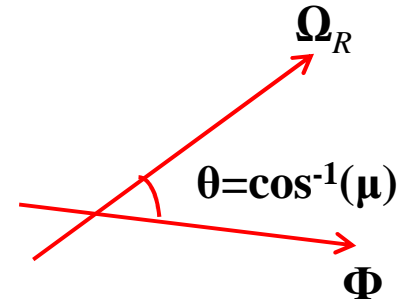
$$\Phi(\mathbf{X}_{R,0}) := \{\mathbf{Z} \in \mathbb{R}^{L \times T} : \mathbf{Z} = \mathbf{U}\mathbf{W}'_1 + \mathbf{W}_2\mathbf{V}', \mathbf{W}_1 \in \mathbb{R}^{T \times r}, \mathbf{W}_2 \in \mathbb{R}^{L \times r}\}$$

- Sparsity-preserving matrices  $\mathbf{R}\mathbf{H}$

$$\Omega_R(\mathbf{A}_0) := \{\mathbf{Z} \in \mathbb{R}^{L \times T} : \mathbf{Z} = \mathbf{R}\mathbf{H}, \text{supp}(\mathbf{H}) \subseteq \text{supp}(\mathbf{A}_0)\}$$

# Incoherence measures

$$\mu(\Omega_R, \Phi) := \max_{\mathbf{Z} \in \Omega_R \setminus \{\mathbf{0}\}} \frac{\|\mathcal{P}_\Phi(\mathbf{Z})\|_F}{\|\mathbf{Z}\|_F}$$



- Identifiability requires  $\Omega_R(\mathbf{A}_0) \cap \Phi(\mathbf{X}_R) = \{\mathbf{0}\} \Leftrightarrow \mu(\Omega_R, \Phi) < 1, \delta_k(\mathbf{R}) < 1$
- Incoherence among columns of  $\mathbf{R} \rightarrow \delta_k(\mathbf{R}), \theta_{s_1, s_2}(\mathbf{R})$
- Exact recovery requires  $\mu(\Omega_R, \Phi) \ll 1, \delta_k(\mathbf{R}) \ll 1$
- Incoherence between  $\mathbf{X}_{R,0}$  and  $\mathbf{R}$

$$\mu_R(\mathbf{U}) := \max_i \frac{\|\mathcal{P}_U(\mathbf{R}\mathbf{e}_i)\|}{\|\mathbf{R}\mathbf{e}_i\|}, \quad \mu(\mathbf{V}) := \max_i \|\mathcal{P}_V(\mathbf{e}_i)\|_F$$

$$\mu_R(\mathbf{U}, \mathbf{V}) := \|\mathbf{R}'\mathbf{U}\mathbf{V}'\|_\infty$$

# Main result

$$\mathbf{Y} = \mathbf{X}_{R,0} + \mathbf{R}\mathbf{A}_0 = \mathbf{U}\mathbf{\Sigma}\mathbf{V}' + \mathbf{R}\mathbf{A}_0$$

$$r := \text{rank}(\mathbf{X}_{R,0}) \quad s := \|\mathbf{A}_0\|_0$$

**Theorem:** Given  $\mathbf{Y}$  and  $\mathbf{R}$ , if every row and column of  $\mathbf{A}_0$  has at most  $k$  non-zero entries and  $\mathbf{R}$  has full row rank, then

$$(1 - \mu(\Omega_R, \Phi))^2 (1 - \delta_k(\mathbf{R})) > \omega_{\max}$$

$$(1 + \alpha_{\max}) \left( \frac{1 + \beta_{\max}}{1 - \beta_{\max}} \right) \mu_R(\mathbf{U}, \mathbf{V}) \sqrt{s} \\ + \mu(\Omega_R, \Phi) (1 + \delta_k(\mathbf{R}))^{1/2} (1 + \alpha_{\max}) \sqrt{r} < 1$$

imply  $\exists \lambda > 0$  for which (P1) **exactly** recovers  $\{\mathbf{X}_{R,0}, \mathbf{A}_0\}$

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# Intuition

- Exact recovery if
  - $r$  and  $s$  are sufficiently small
  - Nonzero entries of  $\mathbf{A}_0$  are “sufficiently spread out”
  - Columns and rows of  $\mathbf{X}_0$  not aligned with canonical basis
  - $\mathbf{R}$  behaves like a “restricted” isometry
- Interestingly
  - Amplitude of non-zero entries of  $\mathbf{A}_0$  irrelevant
  - No randomness assumption
- Satisfiability for certain random ensembles w.h.p

# Validating exact recovery

## ■ Setup

$L=105, F=210, T=420$

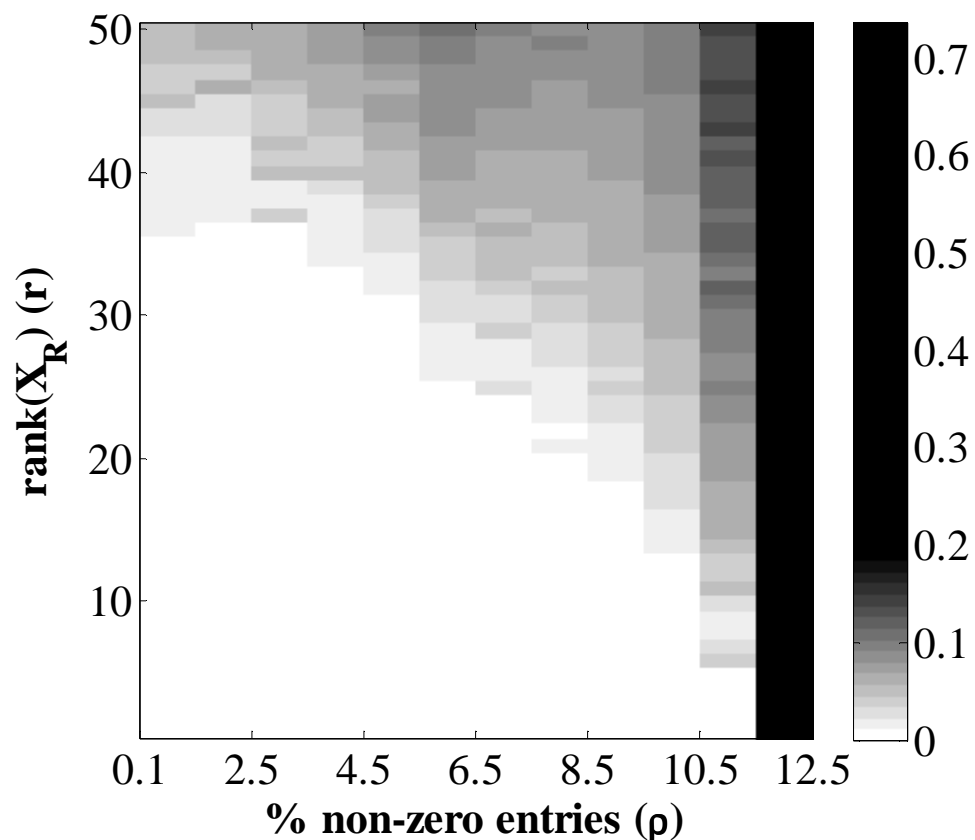
$\mathbf{R} \sim \text{Bernoulli}(1/2)$

$\mathbf{X}_R = \mathbf{R}\mathbf{W}\mathbf{Z}'$ ,  $\mathbf{W}, \mathbf{Z} \sim \mathcal{N}(0, 10^4/FT)$

$a_{ij} \in \{-1, 0, 1\}$  w. prob.  $\{\rho/2, 1-\rho, \rho/2\}$

## ■ Relative recovery error

$$e = \frac{\|\hat{\mathbf{A}} - \mathbf{A}_0\|_F}{\|\mathbf{A}_0\|_F}$$



# Centralized algorithm

$$(\hat{\mathbf{X}}_R, \hat{\mathbf{A}}) = \arg \min_{(\mathbf{X}_R, \mathbf{A})} \frac{1}{2} \|\mathbf{Y} - \mathbf{X}_R - \mathbf{R}\mathbf{A}\|_F^2 + \lambda_* \|\mathbf{X}_R\|_* + \lambda_1 \|\mathbf{A}\|_1$$

- Accelerated proximal gradient method for  $\mathbf{R} = \mathbf{I}_F$  [Lin et al'09]
- Idea: minimize a sequence of **overestimates** of (P1)

$$\mathbf{Z}[k] := \arg \min_{\{\mathbf{X}_R, \mathbf{A}\}} \left\{ \frac{L_f}{2} \|\mathbf{X}_R \mathbf{A}' - \mathbf{G}[k]\|_F^2 + \lambda_1 \|\mathbf{A}\|_1 + \lambda_* \|\mathbf{X}_R\|_* \right\} \quad \text{Separable wrt } \mathbf{X}_R \text{ and } \mathbf{A}$$

$\mathbf{T}[k] - \frac{1}{L_f} \nabla f(\mathbf{T}(k))$

- Intelligent choice of  $\mathbf{T}[k]$  and  $t[k]$

$$\mathbf{T}[k+1] = \mathbf{Z}[k] + \frac{t[k-1]-1}{t[k]} (\mathbf{Z}[k] - \mathbf{Z}[k-1])$$

$$t[k] = \left[ 1 + \sqrt{4t^2[k-1] + 1} \right] / 2$$

- Converges fast with accuracy  $O(1/k^2)$  [Nesterov'83]

# Thresholded updates

## ■ Traffic matrix update

$$\mathbf{X}_R[k+1] := \arg \min_{\mathbf{X}_R} \left\{ \frac{L_f}{2} \|\mathbf{X}_R - \mathbf{G}_X[k]\|_F^2 + \lambda_* \|\mathbf{X}_R\|_* \right\}$$

$$\text{Sol. } \mathbf{X}_R[k+1] = \mathbf{U} \mathcal{S}_{\lambda_*/L_f}[\boldsymbol{\Sigma}] \mathbf{V}'$$

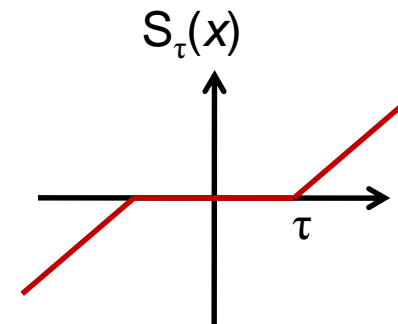
Singular-value  
thresholding

## ■ Anomaly matrix update

$$\mathbf{A}[k+1] := \arg \min_{\mathbf{A}} \left\{ \frac{L_f}{2} \|\mathbf{A} - \mathbf{G}_A[k]\|_F^2 + \lambda_1 \|\mathbf{A}\|_1 \right\}$$

$$\text{Sol. } \mathbf{A}[k+1] = \mathcal{S}_{\lambda_1/L_f}[\mathbf{G}_A[k]]$$

Soft thresholding



## ■ Low rank $\mathbf{X}_R[k+1]$ and sparse $\mathbf{A}[k+1]$

# Benchmark: PCA-based method

- **Idea:** anomalies increase considerably rank( $\mathbf{Y}$ )

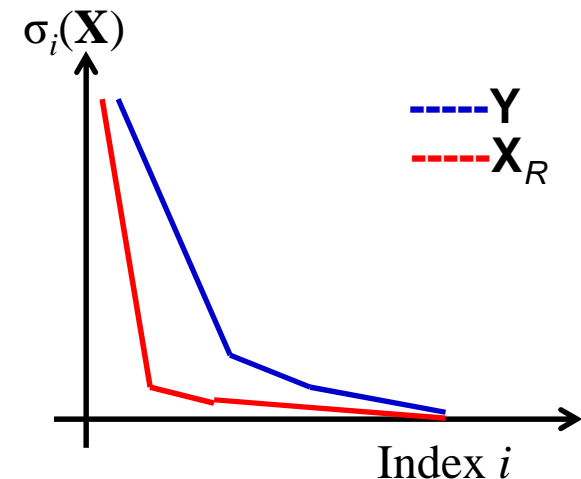
## Algorithm [Lakhina et al'04]

i) Form subspace  $S$  via  $r$ -dominant left singular vectors of  $\mathbf{Y}$  (resp.  $S^c$ )

ii) Test:  $\|\mathcal{P}_{S^c}(\mathbf{y}_t)\|_2 \geq \frac{H_1}{H_0} \tau$ , for  $t = 1, \dots, T$

## ■ Limitations

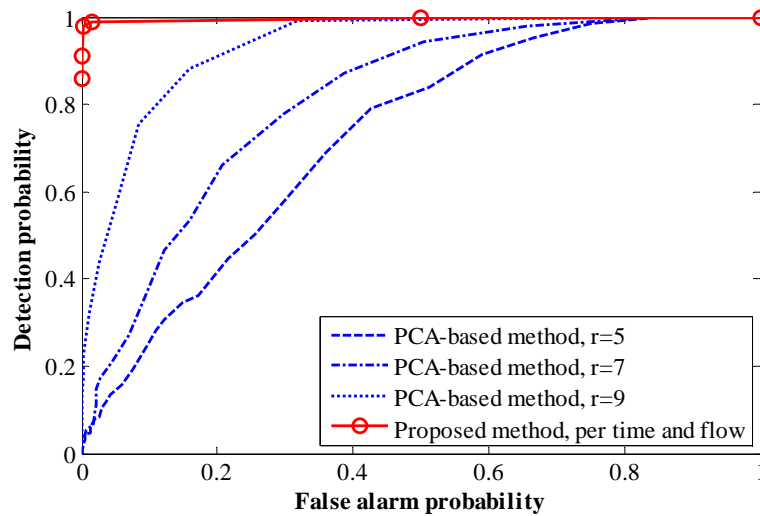
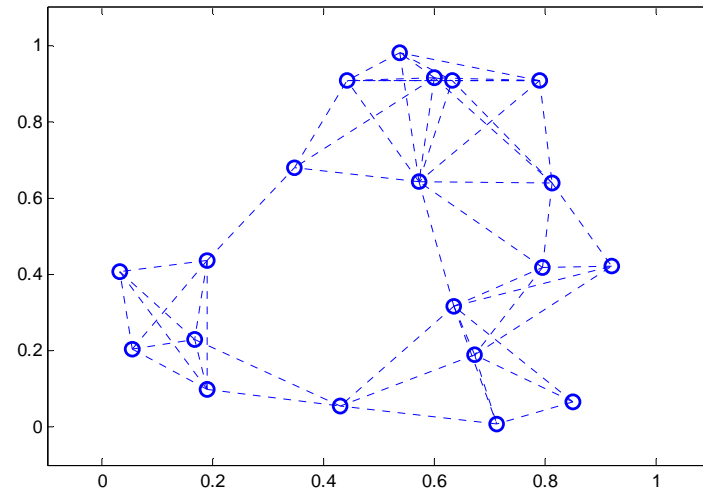
- Unable to identify flows
- Assumes knowledge of rank( $\mathbf{X}_R$ )



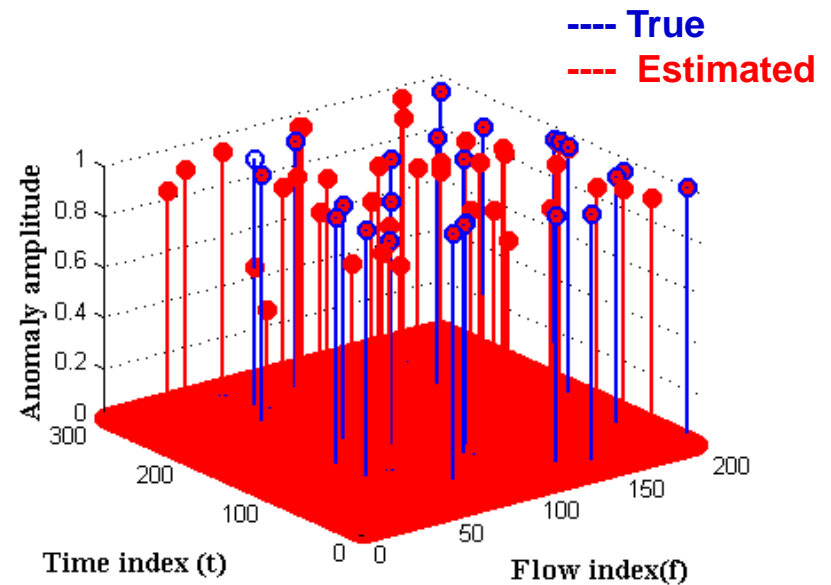


# Synthetic data

- Random network topology
  - $N=20, L=108, F=360, T=760$
  - Minimum hop-count routing



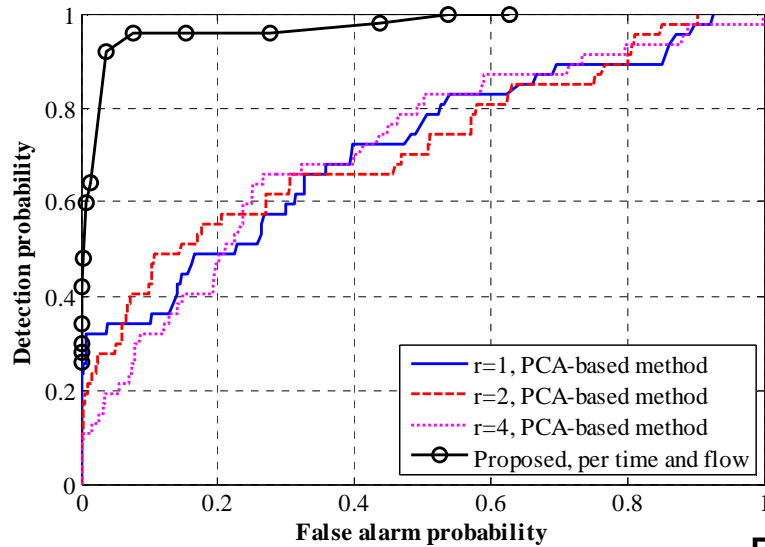
$$P_f = 10^{-4}$$
$$P_d = 0.97$$



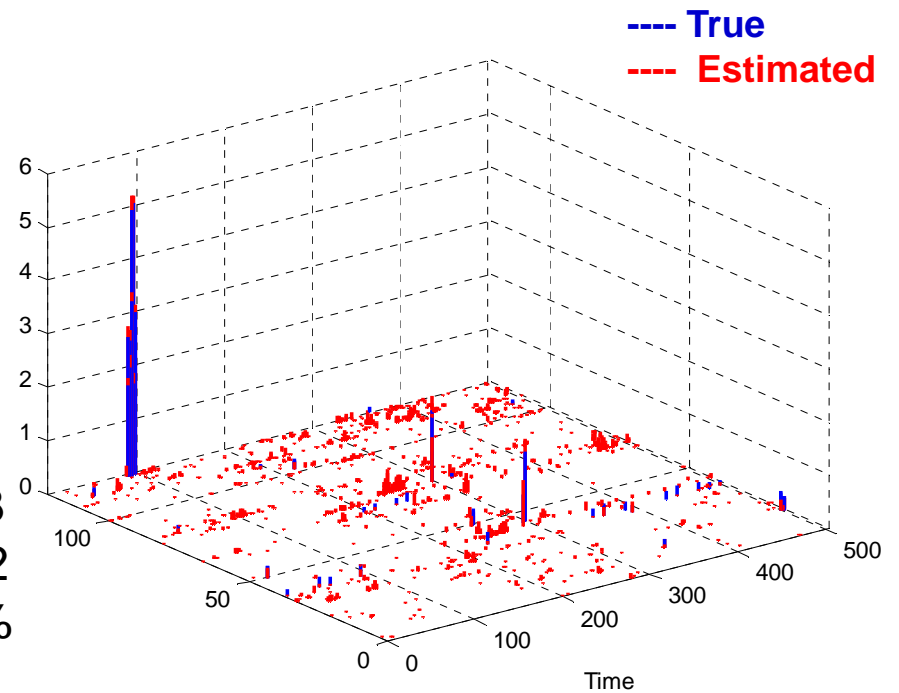
# Real data

## Abilene network data

- Dec. 8-28, 2008
- $N=11$ ,  $L=41$ ,  $F=121$ ,  $T=504$



$P_f = 0.03$   
 $P_d = 0.92$   
 $Q_e = 27\%$



# Concluding summary

- Exact recovery of low-rank plus compressed matrices
- Important task of network anomaly detection
  
- Detailed discussion
  - Identifiability and exact recovery

M. Mardani, G. Mateos, and G. B. Giannakis, "[Recovery of Low-Rank Plus Compressed Sparse Matrices with Application to Unveiling Traffic Anomalies](#)," *IEEE Trans. Info. Theory*, submitted Apr. 2012. **arXiv: 1204.6537**

- Distributed optimization with missing data

M. Mardani, G. Mateos, and G. B. Giannakis, "[In-network Sparsity-regularized Rank Minimization: Algorithms and Applications](#)," *IEEE Trans. Sig. Proc.*, submitted Feb. 2012. **arXiv: 1203.1570**

*Thank You!*

