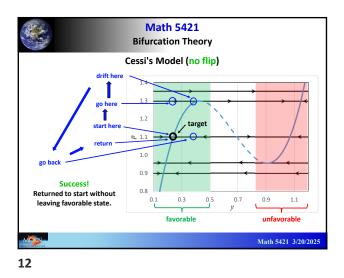
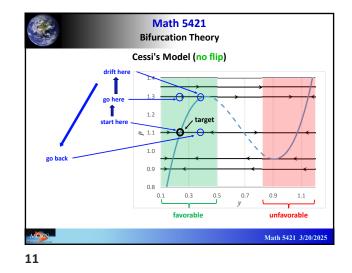
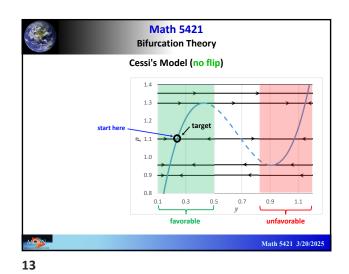
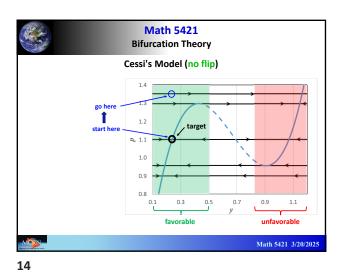


Math 5421 the second **Bifurcation Theory** Cessi's Model (no flip) drift h go her Î 1.2 targe start h ۹, 1.1 1.0 0.9 0.8 0.1 0.3 0.5 0.7 0.9 1.1 favorable unfavorable Math 5421 3/20/2025



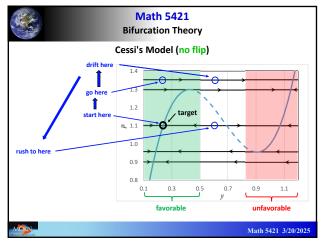


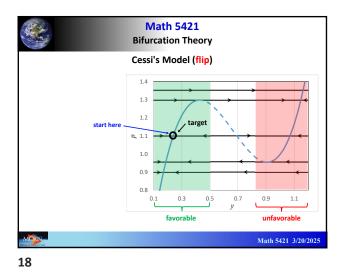


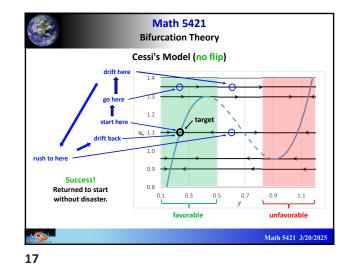


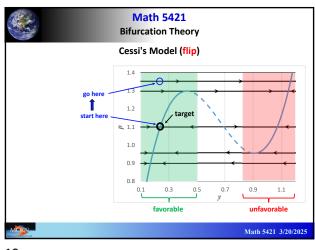
Str. Math 5421 **Bifurcation Theory** Cessi's Model (no flip) drift he Î go her 1.2 start h target ۹, 1.1 1.0 0.9 0.8 0.1 0.3 0.5 0.7 0.9 1.1 favorable unfavorable Math 5421 3/20/2025

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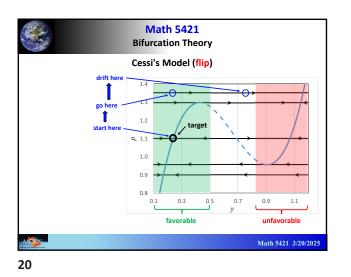


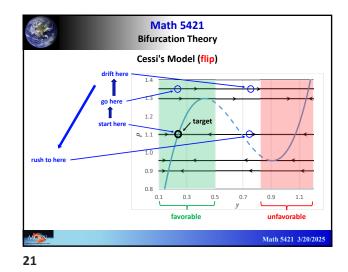






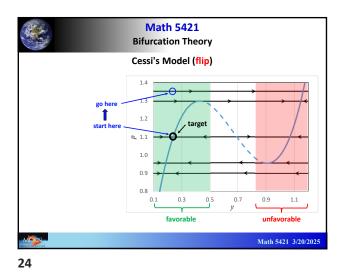


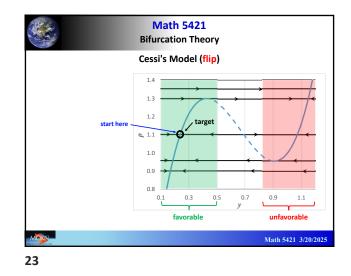


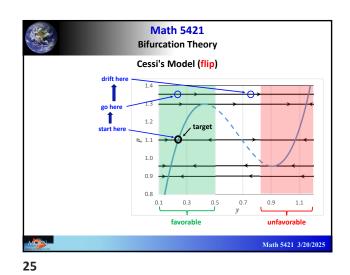


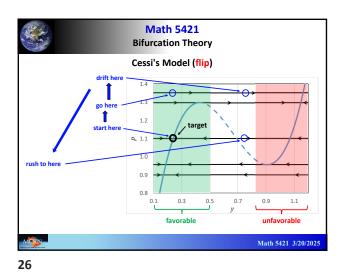
Math 5421 the second **Bifurcation Theory** Cessi's Model (flip) drift h 1 θ go he Î 1.2 targe start h a, 1.1 rush to her 0.9 0.8 Failure! 0.1 0.3 0.5 0.7 0.9 1.1 ended in disaster (already flipped scenario) favorable unfavorable Math 5421 3/20/2025

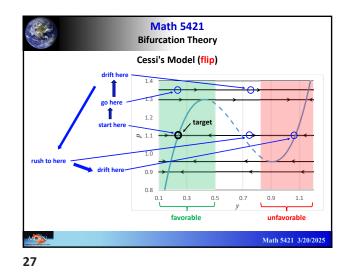
22



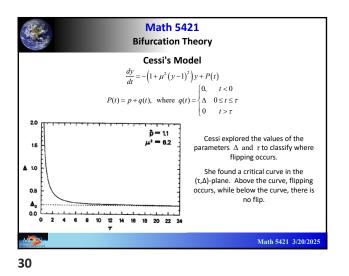


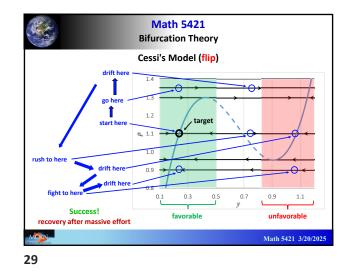


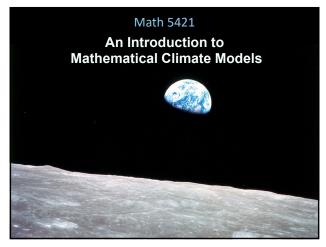




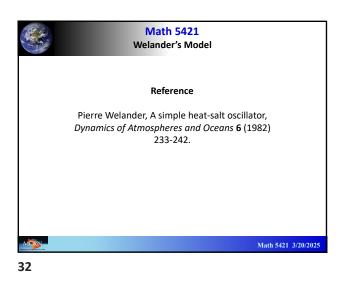
Math 5421 **Bifurcation Theory** Cessi's Model (flip) drift h 1 e Î 1.2 start h targe a, 1.1 rush to 0.9 0.3 0.7 1.1 0.1 0.5 0.9 favorable unfavorable Math 5421 3/20/2025

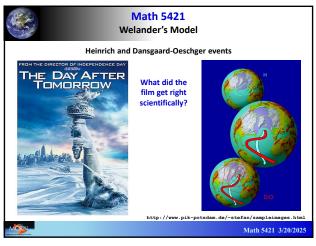




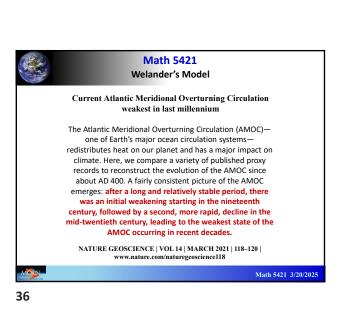


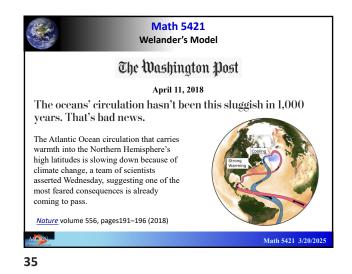


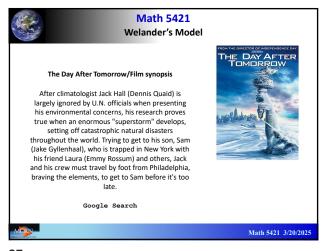




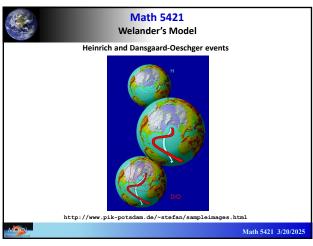


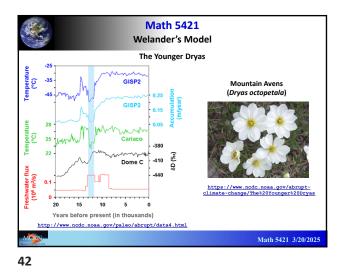


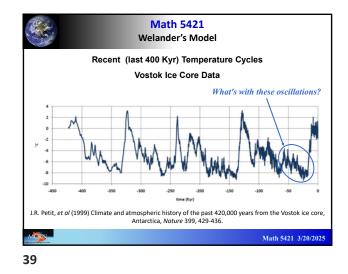


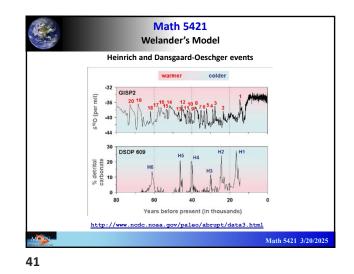


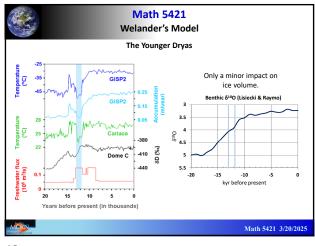


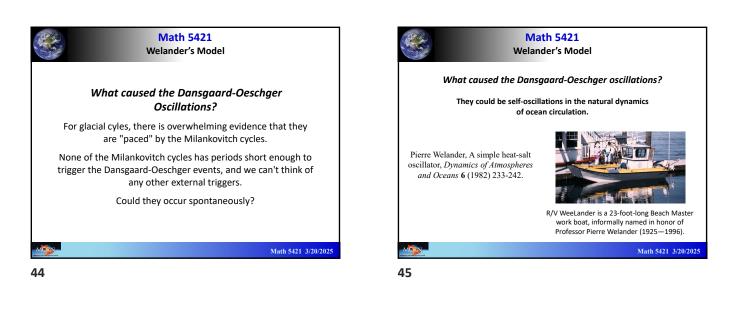


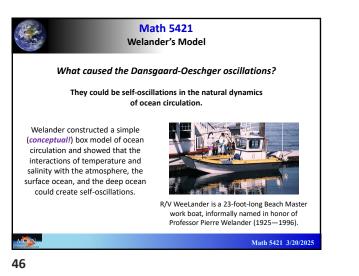




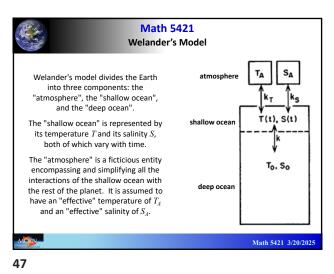


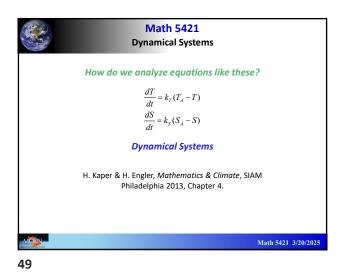


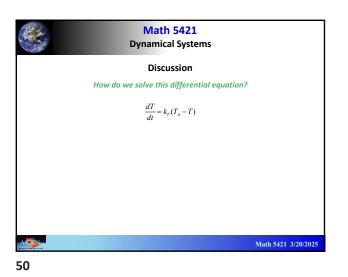


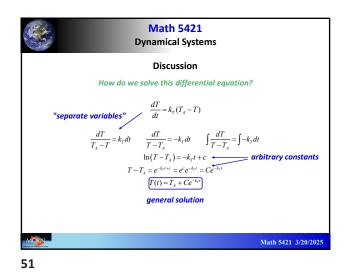


Math 5421 Welander's Model The "deep ocean" is assumed to have a atmosphere constant temperature T_0 and a constant salinity S_0 . The interaction between the shallow T(t). S(t) ocean and the atmosphere is modeled shallow ocean as a dynamic transfer of relaxation to equilibrium: $\frac{dT}{dt} = k_T (T_A - T),$ To, So $\frac{dS}{ds} = k_S(S_A - S),$ deep ocean where k_T and k_S are constants. Math 5421 3/20/2025 48

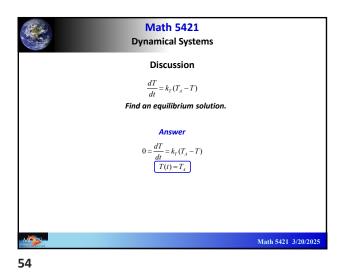






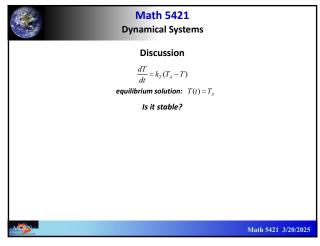


Math 5421
Dynamical SystemsDiscussionHow do we solve this differential equation? $\frac{dT}{dt} = k_r(T_a - T)$
 $\overline{(T(t) = T_a + Ce^{-k_t})}$
general solution
check $\frac{dT}{dt} = \frac{d}{dt}(T_a + Ce^{-k_t}) = 0 + Ce^{-k_t}(-k_r) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a + Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - (T_a - Ce^{-k_t}))) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_rCe^{-k_t}) \ (k_r(T_a - T) = k_r(T_a - Ce^{-k_t})) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_r(T_a - Ce^{-k_t})) = -k_rCe^{-k_t} \ (k_r(T_a - T) = k_rCe^{-k_t}) \ (k_r(T_a - Ce^{-k_t})) = -k_rCe^{-k_t} \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-k_t}) \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-k_t}) \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-k_t}) \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-k_t} \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-k_t}) \ (k_r(T_a - Ce^{-k_t}) = -k_rCe^{-$

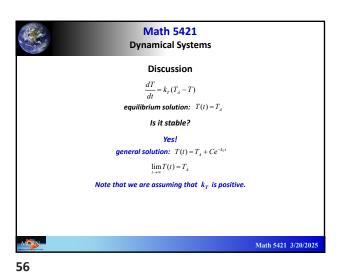


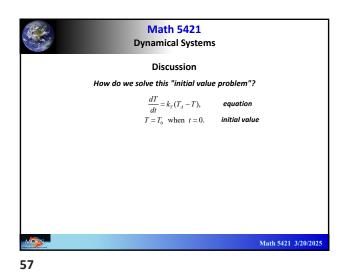
Math 5421
Dynamical SystemsDiscussion $\frac{dT}{dt} = k_r(T_t - T)$
Find an equilibrium solution.

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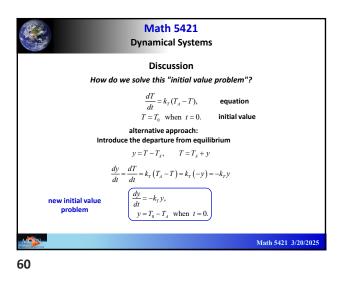


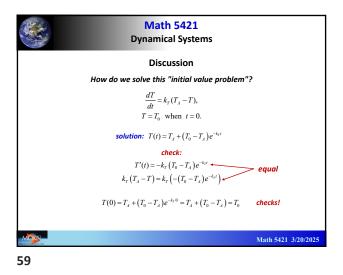
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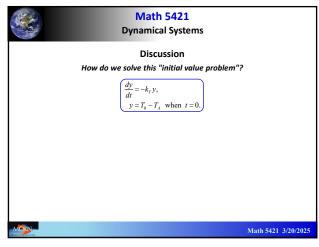




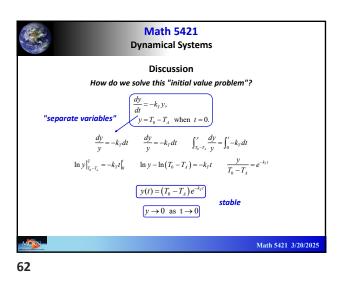
EXAMPLE 1 Distribution Distribution Distribution Distribution Distribution Distribution $d_{di}^{T} = b_{i}^{T} (f_{i} - f_{i})$ $d_{di}^{T} = b_{i}^{T} (f_{i} - f_{i})$ $d_{$

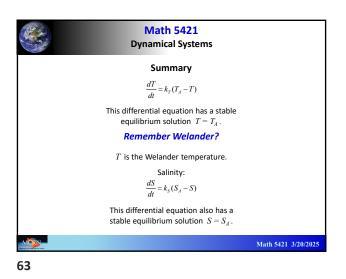


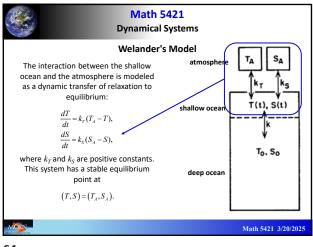












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