

CSci 8980, Fall 2012

Specifying and Reasoning About Computational Systems

Some Examples of Specifications

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Encoding Functional Programs in λ Prolog

We have already seen how to use λ -tree syntax to represent types and (untyped) lambda terms

It is easy to extend this setup to obtain a framework for encoding arbitrary functional programs, e.g.

```

type bool ty.
type lst ty -> ty.

type i int -> tm.
type tt, ff tm.
type nil, cons tm.
type sum tm.
type cond tm -> tm -> tm -> tm.
type fix (tm -> tm) -> tm.

```

Other combinators, functions, data types, can also be encoded
If the types language has explicit polymorphism, this can also be encoded using λ -tree syntax

Typing and Evaluation for Functional Programs

The earlier judgements for typing and evaluation can be easily extended to accommodate the new constructs

For example, consider

```

(of tt bool) & (of ff bool).
of (i I) int.
of sum (int --> int --> int).
...
of (cond C T E) A :-
  of C bool, of T A, of E A.
of (fix E) Ty :-
  pi x\ (of x Ty => of (E x) Ty).
...
eval (app (app sum E1) E2) (i I) :-
  eval E1 (i I1), eval E2 (i I2), I is I1 + I2.
eval (cond C T _) V :- eval C tt, eval T V.
eval (cond C _ E) V :- eval C ff, eval E V.
eval (fix E) V :- eval (E (fix E)) V.

```

Small-Step Evaluation via Evaluation Contexts

Lambda terms provide an elegant means for characterizing evaluation contexts in computation via repeated rewriting

```

type val, non_val, redex tm -> o.
type reduce, eval tm -> tm -> o.
type context tm -> (tm -> tm) -> tm -> o.

context R (x\ x) R :- redex R.
context (cond M N P) (x\ cond (E x) N P) R :-
  non_val M, context M E R.
context (app M N) (x\ (app (E x) N)) R :-
  non_val M, context M E R.
context (app V M) (x\ (app V (E x))) R :-
  val V, non_val M, context M E R.

eval V V :- val V.
eval M V :- context M E R, reduce R N, eval (E N) V.

```

Here `non_val`, `val`, and `redex` recognize non-values, values and redexes at the root and `reduce` contracts redexes

Recognizing Tail Recursive Structure

In an expression of the form `(fix (f\ F))` we have to check that usage of `f` in `F` is suitably restricted

Assume that the signature of the language has been reified via the predicate `term`

```
type tr, fn, trabs, headrec, trbody tm -> o.
tr (fix M) :- pi F\ ((fn F) => (trabs (M F))).
trabs (abs R) :- pi X\ ((term X) => (trabs (R X))).
trabs R :- trbody R.
trbody (cond M N P) :- term M, trbody N, trbody P.
trbody M :- term M ; headrec M.
headrec (app M N) :- (fn M ; headrec M), term N.
```

Recursion over binding structure allows for a generalization of template matching a la Burstall and Darlington (Huet and Lang)

Binding Sensitive Analysis of Functional Programs

Some other examples in the book where λ -tree syntax is used to advantage:

- Partial evaluation, reductions under abstractions
AUGMENT and GENERIC provide logical support for descent inside the body of an (object-language) abstraction
- Continuation-passing style transformation of programs
An approach that uses λ -calculus equivalences to correctly transform programs to a tail recursive form

Specifying a Natural Deduction Calculus

We will think of formalizing this as a typing calculus

A sampling of the proof terms that might be used in this pursuit

kind proof type.

```
type imp_i (proof -> proof) -> proof.
type imp_e form -> proof -> proof -> proof.
type or_i1,
  or_i2 proof -> proof.
type or_e form -> form -> proof
  -> (proof -> proof)
  -> (proof -> proof) -> proof.
type all_e term -> (term -> form) -> proof -> proof.
type all_i (term -> proof) -> proof.
type some_e (term -> form) -> proof ->
  (term -> proof -> proof) -> proof.
type some_i term -> proof -> proof.
```

Typically we store as much information in the proof term as is necessary to make type checking well-behaved

Specifying a Natural Deduction Calculus (Continued)

The inference rules of the calculus are then formalized as the definition of a predicate that relates proof terms and formulas

```
type # proof -> form -> o.      infix # 2.

(imp_i Q) # (A ==> B) :- pi p\ (p # A) => ((Q p) # B).
(imp_e A P1 P2) # B :- (P1 # A), (P2 # (A ==> B)).
(or_i1 P) # (A !! B) :- P # A.
(or_i2 P) # (A !! B) :- P # B.
(or_e A B P Q1 Q2) # C :-
  (P # (A !! B)),
  (pi p1\ (p1 # A) => ((Q1 p1) # C)),
  (pi p2\ (p2 # B) => ((Q2 p2) # C)).
(all_i Q) # (all A) :- pi y\ (Q y) # (A y).
(all_e T A P) # (A T) :- (P # (all A)).
(some_i T P) # (some A) :- P # (A T).
(some_e A P1 Q) # B :-
  (P1 # (some A)),
  pi y\ pi p\ (p # (A y)) => ((Q y p) # B).
```

Specifying versus Implementing Proof Systems

- Declarative specifications like that for the natural deduction calculus are well-suited for meta-theoretic reasoning
- Sometimes, such calculi can also be structured to provide a basis for proof search
E.g, Dyckhoff's calculus and calculi that integrate focusing
- However typically such calculi, together with depth-first exploration, are not good for proof search
- Tactics and tacticals based approaches provide a means to "bake your own" control regime
 - Inference rules are encoded as standalone goal transformers called tactics
 - Tacticals provide a framework for combining such tactics into larger units
 - In the λ Prolog setting, definitions of tacticals use predicate variables

Process Expressions in the π -Calculus

A language for modelling processes that interact using names

Two important syntactic categories: *names* and *processes*

The process expressions in the finite π -calculus:

$$P ::= 0 \mid P \mid P \mid P + P \mid x(y).P \mid \bar{x}y.P \mid [x = y].P \mid \tau.P \mid (y)P$$

Here x and y represent names

The intended meaning of the various expressions

- 0 is the null process, \mid and $+$ stand for parallel composition and choice, $\tau.P$ is a process that can evolve silently to P
- $x(y).P$ can accept a name along channel x and transform into P with y replaced by this name
- $\bar{x}y.P$ can evolve into P by outputting y along channel x
- $[x = y].P$ can become P if x and y are equal
- $(y)P$ represents the restriction of the name y to P

Representing Process Expressions in λ Prolog

Declarations provide the framework for an encoding

```
kind name      type.
kind proc      type.
```

```
type null      proc.
type plus, par proc -> proc -> proc.
type in        name -> (name -> proc) -> proc.
type out, match name -> name -> proc -> proc.
type taup      proc -> proc.
type nu        (name -> proc) -> proc.
```

Note the representation of input processes and restriction

E.g., the process $(b(z).P \mid (y)\bar{b}y.Q)$ will be represented by

```
(par (in b (z\ P')) (nu (y\ (out b y Q'))))
```

where b is declared to be a `name` and P' and Q' are encodings of P and Q

Transitions in the π -Calculus

The operational semantics is given by inference rules defining judgements of the form $P \xrightarrow{A} Q$

To be read as "process P evolves into Q via action A "

Note: This is what is often referred to as "small-step" semantics

There are four kinds of actions

τ	the <i>silent</i> action
$x(y)$	the (bound) input action
$\bar{x}y$	the free output action
$\bar{x}(y)$	the bound output action

The last differs from the third in that it emits a private name (bound by a restriction) on the channel x

The bound actions involve side conditions and formalizing their interaction correctly requires some care

Bound Actions and their Interaction

The rules of interest are the following

$$\frac{}{x(z).P \xrightarrow{x(w)} P\{w/z\}} \text{ INPUT-ACT, } w \text{ not free in } (z)P$$

$$\frac{P \xrightarrow{\bar{x}y} P'}{(y)P \xrightarrow{\bar{x}(w)} P'\{w/y\}} \text{ OPEN, } x \neq y, w \text{ not free in } (y)P$$

$$\frac{P \xrightarrow{\bar{x}(w)} P' \quad Q \xrightarrow{x(w)} Q'}{P|Q \xrightarrow{\tau} (w)(P'|Q')} \text{ CLOSE} \quad \frac{P \xrightarrow{\bar{x}(w)} P' \quad Q \xrightarrow{x(w)} Q'}{Q|P \xrightarrow{\tau} (w)(Q'|P')} \text{ CLOSE}$$

Here

- The OPEN rule “opens” a scope represented by a restriction operator
- The CLOSE rule closes the corresponding scope after interaction with an input action

For example, consider the evolution of $b(z).P|(y)\bar{b}y.Q$

Encoding Transition Rules in λ Prolog

The key idea in capturing the interaction of bounded actions

Bounded actions will produce abstracted processes that can be combined by being fed a common name

To realize this idea, we encode transitions via *two* predicates

Specifically, we will use the following λ Prolog declarations

```
kind action          type.
type tau             action.
type up, dn         name -> name -> action.
```

```
type one            proc -> action -> proc -> o.
type onep          proc -> (name -> action)
                  -> (name -> proc) -> o.
```

Some actions will yield clauses for only one predicate, some will yield clauses for both

Encoding Transition Rules in λ Prolog (Continued)

Using the signature, the actions $x(w)$ and $\bar{x}(w)$ will be represented by $(dn\ x)$ and $(up\ x)$ respectively

The (bound) name w will become an abstraction over the resulting process

The clauses for the INPUT-ACT, OPEN and CLOSE rules

```
onep (in X M) (dn X) M.
onep (nu P) (up X) P' :-
  pi y \ one (P y) (up X y) (P' y).
one (par P Q) tau (nu y \ par (P' y) (Q' y)) &
one (par Q P) tau (nu y \ par (Q' y) (P' y)) :-
  onep P (up X) P', onep Q (dn X) Q'.
```

The use of abstracted processes ensures all the side conditions are met

The clause for the CLOSE action applies these abstractions to a common name to realize the combination

Encoding Transition Rules in λ Prolog (Continued)

To complete the picture, we consider the encoding of some other typical rules

- The free output action will yield a clause only for `one`

$$\frac{}{\bar{x}y.P \xrightarrow{\bar{x}y} P} \text{ OUTPUT-ACT}$$

```
one (out X Y P) (up X Y) P.
```

- Bound input and free output actions can also interact

$$\frac{P \xrightarrow{\bar{x}y} P' \quad Q \xrightarrow{x(z)} Q'}{P|Q \xrightarrow{\tau} P'|(Q[y/z])} \quad \frac{P \xrightarrow{\bar{x}y} P' \quad Q \xrightarrow{x(z)} Q'}{Q|P \xrightarrow{\tau} (Q[y/z])|P} \text{ COM}$$

```
one (par P Q) tau (par S (T Y)) :-
  one P (up X Y) S, onep Q (dn X) T.
one (par P Q) tau (par (S Y) T) :-
  onep P (dn X) S, one Q (up X Y) T.
```

Encoding Transition Rules in λ Prolog (Continued)

- The “congruence” over a choice must be reflected on both `one` and `onep`

$$\text{SUM : } \frac{P \xrightarrow{\alpha} P'}{P + Q \xrightarrow{\alpha} P'} \quad \frac{P \xrightarrow{\alpha} P'}{Q + P \xrightarrow{\alpha} P'}$$

```
one (plus P Q) A P' :- one P A P'; one Q A P'.
onep (plus P Q) A P' :- onep P A P'; onep Q A P'.
```

- A similar kind of congruence applies to parallel composition

$$\text{PAR : } \frac{P \xrightarrow{\alpha} P'}{P | Q \xrightarrow{\alpha} P' | Q} \quad \frac{P \xrightarrow{\alpha} P'}{Q | P \xrightarrow{\alpha} Q | P'}$$

```
one (par P Q) A (par P' Q) &
one (par Q P) A (par Q P') :- one P A P'.
onep (par P Q) A (y \ par (P' y) Q) &
onep (par Q P) A (y \ par Q (P' y)) :- onep P A P'.
```

Using the π -Calculus Specifications

- Specifications can be used to experiment with the behaviour of described systems

λ Prolog allows the specifications to be animated, facilitating, for example

- the inspection of one step transitions from processes
- the examination of traces

Here we are talking about the *may* behaviour of systems

- We can also consider the use of the specifications to *analyze* the behaviour of systems

For example, showing that a process cannot make some transitions, showing similarity between processes, etc

However, for this we also need methods for talking about the *only things* a process can do, i.e. its *must* behaviour

To do this correctly, we will need a framework that treats the “only if” aspect of logic specifications