

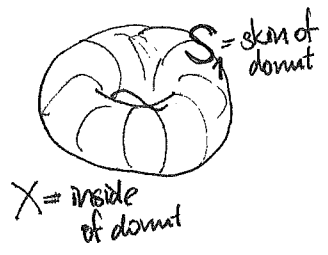
(121) Meanwhile  $\int_S \left( \frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right) dx \wedge dy = \int_S (1 - (-1)) dx \wedge dy = 2 \int_S dx \wedge dy$   
 $= 2 \text{ area}(S) = 2\pi(2^2 - 1^2) = 6\pi \checkmark$

4/23/07 > THM 6.10.6 (Gauss's Thm. or Divergence Thm.)

For  $X$  a piece-with-boundary in  $\mathbb{R}^3$  and boundary surfaces  $S_1, \dots, S_r$   
 a 2-form  $\varphi = \Phi_F$  for some  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  will have

$$\int_X \text{div} \vec{F} dx dy dz = \int_X d\varphi = \int_{\partial X} \varphi = \sum_{i=1}^r \int_{S_i} \Phi_F = \sum_{i=1}^r \int_{S_i} \vec{F} \cdot \vec{n} |d\vec{x}|$$

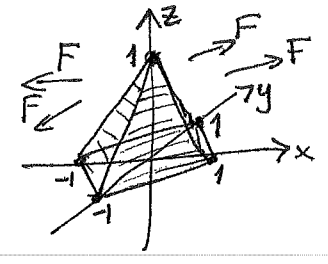
↑  
appropriately oriented



EXAMPLE: Let  $\vec{F} = \text{curl} \begin{pmatrix} z^2 \\ z^3 \\ z^4 \end{pmatrix}$ . What is  $\int_S \Phi_F$  for  $S =$  the four top slanted faces of this pyramid?

(A typical trick question involving Stokes-type theorems)

$$= \begin{bmatrix} \partial/\partial x \\ \partial/\partial y \\ \partial/\partial z \end{bmatrix} \times \begin{bmatrix} z^2 \\ z^3 \\ z^4 \end{bmatrix} = \begin{bmatrix} -3z^2 \\ -(-2z) \\ 0 \end{bmatrix}$$



Letting  $X =$  inside of pyramid  
 $S' =$  bottom face of pyramid

then  $\int_X \text{div} \vec{F} dx dy dz = \int_S \Phi_F + \int_{S'} \Phi_F$   
 =  $\int_S \Phi_F + \int_{S'} \Phi_F$  with appropriate orientations

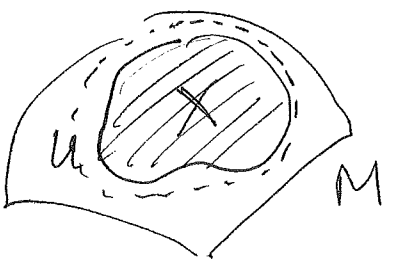
$$0 = \int_X \text{div} \text{curl} \begin{pmatrix} z^2 \\ z^3 \\ z^4 \end{pmatrix} dx dy dz \Rightarrow \int_S \Phi_F = - \int_{S'} \Phi_F = 0$$

because  $\vec{F} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{bmatrix} -3z^2 \\ 2z \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  on the whole face  $S'$ , where  $z=0$

See book's EXAMPLE 6.10.8 for a nice derivation of Archimedes's principle of buoyancy from Div. Thm!

§6.9 General Stokes's Thm (+ sketch informal proof)

THM 6.9.2  $X$  piece-with-boundary  $\subset M$   $k$ -dim manifold and  $\varphi \in A^{k-1}(U)$  with coefficients in  $C^0(U)$



$U_{\text{open}} \subset \mathbb{R}^n$

$\Rightarrow \int_{\frac{\partial X}{\text{given boundary orientation induced from } X}} \varphi = \int_X d\varphi$

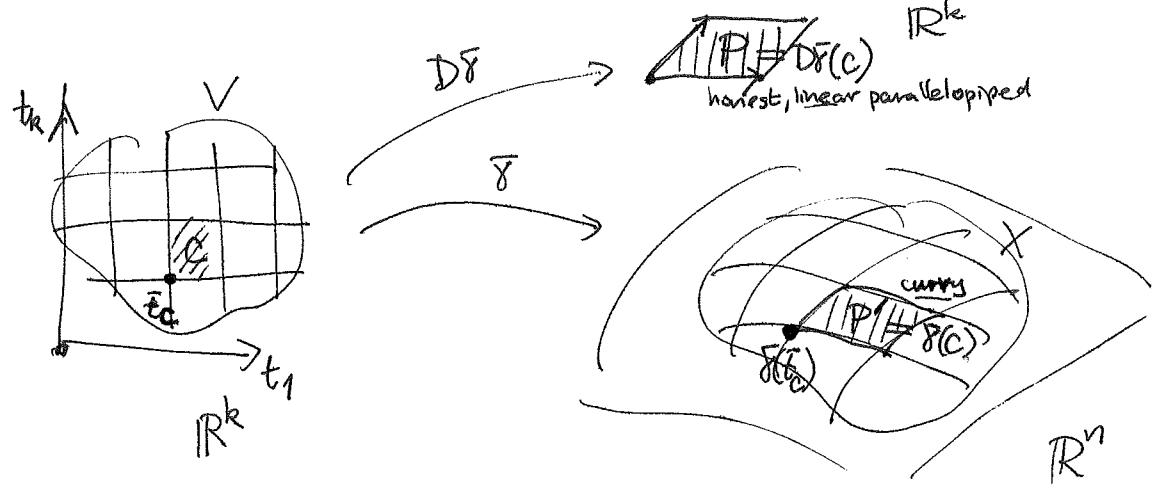
Informal sketch proof:

A key point is that if we rephrase our definition of  $d\varphi$ , then it shows we have made Stokes's Thm true infinitesimally (by defn!) for small parallelepipeds  $P = P_x(hv_1, \dots, hv_k)$  with tangents:

$$\begin{aligned} d\varphi(P_x(\bar{v}_1, \dots, \bar{v}_k)) & \stackrel{\text{DEFN}}{=} \lim_{h \rightarrow 0} \frac{1}{h^k} \int_{\partial P_x(h\bar{v}_1, \dots, h\bar{v}_k)} \varphi = \lim_{h \rightarrow 0} \frac{1}{h^k} \int_{\partial P} \varphi \\ & \parallel \\ & \frac{1}{h^k} d\varphi(P_x(h\bar{v}_1, \dots, h\bar{v}_k)) \\ & \parallel \\ & \frac{1}{h^k} d\varphi(P) \end{aligned}$$

i.e.  $d\varphi(P) \approx \int_{\partial P} \varphi$

Now if we compute  $\int_X d\varphi$  via a parametrization  $V_{\text{open}} \xrightarrow{\delta} X$



(123)

$$\int_X d\varphi := \int_V d\varphi(P_{\mathcal{F}(E)}(D\mathcal{F}(E)(\vec{e}_1), \dots, D\mathcal{F}(E)(\vec{e}_k))) |d^k E|$$

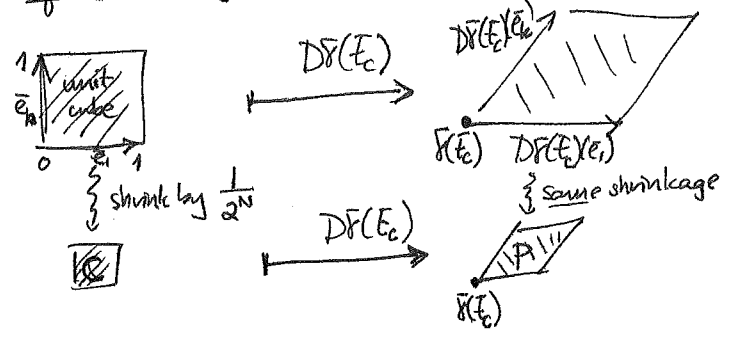
$D\mathcal{F}(E)$  as a matrix of column vectors

$$= \lim_{N \rightarrow \infty} \sum_{\substack{C \in \mathcal{D}_N(\mathbb{R}^k) \\ \text{CCV}}} d\varphi(P_{\mathcal{F}(E_c)}(D\mathcal{F}(E_c))) \text{vol}_k(C)$$

use Riemann sums with  $E_c$  as sample point in  $C$



this equals  $d\varphi(P)$  where  $P := D\mathcal{F}(E_c)(C)$ :



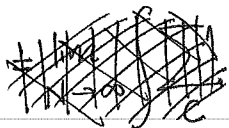
$$= \lim_{N \rightarrow \infty} \sum_C d\varphi(P)$$

Boxed fact from before

$$\approx \lim_{N \rightarrow \infty} \sum_C \int_{\partial P} \varphi$$

$P'$  is close to  $P$  for  $C$  small

$$\approx \lim_{N \rightarrow \infty} \sum_C \int_{\partial P'} \varphi$$



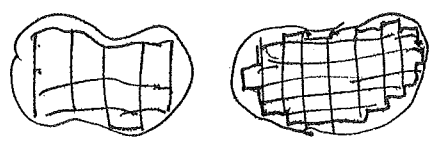
$$= \int_{\partial(\cup_C P')} \varphi$$

$$\approx \int_{\partial X} \varphi$$

"QED"

Because outward normals for adjacent  $P'$  are opposite, so interior faces of  $P'$  cancel!

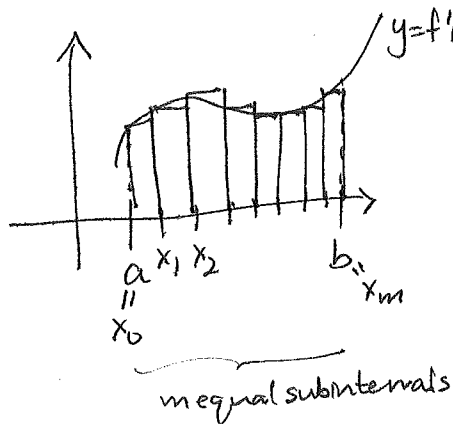
the boundary of  $\cup P'$  approximates  $\partial X$  better and better in the limit



(124) what is slippery here is that the approximations " $\approx$ " have ~~small~~ small errors, and the errors have to be summed over sums that have more and more terms, so one might worry that they don't stay arbitrarily small!

5/1/2017 REASSURANCE 1:

The book sketches its 2<sup>nd</sup> proof of Fund'l Thm. of Calculus, and bounds the errors ...



with  $f \in C^2(U)$  for some  $U \supset [a, b]$

Informally first, for  $m$  large

$$\int_a^b f'(x) dx \quad \textcircled{A} \quad \approx \sum_{i=0}^{m-1} f'(x_i)(x_{i+1} - x_i) \quad \textcircled{B_m} \quad \approx \sum_{i=0}^{m-1} (f(x_{i+1}) - f(x_i)) \quad \textcircled{C_m} = f(b) - f(a)$$

↑  
because Mean Value Thm. gives some  $c_i \in (x_i, x_{i+1})$  with  $f(x_{i+1}) - f(x_i) = f'(c_i)(x_{i+1} - x_i)$ , and  $f \in C^1 \Rightarrow f'(c_i) \approx f'(x_i)$

telescoping sum

To bound the errors, given  $\epsilon > 0$ , suffices to show  $\exists M$  such that  $\forall m \geq M$

$$|\textcircled{A} - \textcircled{B_m}| < \epsilon$$

$$\text{and } |\textcircled{B_m} - \textcircled{C_m}| < \epsilon.$$

For  $|\textcircled{A} - \textcircled{B_m}| < \epsilon$ , this is just Riemann integrability of  $f'$ , which is continuous on  $[a, b]$ , since  $f \in C^2(U)$  for  $[a, b] \subset U$ .

For  $|\textcircled{B_m} - \textcircled{C_m}| < \epsilon$ , use uniform continuity of  $f'$  on  $[a, b]$  ( $f'$  is continuous,  $[a, b]$  is compact) to choose  $M$  so  $m \geq M$  implies  $|f'(c_i) - f'(x_i)| \leq \epsilon$

$$\text{and then } |\textcircled{B_m} - \textcircled{C_m}| = \left| \sum_{i=0}^{m-1} f'(x_i)(x_{i+1} - x_i) - \sum_{i=0}^{m-1} (f(x_{i+1}) - f(x_i)) \right| = \left| \sum_{i=0}^{m-1} (f'(x_i) - f'(c_i))(x_{i+1} - x_i) \right|$$

$$= \sum_{i=0}^{m-1} |f'(x_i) - f'(c_i)| |x_{i+1} - x_i| \leq \epsilon \sum_{i=0}^{m-1} |x_{i+1} - x_i| \leq \epsilon(b-a).$$