

Chapter 1 - Flythrough

This will be a fast review/intro - You're responsible for reading Chapter 1 (and 2) and talking to me if there's something you don't follow.

(Think: big ideas/terms, like "set," not the intricacies of, say, proof of Proposition 1.30...)

★ I'll post a review of solving systems of linear eqns using subst'n, elimination or matrix multiplication.

Fundamentals / Vocabulary

\forall : for every, for all

\exists : there exists ($\exists!$: there exists a unique)

iff : iff and only if, \Leftrightarrow

We won't use sets in much depth. Mostly:

$\mathbb{R} = \text{real numbers} = \{x : x \in \mathbb{R}\}$

$\mathbb{R}^2 = \{(x, y) : x, y \in \mathbb{R}\}$

and esp. subsets of those

Recall "Abstract" Function Notation

$$f: A \rightarrow B$$

$$x \mapsto f(x)$$

$$x \rightsquigarrow f(x)$$

↑
"maps to"

A: domain

B: codomain (image, range)
target (space)

Ex $f: \mathbb{R} \rightarrow \mathbb{R}$ or $\{x \in \mathbb{R}: x \geq 0\}$

$$x \rightsquigarrow x^2$$

Def **injective** or **one-to-one** (1:1): two elts in domain sent to different outputs.

surjective or **onto**: every elt of codomain is hit.

Functions

Injective

Surjective

Not a Function

1.



2.



3.



4.



(bijection)

5.



6.



$$f(1) = (1, 1) \neq (-1, 1) = f(-1)$$

7.



8.

9.

10.



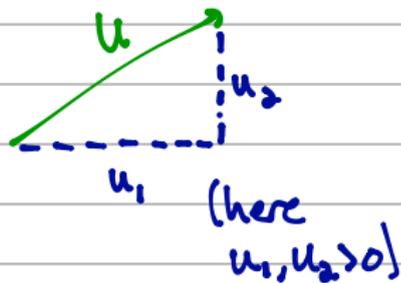
Vectors, Points and Lines

A (2D) **vector** is an ordered pair of real #'s, (a, b) .

Common notations: $\langle a, b \rangle$, $\overrightarrow{(a, b)}$

Our book: $u = (u_1, u_2)$

Graphically, u is an arrow:

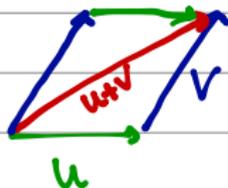


Virtually every vector concept has an **algebraic** defⁿ/
interpretation and a **geometric/axiomatic** one.

alg

geo

Addition $U+V = (u_1, u_2) + (v_1, v_2)$
 $= (u_1+v_1, u_2+v_2)$



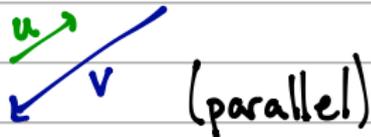
(scalar)

mult'n $cU = c(u_1, u_2)$
 $= (cu_1, cu_2)$



Subtraction $U-V = U + (-1)V$
 $= (u_1-v_1, u_2-v_2)$

linearly dependent $U=cV$ or $V=cU$
 $\exists a, b$ such that
 $aU+bV=0 (= (0,0))$
 a, b not both 0.



alg

geo

dot product:

(inner product,
scalar product)

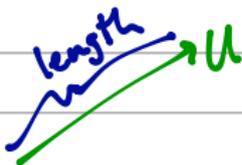
$$\begin{aligned}u \cdot v &= (u_1, u_2) \cdot (v_1, v_2) \\ &= u_1 v_1 + u_2 v_2 \\ &\neq (u_1 v_1, u_2 v_2)\end{aligned}$$

?

$$u \cdot v = \langle u, v \rangle$$

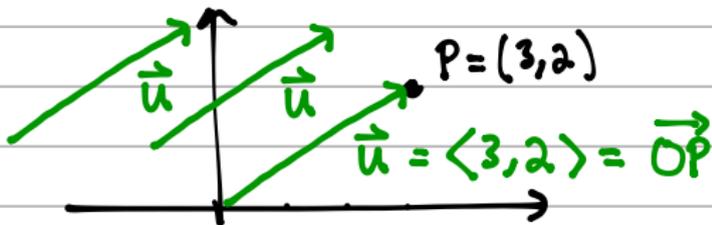
length/
magnitude

$$\begin{aligned}\|u\| &= \sqrt{u \cdot u} \\ &= \sqrt{u_1^2 + u_2^2}\end{aligned}$$



! If you learned vectors from Stewart's book...

Stewart make huge distinctions between points and vectors:



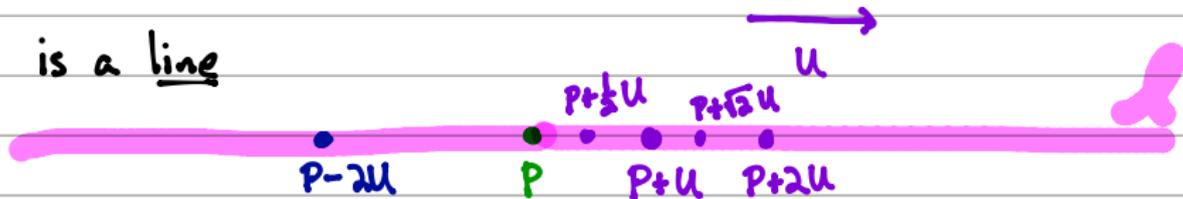
We won't. For us, vector and point are synonyms.

It's clear from context, and it makes life easier to do it this way. To wit:

Def Given a point P and non-zero vector U , the set

$$l = \{ P + sU : s \in \mathbb{R} \}$$

is a line



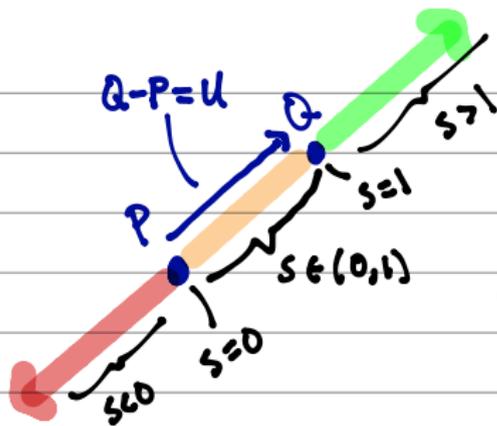
U is a direction indicator (dir vector). Points on l are "incident" with line.

P_1, P_2, \dots, P_n are collinear if \exists line incident w/ all of them.

Ex $(-1, 2) + s(3, -4)$ $(\frac{1}{2}, 0)$ is on line ($s = \frac{1}{2}$)

$(5, 6)$ is not. $\left. \begin{array}{l} -1 + 3s = 5 \\ 2 - 4s = 6 \end{array} \right\}$ no sol'n

$$P + s(Q - P)$$



$$\overline{PQ} = \overline{QP}$$

//

//

$$\{P + s(Q - P)\} \quad \{Q + s(P - Q)\}$$

$$\overleftrightarrow{PQ} = \overleftrightarrow{QP}$$

$$\overrightarrow{PQ} \neq \overrightarrow{QP}$$

$$\|X\| = \sqrt{X \cdot X}$$

length of \overline{PQ} is $\|Q - P\| = \|P - Q\|$

$$= \sqrt{\langle Q - P, Q - P \rangle}$$

$$= \sqrt{(Q - P) \cdot (Q - P)}$$

Does this defⁿ cover everything we expect?

- Can get segments, rays using restricted values of s .
- Two points form a line? Yes (wksheet)

Prop 1.4 two non-zero vectors are DI's of same line iff they're scalar mult's of each other.

Let $P \neq Q$. Then \exists unique line \overleftrightarrow{PQ} incident with both, $u = Q - P$ is a DI of \overleftrightarrow{PQ} , and every DI of \overleftrightarrow{PQ} is difference of two pts on the line.

- slope of $P + s u$ is $\frac{u_2}{u_1}$, if $u_1 \neq 0$.



other forms: eliminate parameter

$$\underline{\text{Ex}} \quad (-1, 2) + s(3, -4) = \underbrace{(-1 + 3s)}_{x(t)}, \underbrace{(2 - 4s)}_{y(t)}$$

$$x = 3s - 1 \Rightarrow s = \frac{1}{3}(x + 1)$$

$$y = -4s + 2 \Rightarrow s = -\frac{1}{4}(y - 2)$$

$$\frac{1}{3}(x + 1) = -\frac{1}{4}(y - 2)$$

$$4x + 4 = -3y + 6 \quad \text{solve for } y \dots$$

$$3y = -4x + 2$$

$$y = -\frac{4}{3}x + \frac{2}{3}$$

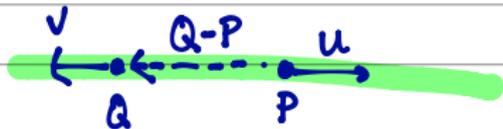
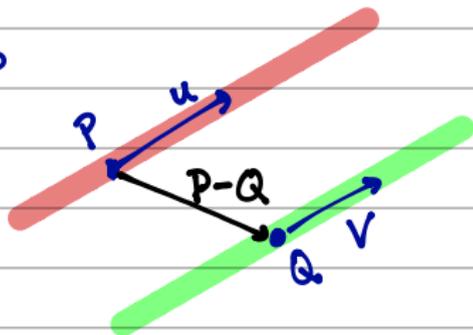
Def Two lines l, m are parallel, $l \parallel m$ if $\text{DI}'s$ are \parallel .

Prop 1.6 Lines $l = \{P + sU\}$, $m = \{Q + tV\}$

• Ω in one point if U, V lin. indep (not \parallel)

• empty Ω 'n if $U \parallel V$ and $U \not\parallel Q - P$

• are same line if $U \parallel V$
and $U \parallel Q - P$



Warmup Problem (9/13/17)

Recall: $U \cdot V = (u_1, u_2) \cdot (v_1, v_2) = u_1 v_1 + u_2 v_2$

Prove: The dot product is commutative: $U \cdot V = V \cdot U$

$$U \cdot V = u_1 v_1 + u_2 v_2 = v_1 u_1 + v_2 u_2 = V \cdot U$$

Prove: The dot product is distributive: $U \cdot (V+W) = U \cdot V + U \cdot W$

$$U \cdot (V+W) = (u_1, u_2) \cdot (v_1 + w_1, v_2 + w_2)$$

$$= u_1 (v_1 + w_1) + u_2 (v_2 + w_2)$$

$$= u_1 v_1 + u_1 w_1 + u_2 v_2 + u_2 w_2$$

$$= (u_1 v_1 + u_2 v_2) + (u_1 w_1 + u_2 w_2)$$

$$= U \cdot V + U \cdot W$$

Quick Status Check : which of Euclid's Axioms work so far?

① Given two pts, \exists line containing them ✓

② Lines can be extended indefinitely ✓

③ Given A, B , \exists circle cent'd at A with radius \overline{AB} . ✓



$$r = \|B - A\|$$

$$C = \{X : \|X - A\| = r\}$$

④ Right angles are all equal ✗

⑤ \parallel postulate (✓ HW)

Perpendicularity / Orthogonality

Def $U \perp V$ if $U \cdot V = u_1v_1 + u_2v_2 = 0$. Two lines l, m are perpendicular if they have \perp Direction Indicators.

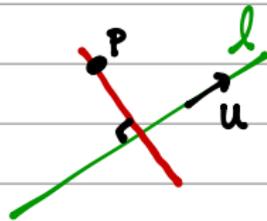
\parallel and \perp play important roles...

Corollary 1.11 If l is a line and P is a point, \exists exactly one line incident with P and \parallel to l .

Prop 1.15 If l is a line and P is a point, \exists exactly one line incident with P and \perp to l .

Prop 1.15 If l is a line and P is a point, \exists exactly one line incident with P and \perp to l .

Pf Suppose $l: Q + sU, U \neq 0$



Claim: $U = (u_1, u_2) \Rightarrow V = (-u_2, u_1) \perp U$

now show any vector $\perp U$ is

Case 1 $U = (u_1, u_2), u_1 = 0 \Rightarrow V = (-u_2, 0)$ scalar mult. of this.



$$U \cdot V = (0, u_2) \cdot (-u_2, 0) = 0 + 0 = 0 \quad \checkmark$$

Case 2 $u_2 = 0$

Case 3 in gen'l, $U \cdot V = (u_1, u_2) \cdot (-u_2, u_1) = -u_1 u_2 + u_1 u_2 = 0$

$m: P + sV$ incident w/ $P, \perp l$.

Normal Form

Given line l , choose $Y \in l$ and $A \perp l$
(i.e. $A \perp u$, u any DI of l). Then

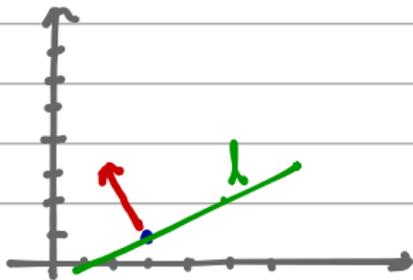
$$l = \{X : \underbrace{A \cdot (X - Y)}_{=0} = 0\}$$

nl eqn of line

Remember A, Y fixed; $X = (x_1, x_2)$ ($= (x, y)$)
is variable. If $\|A\| = 1$, this is "special" nl eqn.

Ex $Y = (3, 1)$, $A = (-1, 2)$

$$\begin{aligned}(-1, 2) \cdot (X - Y) &= (-1, 2) \cdot ((x_1, x_2) - (3, 1)) \\ &= (-1, 2) \cdot (x_1 - 3, x_2 - 1) \\ &= -x_1 + 3 + 2x_2 - 2 = 0\end{aligned}$$



$$\begin{aligned}2x_2 &= x_1 - 1 & y &= \frac{1}{2}x - \frac{1}{2} \\ x_2 &= \frac{1}{2}x_1 - \frac{1}{2}\end{aligned}$$

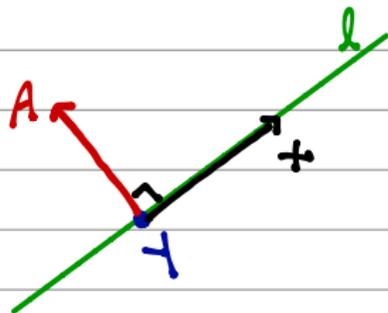
∃ alternate version of normal form:

$$A \cdot (x - y) = 0$$

$$A \cdot X - A \cdot Y = 0$$

$$A \cdot (x, y) - c = 0$$

$$A \cdot X = c \quad [A \cdot (x_1, x_2) = c]$$



Ex $A = (-1, 2), Y = (3, 1)$

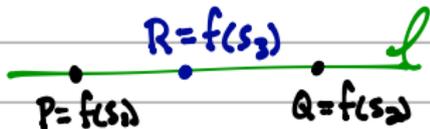
$$A \cdot (x - y) = 0$$

$$A \cdot X - \underbrace{A \cdot Y}_{=-1} = 0 \quad \Rightarrow \quad A \cdot X + 1 = 0$$

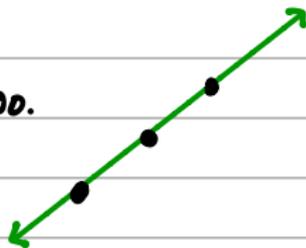
$$A \cdot X = -1$$

Betweenness

Def/Prop Let $f(s)$ be eqn of line, $f(s_1) = P$, $f(s_2) = Q$. Then R is between P, Q if $\exists s_3$, $s_1 < s_3 < s_2$, $f(s_3) = R$.

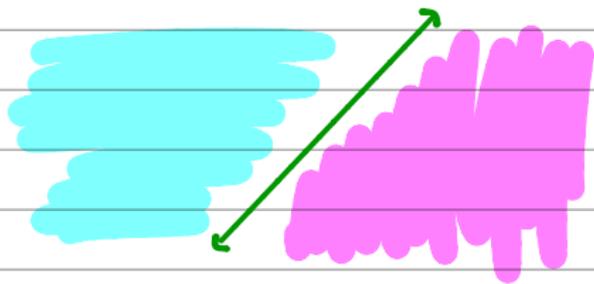


Corollary 1.22 Given 3 pts on a line,
one must be b/w other two.

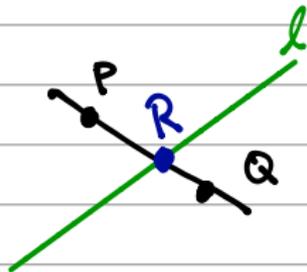
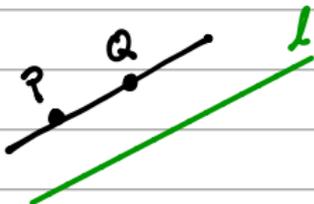
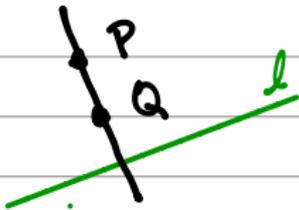


See book for further corollaries with 4+ points

A line separates \mathbb{R}^2 into two "half planes."



Clever Def $P, Q \notin l$ on opposite sides of l if $\exists R \in l$ between them. Otherwise, they're on the same side.

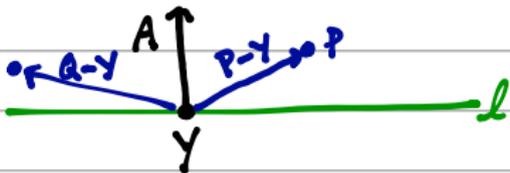


Prop 1.30 Let $l: A \cdot (x-y) = 0$ ($Y \in l, A \perp l$) and $P, Q \notin l$. Then P and Q are on same/opposite side of l if $A \cdot (P-Y), A \cdot (Q-Y)$ have same signs.

! Book uses $A \cdot X = c$, compares $A \cdot P - c, A \cdot Q - c$.

!! Would be "simple" (well, simpler) if we had

$$\vec{a} \cdot \vec{b} = \|\vec{a}\| \cdot \|\vec{b}\| \cos \theta > 0 \text{ for } \theta \in [0, \pi/2) \\ < 0 \text{ for } \theta \in (\pi/2, \pi]$$



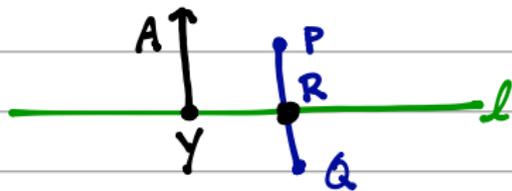
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Pf Let $g(s) = A \cdot \underbrace{[P + s(Q-P)] - Y}_{\text{line segment } \overline{PQ}}$ for $0 \leq s \leq 1$

$g(s) = 0$ for some s iff \overline{PQ} intersects l at pt R
 $(\Rightarrow P, Q$ opposite sides)

$$\text{Now } g(s) = \underbrace{A \cdot (P-Y)}_{\#} + s \underbrace{A \cdot (Q-P)}_{\#} = b + ms = ms + b$$

That's linear, so min/max values
 @ endpoints, $g(s) = 0$ only if
 $g(0), g(1)$ have diff. signs.



$$g(0) = A \cdot (P-Y), g(1) = A \cdot (Q-Y).$$

Second Warmup Question:

Prove: $(cU) \cdot V = c(U \cdot V)$

Pf: $(cU) \cdot V = (cu_1, cu_2) \cdot (v_1, v_2)$

$$= cu_1v_1 + cu_2v_2$$

$$= c(u_1v_1 + u_2v_2)$$

$$= c(U \cdot V)$$

Moving on to Chapter 2...

You read §2.1 on "Matrix Concepts. Other than matrix multiplication, all we'll need for now:

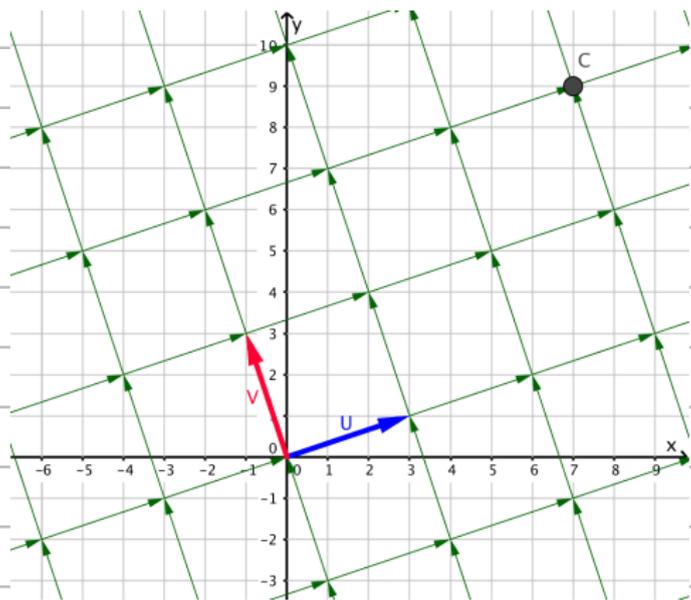
Lemma 2.1 Let $U, V \in \mathbb{R}^2$ be linearly independent. Then $\forall X \in \mathbb{R}^2, \exists$ unique $a, b \in \mathbb{R}$ such that

$$X = \underbrace{aU + bV}_{\substack{\text{linear combination} \\ \text{of } U, V.}} \quad \text{"coords } (a, b)\text{"}$$

(see lemma for formulas for a, b in particular...)

Lemma 2.4 Let $u, v \neq 0$ in \mathbb{R}^2 , with $u \perp v$. Let $x \in \mathbb{R}^2$. Then

$$x = \frac{x \cdot u}{\|u\|^2} u + \frac{x \cdot v}{\|v\|^2} v$$



Corollary 2.5 (Same conditions) $\|x\|^2 = \frac{(x \cdot u)^2}{\|u\|^2} + \frac{(x \cdot v)^2}{\|v\|^2}$

Distances and Inequalities

We defined $\|x\| = \sqrt{x \cdot x} = \langle x, x \rangle^{1/2}$

Also,

$$\|Q-P\| = \text{dist from } P \text{ to } Q = \|P-Q\| = |\overline{PQ}| = |\overline{QP}|$$

$$\forall u, \|u\| = \|-u\|$$

Def $\overline{PQ} \approx \overline{RS}$ are congruent if $|\overline{PQ}| = |\overline{RS}|$.

Def Congruence of line segments is equivalence relation.

Quick Aside: Equivalence Relations

Examples of Relations

$$\mathbb{Z}, < : 3 < 4, 5 \neq 1$$

$$\mathbb{R}, aRb \text{ if } a^2 = b^2$$

$$\mathbb{R}, = : 3 = 3, 3 \neq 4$$

A rel'n is an equivalence rel'n if it is...

① reflexive: $\forall x, xRx$

② symmetric: $\forall x, y, \text{ if } xRy \text{ then } yRx.$

③ transitive: $\forall x, y, z, \text{ if } xRy \text{ and } yRz, \text{ then } xRz$

You try: (I didn't type this up...)

Which of the following are equivalence relations?

people, "have same birthday" yes

lines, \parallel yes

integers, \leq \times not
Symm

lines, \perp \times not reflexive
or trans.

\mathbb{R} , aRb if $a^2=b^2$ yes

\mathbb{R} , \approx (?)

\hookrightarrow appx equal to.

Cauchy-Schwarz (-Bunyakovsky) Inequality (Lemma 2.11)

$$|u \cdot v| \leq \|u\| \cdot \|v\| \quad \text{with equality iff } u \parallel v.$$

① Standard Pf

② Quicker Pf using lin. alg. concepts from Chapter 2.

(These were done on board)

end day 2.

Lemma 2.12 (Δ inequality):

(done on board)

(Restated in Prop 2.13 w/ line segments)

Thm 1.55 (Pythagorean) Let $A, B, C \in \mathbb{R}^2$ be distinct points.

(done on board)

