EIGENVALUE PROBLEMS

- Background and review on eigenvalue problems
- Diagonalizable matrices
- The Schur form
- Localization of eigenvalues Gerschgorin's theorem
- Perturbation analysis, condition numbers..

Eigenvalue Problems. Introduction

Let A an $n \times n$ real nonsymmetric matrix. The eigenvalue problem:

$$Ax = \lambda x$$
 $\lambda \in \mathbb{C}$: eigenvalue $x \in \mathbb{C}^n$: eigenvector

Types of Problems:

- Compute a few λ_i 's with smallest or largest real parts;
- Compute all λ_i 's in a certain region of \mathbb{C} ;
- Compute a few of the dominant eigenvalues;
- Compute all λ_i 's.

Eigenvalue Problems. Their origins

- Structural Engineering [$Ku = \lambda Mu$]
- Stability analysis [e.g., electrical networks, mechanical system,..]
- Bifurcation analysis [e.g., in fluid flow]
- Electronic structure calculations [Schrödinger equation..]
- Applications of new era: page rank (of the world-wide web) and many types of dimension reduction (SVD instead of eigenvalues)

A complex scalar λ is called an eigenvalue of a square matrix A if there exists a nonzero vector u in \mathbb{C}^n such that $Au = \lambda u$. The vector u is called an eigenvector of A associated with λ . The set of all eigenvalues of A is the 'spectrum' of A. Notation: $\Lambda(A)$.

> λ is an eigenvalue iff the columns of $A - \lambda I$ are linearly dependent.

 \succ ... equivalent to saying that its rows are linearly dependent. So: there is a nonzero vector w such that

$$w^H(A - \lambda I) = 0$$

> w is a left eigenvector of A (u= right eigenvector)

> λ is an eigenvalue iff $det(A - \lambda I) = 0$

Basic definitions and properties (cont.)

> An eigenvalue is a root of the Characteristic polynomial:

$$p_A(\lambda) = \det(A - \lambda I)$$

> So there are n eigenvalues (counted with their multiplicities).

> The multiplicity of these eigenvalues as roots of p_A are called algebraic multiplicities.

The geometric multiplicity of an eigenvalue λ_i is the number of linearly independent eigenvectors associated with λ_i .

 \blacktriangleright Geometric multiplicity is \leq algebraic multiplicity.

- > An eigenvalue is simple if its (algebraic) multiplicity is one.
- It is semi-simple if its geometric and algebraic multiplicities are equal.

Mail Consider

 $A = egin{pmatrix} 1 & 2 & -4 \ 0 & 1 & 2 \ 0 & 0 & 2 \end{pmatrix}$

Eigenvalues of A? their algebraic multiplicities? their geometric multiplicities? Is one a semi-simple eigenvalue?

- **2** Same questions if a_{33} is replaced by one.
- Same questions if, in addition, a_{12} is replaced by zero.

 \blacktriangleright Two matrices A and B are similar if there exists a nonsingular matrix X such that

$$A = XBX^{-1}$$

 $\blacktriangleright Av = \lambda v \Longleftrightarrow B(X^{-1}v) = \lambda(X^{-1}v)$

eigenvalues remain the same, eigenvectors transformed.

 \blacktriangleright Issue: find X so that B has a simple structure

Definition: *A* is diagonalizable if it is similar to a diagonal matrix

THEOREM: A matrix is diagonalizable iff it has n linearly independent eigenvectors

> ... iff all its eigenvalues are semi-simple

 \blacktriangleright ... iff its eigenvectors form a basis of \mathbb{R}^n

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GvL 7.1-7.4,7.5.2 - EigenPart1

Transformations that preserve eigenvectors

Shift	$B = A - \sigma I$: $Av = \lambda v \iff Bv = (\lambda - \sigma)v$ eigenvalues move, eigenvectors remain the same.
Polynomial	$B=p(A)=lpha_0I+\dots+lpha_nA^n$: $Av=\lambda v \Longleftrightarrow Bv=p(\lambda)v$ eigenvalues transformed, eigenvectors remain the same.
Invert	$B = A^{-1}$: $Av = \lambda v \iff Bv = \lambda^{-1}v$ eigenvalues inverted, eigenvectors remain the same.
Shift & Invert	$B = (A - \sigma I)^{-1}$: $Av = \lambda v \iff Bv = (\lambda - \sigma)^{-1}v$ eigenvalues transformed, eigenvectors remain the same. spacing between eigenvalues can be radically changed.

THEOREM (Schur form): Any matrix is unitarily similar to a triangular matrix, i.e., for any A there exists a unitary matrix Q and an upper triangular matrix R such that

 $A = QRQ^H$

➤ Any Hermitian matrix is unitarily similar to a real diagonal matrix, (i.e. its Schur form is real diagonal).

 \blacktriangleright It is easy to read off the eigenvalues (including all the multiplicities) from the triangular matrix ${\bf R}$

Eigenvectors can be obtained by back-solving

Schur Form – Proof

A Show that there is at least one eigenvalue and eigenvector of A: $Ax = \lambda x$, with $\|x\|_2 = 1$

There is a unitary transformation P such that $Px = e_1$. How do you define P?

$$\fbox{6} \text{ Show that } \boldsymbol{P}\boldsymbol{A}\boldsymbol{P}^{H} = \left(\begin{array}{c|c} \boldsymbol{\lambda} & \ast \ast \\ \hline \boldsymbol{0} & \boldsymbol{A}_{2} \end{array} \right).$$

- Apply process recursively to A_2 .
- Mhat happens if A is Hermitian?
- Another proof altogether: use Jordan form of A and QR factorization

Localization theorems and perturbation analysis

> Localization: where are the eigenvalues located in \mathbb{C} ?

> Perturbation analysis: If A is perturbed how does an eigenvalue change? How about an eigenvector?

- > Also: sensitivity of an eigenvalue to perturbations
- Next result is a "localization" theorem
- > We have seen one such result before. Let $\|.\|$ be a matrix norm.

Then:

$$orall \, \lambda \ \in \Lambda(A) : |\lambda| \leq \|A\|$$

> All eigenvalues are located in a disk of radius ||A|| centered at 0.

More refined result: Gershgorin

THEOREM [Gershgorin]

$$orall \, \lambda \, \in \Lambda(A), \ \ \exists \ i \ \ ext{such that} \ \ |\lambda-a_{ii}| \leq \sum_{\substack{j=1\ j
eq i}}^{j=n} |a_{ij}| \ .$$

► In words: eigenvalue λ is located in one of the closed discs of the complex plane centered at a_{ii} and with radius $\rho_i = \sum_{j \neq i} |a_{ij}|$.



Proof: By contradiction. If contrary is true then there is one eigenvalue λ that does not belong to any of the disks, i.e., such that $|\lambda - a_{ii}| > \rho_i$ for all *i*. Write matrix $A - \lambda I$ as:

$$A - \lambda I = D - \lambda I - [D - A] \equiv (D - \lambda I) - F$$

where D is the diagonal of A and -F = -(D - A) is the matrix of off-diagonal entries. Now write

$$A - \lambda I = (D - \lambda I)(I - (D - \lambda I)^{-1}F).$$

From assumptions we have $||(D - \lambda I)^{-1}F||_{\infty} < 1$. (Show this). The Lemma in P. 5-3 of notes would then show that $A - \lambda I$ is nonsingular – a contradiction \Box

Gershgorin's theorem - example

Find a region of the complex plane where the eigenvalues of the following matrix are located:

$$A=egin{pmatrix} 1&-1&0&0\ 0&2&0&1\ -1&-2&-3&1\ rac{1}{2}&rac{1}{2}&0&-4 \end{pmatrix}$$

> Refinement: if disks are all disjoint then each of them contains one eigenvalue

> Refinement: can combine row and column version of the theorem (column version: apply theorem to A^H).

Bauer-Fike theorem

THEOREM [Bauer-Fike] Let $\tilde{\lambda}$, \tilde{u} be an approximate eigenpair with $\|\tilde{u}\|_2 = 1$, and let $r = A\tilde{u} - \tilde{\lambda}\tilde{u}$ ('residual vector'). Assume A is diagonalizable: $A = XDX^{-1}$, with D diagonal. Then

$$\exists \ \lambda \in \ \Lambda(A) \hspace{0.2cm}$$
 such that $\ |\lambda - ilde{\lambda}| \leq {\sf cond}_2(X) \|r\|_2$.

- Very restrictive result also not too sharp in general.
- > Alternative formulation. If *E* is a perturbation to *A* then for any eigenvalue $\tilde{\lambda}$ of A + E there is an eigenvalue λ of *A* such that:

$$|oldsymbol{\lambda}- ilde{oldsymbol{\lambda}}| \leq \mathsf{cond}_2(oldsymbol{X}) \|oldsymbol{E}\|_2 \ .$$

Conditioning of Eigenvalues

> Assume that λ is a simple eigenvalue with right and left eigenvectors u and w^H respectively. Consider the matrices:

$$A(t) = A + tE$$
 Eigenvalue $\lambda(t)$,
Eigenvector $u(t)$.

► Conditioning of λ of A relative to E is $\left|\frac{d\lambda(t)}{dt}\right|_{t=0}$.

> Write $A(t)u(t) = \lambda(t)u(t)$

Then multiply both sides to the left by w^H :

.

$$egin{aligned} &w^H(A+tE)u(t)\ &=\lambda(t)w^Hu(t)\ & o\ &\lambda(t)w^Hu(t)\ &=w^HAu(t)+tw^HEu(t)\ &=\lambda w^Hu(t)+tw^HEu(t) \end{aligned}$$

$$\rightarrow \qquad \frac{\lambda(t)-\lambda}{t}w^{H}u(t) \ = w^{H}Eu(t)$$
Take the limit at $t=0,$

$$\lambda'(0) = \frac{w^{H}Eu}{w^{H}u}$$

Note: the left and right eigenvectors associated with a simple eigenvalue cannot be orthogonal to each other.

> Actual conditioning of an eigenvalue, given a perturbation "in the direction of E" is $|\lambda'(0)|$.

> In practice only estimate of ||E|| is available, so

$$|\lambda'(0)| \leq rac{\|Eu\|_2\|w\|_2}{|(u,w)|} \leq \|E\|_2 rac{\|u\|_2\|w\|_2}{|(u,w)|}$$

GvL 7.1-7.4,7.5.2 – EigenPart1

Definition. The condition number of a simple eigenvalue λ of an arbitrary matrix A is defined by

$$\operatorname{cond}(\lambda) = rac{1}{\cos heta(u,w)}$$

in which u and w^H are the right and left eigenvectors, respectively, associated with λ .

Example: Consider the matrix

$$A=\left(egin{array}{cccc} -149 & -50 & -154 \ 537 & 180 & 546 \ -27 & -9 & -25 \end{array}
ight)$$

 $\succ \Lambda(A) = \{1, 2, 3\}$. Right and left eigenvectors associated with $\lambda_1 = 1$:

$$u = egin{pmatrix} 0.3162 \ -0.9487 \ 0.0 \end{pmatrix}$$
 and $w = egin{pmatrix} 0.6810 \ 0.2253 \ 0.6967 \end{pmatrix}$

> Perturbing a_{11} to -149.01 yields the spectrum:

 $\{0.2287, 3.2878, 2.4735\}.$

► as expected..

For Hermitian (also normal matrices) every simple eigenvalue is well-conditioned, since $cond(\lambda) = 1$.

So:

Perturbations with Multiple Eigenvalues - Example

> Consider
$$A = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

> Worst case perturbation is in 3,1 position: set $A_{31} = \epsilon$.

► Eigenvalues of perturbed *A* are the roots of $p(\mu) = (\mu - 1)^3 - 4 \cdot \epsilon.$

► Roots:
$$\mu_k = 1 + (4\epsilon)^{1/3} e^{\frac{2ki\pi}{3}}, \quad k = 1, 2, 3$$

> Hence eigenvalues of perturbed A are $1 + O(\sqrt[3]{\epsilon})$.

► If index of eigenvalue (dimension of largest Jordan block) is k, then an $O(\epsilon)$ perturbation to A leads to $O(\sqrt[k]{\epsilon})$ change in eigenvalue. Simple eigenvalue case corresponds to k = 1.