

SYMMETRIC POSITIVE DEFINITE (SPD) MATRICES

SPD LINEAR SYSTEMS

- Symmetric positive definite matrices.
- The LDL^T decomposition; The Cholesky factorization

A few properties of SPD matrices

- Diagonal entries of A are positive
- Recall: the k -th principal submatrix A_k is the $k \times k$ submatrix of A with entries a_{ij} , $1 \leq i, j \leq k$ (Matlab: $A(1:k, 1:k)$).
- 1 Each A_k is SPD
- 2 Consequence: $\text{Det}(A_k) > 0$ for $k = 1, \dots, n$. In fact A is SPD iff this condition holds.
- 3 If A is SPD then for any $n \times k$ matrix X of rank k , the matrix $X^T A X$ is SPD.

Positive-Definite Matrices

- A real matrix is said to be positive definite if

$$(Au, u) > 0 \text{ for all } u \neq 0, u \in \mathbb{R}^n$$

- Let A be a real positive definite matrix. Then there is a scalar $\alpha > 0$ such that

$$(Au, u) \geq \alpha \|u\|_2^2.$$

- Consider now the case of Symmetric Positive Definite (SPD) matrices.
- Consequence 1: A is nonsingular
- Consequence 2: the eigenvalues of A are (real) positive

- The mapping : $x, y \rightarrow (x, y)_A \equiv (Ax, y)$

defines a proper inner product on \mathbb{R}^n . The associated norm, denoted by $\|\cdot\|_A$, is called the **energy norm**, or simply the **A-norm**:

$$\|x\|_A = (Ax, x)^{1/2} = \sqrt{x^T A x}$$

- Related measure in Machine Learning, Vision, Statistics: the **Mahalanobis distance** between two vectors:

$$d_A(x, y) = \|x - y\|_A = \sqrt{(x - y)^T A (x - y)}$$

Appropriate distance (measured in # standard deviations) if x is a sample generated by a Gaussian distribution with covariance matrix A and center y .

More terminology

- A matrix is **Positive Semi-Definite** if: $(Au, u) \geq 0$ for all $u \in \mathbb{R}^n$
- Eigenvalues of symmetric positive semi-definite matrices are real nonnegative, i.e., ...
- ... A can be singular [If not, A is SPD]
- A matrix is said to be **Negative Definite** if $-A$ is positive definite. Similar definition for Negative Semi-Definite
- A matrix that is neither positive semi-definite nor negative semi-definite is **indefinite**

☞4 Show that if $A^T = A$ and $(Ax, x) = 0 \forall x$ then $A = 0$

☞5 Show: $A \neq 0$ is indefinite iff $\exists x, y : (Ax, x)(Ay, y) < 0$

6-5 GvL 4 – SPD

- Alternative proof: exploit uniqueness of LU factorization without pivoting + symmetry: $A = LDM^T = MDL^T \rightarrow M = L$
- The diagonal entries of D are positive [Proof: consider $L^{-1}AL^{-T} = D$]. In the end:

$$A = LDL^T = GG^T \text{ where } G = LD^{1/2}$$

- Cholesky factorization is a specialization of the LU factorization for the SPD case. Several variants exist.

6-7 GvL 4 – SPD

The LDL^T and Cholesky factorizations

☞6 The (standard) LU factorization of an SPD matrix A exists

- Let $A = LU$ and $D = \text{diag}(U)$ and set $M \equiv (D^{-1}U)^T$.

Then

$$A = LU = LD(D^{-1}U) = LDM^T$$

- Both L and M are unit lower triangular
- Consider $L^{-1}AL^{-T} = DM^TL^{-T}$
- Matrix on the right is upper triangular. But it is also symmetric. Therefore $M^TL^{-T} = I$ and so $M = L$

6-6 GvL 4 – SPD

First algorithm: row-oriented LDLT

Adapted from Gaussian Elimination. **Main observation:** The working matrix $A(k+1 : n, k+1 : n)$ in standard LU remains symmetric.
→ Work only on its upper triangular part & ignore lower part

```

1. For  $k = 1 : n - 1$  Do:
2.   For  $i = k + 1 : n$  Do:
3.      $piv := a(k, i) / a(k, k)$ 
4.      $a(i, i : n) := a(i, i : n) - piv * a(k, i : n)$ 
5.   End
6. End
    
```

- This will give the U matrix of the LU factorization. Therefore $D = \text{diag}(U)$, $L^T = D^{-1}U$.

6-8 GvL 4 – SPD

Row-Cholesky (outer product form)

Scale the rows as the algorithm proceeds. Line 4 becomes

$$a(i, :) := a(i, :) - [a(k, i) / \sqrt{a(k, k)}] * [a(k, :) / \sqrt{a(k, k)}]$$

ALGORITHM : 1 ■ Outer product Cholesky

1. For $k = 1 : n$ Do:
2. $A(k, k : n) = A(k, k : n) / \sqrt{A(k, k)}$;
3. For $i := k + 1 : n$ Do :
4. $A(i, i : n) = A(i, i : n) - A(k, i) * A(k, i : n)$;
5. End
6. End

➤ Result: Upper triangular matrix U such $A = U^T U$.

6-9 GvL 4 – SPD

Column Cholesky. Let $A = GG^T$ with G = lower triangular. Then equate j -th columns:

$$a(:, j) = \sum_{k=1}^j g(:, k) g^T(k, j) \rightarrow$$

$$\begin{aligned} A(:, j) &= \sum_{k=1}^j G(j, k) G(:, k) \\ &= G(j, j) G(:, j) + \sum_{k=1}^{j-1} G(j, k) G(:, k) \rightarrow \\ G(j, j) G(:, j) &= A(:, j) - \sum_{k=1}^{j-1} G(j, k) G(:, k) \end{aligned}$$

6-11 GvL 4 – SPD

Example:

$$A = \begin{pmatrix} 1 & -1 & 2 \\ -1 & 5 & 0 \\ 2 & 0 & 9 \end{pmatrix}$$

- Ex7 Is A symmetric positive definite?
- Ex8 What is the LDL^T factorization of A ?
- Ex9 What is the Cholesky factorization of A ?

6-10 GvL 4 – SPD

- Assume that first $j - 1$ columns of G already known.
- Compute unscaled column-vector:

$$v = A(:, j) - \sum_{k=1}^{j-1} G(j, k) G(:, k)$$

- Notice that $v(j) \equiv G(j, j)^2$.
- Compute $\sqrt{v(j)}$ and scale v to get j -th column of G .

6-12 GvL 4 – SPD

ALGORITHM : 2. *Column Cholesky*

```
1. For  $j = 1 : n$  do
2.   For  $k = 1 : j - 1$  do
3.      $A(j : n, j) = A(j : n, j) - A(j, k) * A(j : n, k)$ 
4.   EndDo
5.   If  $A(j, j) \leq 0$  ExitError("Matrix not SPD")
6.    $A(j, j) = \sqrt{A(j, j)}$ 
7.    $A(j + 1 : n, j) = A(j + 1 : n, j) / A(j, j)$ 
8. EndDo
```

 10 Try algorithm on:

$$A = \begin{pmatrix} 1 & -1 & 2 \\ -1 & 5 & 0 \\ 2 & 0 & 9 \end{pmatrix}$$