



 1 What is the inverse of a unitary (complex) or orthogonal (real) matrix?


**Solution:** If  $Q$  is unitary then  $Q^{-1} = Q^H$ . ☐

 2 What can you say about the diagonal entries of a skew-symmetric (real) matrix?


**Solution:** They must be equal to zero. ☐

 3 What can you say about the diagonal entries of a Hermitian (complex) matrix?

**Solution:** We must have  $a_{ii} = \bar{a}_{ii}$ . Therefore  $a_{ii}$  must be real. ☐

 4 What can you say about the diagonal entries of a skew-Hermitian (complex) matrix?

**Solution:** We must have  $a_{ii} = -\bar{a}_{ii}$ . Therefore  $a_{ii}$  must be purely imaginary. ☐

 5 Which matrices of the following type are also normal: real symmetric, real skew-symmetric, Hermitian, skew-Hermitian, com-

plex symmetric, complex skew-symmetric matrices.

**Solution:** Real symmetric, real skew-symmetric, Hermitian, skew-Hermitian matrices are normal. Complex symmetric, complex skew-symmetric matrices are not necessarily normal.  $\square$

 6 Find all real  $2 \times 2$  matrices that are normal.

**Solution:** [result only] You will find that all such matrices are of the form  $I + \alpha B$  where  $\alpha$  is a real scalar and  $B$  is either Symmetric or skew-symmetric.  $\square$

 7 Show that a triangular matrix that is normal is diagonal.

**Solution:** To simplify notation, we consider only the case of real matrices. We will use an induction argument on  $n$  this size of the matrix. The case  $n = 1$  is trivial. Assume that the result is true for matrices of size  $n - 1$  and let  $R$  be an upper triang. matrix of size  $n$  that is normal.

Since  $R$  is normal we have  $R^T R = R R^T$ . Let  $C$  be this product and consider the term  $c_{11}$ . Because  $R^T R = R R^T$  we have on the one hand:

$$c_{11} = r_{11}^2$$

and on the other:

$$c_{11} = r_{11}^2 + r_{12}^2 + r_{13}^2 + \cdots + r_{1n}^2$$

By equating the two quantities we obtain:

$$r_{12}^2 + r_{13}^2 + \cdots + r_{1n}^2 = 0,$$

which implies that  $r_{1j} = 0$  for  $j > 1$ , i.e., the entries of the first row of  $\mathbf{R}$  - not including the diagonal - are all zero. The remaining matrix, namely  $\mathbf{R}_1 = \mathbf{R}(2 : n, 2 : n)$  in matlab notation is a matrix of size  $n - 1$  and it can be seen that it satisfies the relation  $\mathbf{R}_1^T \mathbf{R}_1 = \mathbf{R}_1 \mathbf{R}_1^T$  - because of the fact that  $r_{1j} = 0$  for  $j > 1$ . Now our induction hypothesis will help us complete the proof since it implies that  $\mathbf{R}_1$  is diagonal.  $\square$

 9 What does the matrix-vector product  $\mathbf{V}\mathbf{a}$  represent?

**Solution:** If  $\mathbf{a} = [a_0, a_1, \cdots, a_n]$  and  $p(t)$  is the  $n$ -th degree polynomial:


$$p(t) = a_0 + a_1 t + a_2 t^2 + \cdots + a_n t^n$$

then  $\mathbf{V}\mathbf{a}$  is a vector whose components are the values  $p(x_0), p(x_1), \cdots, p(x_n)$ .  $\square$


 10 Interpret the solution of the linear system  $\mathbf{V}\mathbf{a} = \mathbf{y}$  where  $\mathbf{a}$  is

the unknown. Sketch a ‘fast’ solution method based on this.

**Solution:** Given the previous exercise, the interpretation is that we are seeking a polynomial of degree  $n$  whose values at  $x_0, \dots, x_n$  are the components of the vector  $y$ , i.e.,  $y_0, y_1, \dots, y_n$ . This is known as polynomial interpolation (see csci 5302). The polynomial can be determined by, e.g., the Newton table in  $O(n^2)$  operations.  $\square$

 14 If  $C$  is circulant (real) and symmetric, what can be said about the  $c_i$ s?

**Solution:** By comparing the first row and 1st column of  $C$ , one can see that when  $C$  is symmetric then the 1st row starting in position 2, i.e., the row  $c(2 : n) = [c_2, \dots, c_n]$  must be ‘symmetric’ in that  $c_2 = c_n; c_3 = c_{n-1}; \dots c_j = c_{n-j+2}; \dots \square$

 15 What is the result of multiplying  $S_n$  by a vector? What are the powers of  $S_n$ ? What is the inverse of  $S_n$ ?

**Solution:** We consider the case  $n = 5$  (no loss of generality). The vector  $S_5 v$  results from  $v$  by shifting  $v$  cyclically upward. For the same reason,  $S_5^k$  shifts the columns of  $S_k$  upward cyclically  $k$  times. The inverse of  $S_5$  corresponds to the inverse operation from ‘shifting up’, which is shifting down. The corresponding matrix, which is the

inverse of  $S_5$ , is the transpose of  $S_5$ .


 16 Show that

$$C = c_1 I + c_2 S_n + c_3 S_n^2 + \cdots + c_n S_n^{n-1}$$

As a result show that all circulant matrices of the same size commute.

**Solution:** The first term is indeed the diagonal of  $C$ . The second term is the diagonal matrix  $c_2 I$  with entries shifted up (cyclically) by one position. The 3rd term is the diagonal matrix  $c_3 I$  with entries shifted up (cyclically) by two positions, etc. This is indeed what is observed in  $C$ .

The product of two circulant matrices is a product like  $p(S_n)q(S_n)$  where  $p, q$  are 2 polynomials of degree  $n - 1$ . It is easy to see that for any matrix  $A$ , the products  $p(A)q(A)$  and  $q(A)p(A)$  are the same, which shows the result.  $\square$

 17 (Continuation) Use the result of the previous exercise to show that the product of two circulant matrices is circulant.

**Solution:** This is because  $p(S_n)q(S_n)$  can be expressed as a polynomial of degree  $n - 1$  of  $S_n$ . Indeed note that  $S_n^n = I$  so all powers in the product can be reduced to a power  $< n$ .  $\square$