### An introduction to the Posix Thread API

- General introduction
- Creation and termination
- Mutex locks
- An example: parallel sum or inner product

 $\overline{Threa} \underline{ds}$ 

- Mode of programming for shared memory [shared address space or symmetric multi-processing (SMP)
- ➤ Very common supported by all vendors. Part of unix standard.
- ➤ Low-level
- Helps understand issues with racing, synchronization, etc.
- $\triangleright$  Here: we will provide basic overview + cover an example.

*Pros:* simple approach –

Cons: Limited to SMPs . Gets complicated for longer codes

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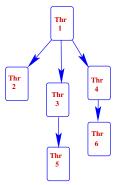
# The basic commands

See https://computing.llnl.gov/tutorials/pthreads/

among many resources for details.

"a thread is defined as an independent stream of instructions that can be scheduled to run as such by the operating system." (source: above)

- ➤ Initially, main() comprises a single thread
- Programmer can instruct the program to start threads that execute independently.
- \*However\*: you are responsible for coordinating the concurrent accesses/ modifications of memory variables by different threads
- ➤ Once initiated a thread can itself create other threads



Thread creation

pthread\_create (thread,attr,thread\_fun,arg)

thread is of type  $pthread_t = (unique)$  idenfifier of thread

attr is of type  $pthread_attr_t = may$  be used to set thread attributes.

thread\_fun is a function pointer. The thread will execute this function after creation.

arg is of type \*void. This argument is passed to the function *thread\_fun*. If more than one argument use a struct

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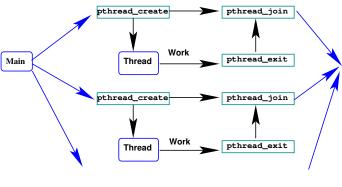
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pthread\_join : blocks calling thread until specified thread ends.
Allows to synchronize

pthread\_join (threadid, status)

threadid is of type pthread\_t = idenfifier of thread
status is of type void\*\*.



pthread\_attr\_init(&attr); // initialize
pthread\_attr\_setdetachstate(&attr,
 PTHREAD\_CREATE\_JOINABLE); //set
....
/\* at end \*/

pthread\_attr\_destroy(&attr); // Free attr

// declare

Use the attribute for declaring thread as joinable

pthread\_attr\_t attr;

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# A common mistake

Function to be called by each thread. It will print a message that contains the thread Id.

```
int main(int argc, char *argv[]){
  /* Adapted from llnl online tutorial. A basic
  "hello world" Pthreads program showing thread
  creation + termination ----*/
 #include <pthread.h>
 #include <stdio.h>
 #include <stdlib.h>
 #define NUM THREADS 8
  pthread_t thrdNUM_THREADS];
  int rc, t;
  for (t=0; t < NUM_THREADS; t++) {</pre>
    rc=pthread_create(&thrdt,NULL,P_hello,&t);
    if (rc){
      printf("ERROR: return code: %d\n",rc);
      exit(-1);
  pthread_exit(NULL);
```

 $\triangleright$  Pay attention to argument passed to  $P_{-}hello$  – last arg. of  $pthread\_create$ 

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### Discussion

- Try again several times. Can you explain what happens?

Also: run the driver without the last pthread\_exit. Can you explain?

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A thread can finish on its own if parent thread (e.g., main) does not need it to join at completion.

➤ In this case: declare as 'detached'

#### Other functions:

pthread\_attr\_getdetachstate (attr,detachstate)
pthread\_attr\_setdetachstate (attr,detachstate)

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# Shared variables and mutual exclusion: Mutexes

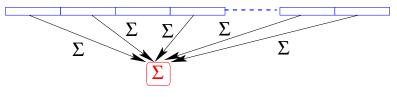
- Accessing shared variables requires careful control if data is altered by a thread: If several threads modify a shared variable, we need to make sure only one thread accesses it at a time
- Mechanism: Mutual Exclusion or Mutex.

```
// Declare as
pthread_mutex_t mutex1;
// then set as
pthread_mutex_init(mutex1, attr);
// or with static initialization
pthread_mutex_t mutex1 = PTHREAD_MUTEX_INITIALIZER;

//lock this critical section:
pthread_mutex_lock (mutex1);
// do the work needed in this section
// Nobody else can modify variables in this section
// then unlock
pthread_mutex_unlock (mutex1)
// at completion free:
pthread_mutex_destroy (mutex1)
```

# Example: parallel sum of n numbers

- ➤ We want to sum the *n* numbers of an array a [0:n-1] by dividing the sums into *p* subsums which are added in a common location in memory. Shared variable SUM will contain the final sum.
- . . . Each thread computes its subsum
- . . . locks the code section that updates SUM
- . . . adds subsum to SUM
- . . . Unlocks critical section
- . . . and exit thread.



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```
! Main program generates data (a vector) of length n -- then
! generates threads that call the sum_mtx function to
! compute partial sums and sum them. Upon completion the
! result is printed. Main thread will wait for all threads
! to complete. This code also illustrates thread
! *attributes*. It sets the threads to be *joinable*
! (allows the main thread to join with the threads it
! creates). -----*/
              /*----
              * illustrates the use of mutex variables
              * in a threads program to sum n numbers
              #include <pthread.h>
              #include <stdio.h>
              #include <stdlib.h>
              /*-----Data is passed to
 Declarations
              threads through the following struct */
              typedef struct {
               double *a;
               double sum;
               int loclen:
               int totlen;
             s } sumstr, *SumPtr;
             sumstr SUMST:
```

int main (int argc, char \*argv[]){
 int i, n = VECLEN;
 int \*thrNum, \*status;
 double \*a;
}

```
pthread_attr_t attr;
        *----- alloc storage + initialize values */
        a = (double*) malloc (NUMTHRDS*VECLEN*sizeof(double));
        thrNum = (int*) malloc (NUMTHRDS*sizeof(int));
         for (i=0; i<n; i++) a[i]=(double)i;</pre>
        *----- have thread number in array */
        for (i=0; i<NUMTHRDS; i++)</pre>
          thrNum[i] = i;
         SUMST.totlen = n;
         SUMST.loclen = 1+(int) ((n-1)/NUMTHRDS);
        SUMST.a = a;
         SUMST.sum=0;
        *----- initialize mutex */
        pthread_mutex_init(&mutexsum, NULL);
        pthread_attr_init(&attr);
Main
        pthread_attr_setdetachstate(&attr, PTHREAD_CREATE_JOINABLE);
         for(i=0;i<NUMTHRDS;i++) {</pre>
        *----- Each thread works on a different subset */
        pthread_create(&callThd[i],&attr,sum_mtx,(void *)&thrNum[i]);
        pthread_attr_destroy(&attr);
        *---- Join to wait for the other threads */
        for(i=0:i<NUMTHRDS:i++) {</pre>
        status = &thrNum[i];
        printf(" join number %d -- status %d \n",i,*status);
}
          pthread_join( callThd[i], (void **)status);
       /*---- Now print out the sum and cleanup */
        printf ("Total Sum in main thread = %10.2f \n", SUMST.sum);
        free (a); free (thrNum);
        pthread_mutex_destroy(&mutexsum);
        pthread_exit(NULL);
```

#define NUMTHRDS 8 #define VECLEN 78 pthread\_t callThd[NUMTHRDS]; pthread\_mutex\_t mutexsum; /\*----- function sum -- activated when thread is created. \*/ void \*sum\_mtx(void \*arg){ /\*----local variables \*/ int i, start, end, \*blkNum, len ; double mysum, \*x; blkNum = (int\*)arg; len = SUMST.loclen; start = (\*blkNum)\*len; /\* end = start+len > SUMST.totlen ? SUMST.totlen : start+len:\*/ end = (\*blkNum) < NUMTHRDS? start+len:SUMST.totlen:</pre> x = SUMST.a; /\*---- sum \*/ mvsum = 0: for (i=start; i<end; i++)</pre> mvsum += x[i];21 /\*----- Lock a mutex before updating the value in the shared struct \*/ pthread\_mutex\_lock (&mutexsum); SUMST.sum += mysum; /\*---- unlock it now that update is pthread\_mutex\_unlock (&mutexsum); printf(" -- Local sum in thread %d is %10.2f total : %10.2f\n ", \*blkNum, mysum, SUMST.sum); printf(" len %d %d %d %5.2f \n",len,start,end,x [start]); \*----- done with this thread \*/ pthread\_exit((void\*) 0);

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Function

sum\_dat