CONVERGENCE THEORY

- Background: Best uniform approximation;
- Chebyshev polynomials;
- Analysis of the CG algorithm;
- Analysis in the non-Hermitian case (short)

Background: Best uniform approximation

We seek a function ϕ (e.g. polynomial) which deviates as little as possible from f in the sense of the $\|\cdot\|_{\infty}$ -norm, i.e., we seek the

$$\min_{\phi} \; \max_{t \; \in \; [a,b]} \; \left| f(t) - \phi(t)
ight| \; = \min_{\phi} \| f - \phi \|_\infty$$

where ϕ is in a finite dimensional space (e.g., space of polynomials of degree $\leq n$)

> Solution is the "best uniform approximation to f"

- \blacktriangleright Important case: ϕ is a polynomial of degree $\leq n$
- \blacktriangleright In this case ϕ belongs to \mathbb{P}_n

$$ho_n(f) = \min_{p \in \mathbb{P}_n} \; \max_{x \in [a,b]} \; \left| f(t) - p(t)
ight|$$

 \blacktriangleright If f is continuous, best approximation to f on [a,b] by polynomials of degree $\leq n$ exists and is unique

> ... and $\lim_{n\to\infty} \rho_n(f) = 0$ (Weierstrass theorem).

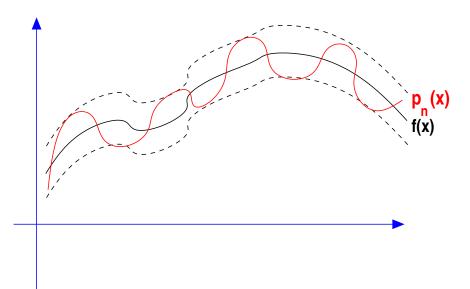
Question: How to find the best polynomial?

Answer: Chebyshev's equi-oscillation theorem.

 $\frac{\text{Chebyshev equi-oscillation theorem: } p_n \text{ is the best uniform approximation to } f \text{ in } [a,b] \text{ if and only if there are } n+2 \\ \text{points } t_0 < t_1 < \ldots < t_{n+1} \text{ in } [a,b] \text{ such that}}$

$$\|f(t_j)-p_n(t_j)=c(-1)^j\|f-p_n\|_\infty$$
 with $c=\pm 1$

 $\left[p_{n} ext{ 'equi-oscillates' } n+2 ext{ times around } f ext{ }
ight]$



Application: Chebyshev polynomials

Question: Among all monic polynomials of degree n + 1 which one minimizes the infinity norm? Problem:

Minimize
$$||t^{n+1} - a_n t^n - a_{n-1} t^{n-1} - \cdots - a_0||_{\infty}$$

Reformulation: Find the best uniform approximation to t^{n+1} by polynomials p of degree $\leq n$.

> $t^{n+1} - p(t)$ should be a polynomial of degree n + 1 which equi-oscillates n + 2 times.

Define Chebyshev polynomials:

$$C_k(t)=\cos(k\cos^{-1}t)$$
 for $k=0,1,...$, and $t~\in~[-1,1]$

- > Observation: C_k is a polynomial of degree k, because:
- \succ the C_k 's satisfy the three-term recurrence :

$$C_{k+1}(t) = 2xC_k(t) - C_{k-1}(t)$$

with
$$C_0(t)=1$$
, $C_1(t)=t$.



 $\fbox{2}$ Compute C_2, C_3, \ldots, C_8

🏂 Show that for
$$|t|>1$$
 we have

$$C_k(t) = \operatorname{ch}(k \operatorname{ch}^{-1}(t))$$

\succ C_k Equi-Oscillates k+1 times around zero.

Normalize C_{n+1} so that leading coefficient is 1

The minimum of $\|t^{n+1}-p(t)\|_\infty$ over $p\in \mathbb{P}_n$ is achieved when $t^{n+1}-p(t)=rac{1}{2^n}C_{n+1}(t).$

Another important result:

Let $[\alpha, \beta]$ be a non-empty interval in \mathbb{R} and let γ be any real scalar outside the interval $[\alpha, \beta]$. Then the minimum

 $\min_{p\in \mathbb{P}_k, p(\gamma)=1} \; \max_{t\in [lpha,eta]} |p(t)|$

is reached by the polynomial: $\hat{C}_k(t) \equiv rac{C_k\left(1+2rac{lpha-t}{eta-lpha}
ight)}{C_k\left(1+2rac{lpha-\gamma}{eta-lpha}
ight)}.$

Convergence Theory for CG

> Approximation of the form $x = x_0 + p_{m-1}(A)r_0$. with $x_0 =$ initial guess, $r_0 = b - Ax_0$;

> Recall property: x_m minimizes $||x - x_*||_A$ over $x_0 + K_m$

Consequence: Standard result

Let $x_m = m$ -th CG iterate, $x_* =$ exact solution and $\eta = rac{\lambda_{min}}{\lambda_{max} - \lambda_{min}}$ Then: $\|x_* - x_m\|_A \leq rac{\|x_* - x_0\|_A}{C_m(1+2\eta)}$ where $C_m =$ Chebyshev polynomial of degree m. > Alternative expression. From $C_k = ch(kch^{-1}(t))$:

$$egin{aligned} C_m(t) &= rac{1}{2} \left[\left(t + \sqrt{t^2 - 1}
ight)^m + \left(t + \sqrt{t^2 - 1}
ight)^{-m}
ight] \ &\geq rac{1}{2} \left(t + \sqrt{t^2 - 1}
ight)^m \,. & ext{Then:} \end{aligned}$$

$$egin{split} C_m(1+2\eta) &\geq rac{1}{2} \left(1+2\eta + \sqrt{(1+2\eta)^2-1}
ight)^m \ &\geq rac{1}{2} \left(1+2\eta + 2\sqrt{\eta(\eta+1)}
ight)^m. \end{split}$$

> Next notice that:

$$egin{aligned} 1+2\eta+2\sqrt{\eta(\eta+1)}&=\left(\sqrt{\eta}+\sqrt{\eta+1}
ight)^2\ &=rac{\left(\sqrt{\lambda_{min}}+\sqrt{\lambda_{max}}
ight)^2}{\lambda_{max}-\lambda_{min}} \end{aligned}$$

Text: 6.11 - theory

$$=rac{\sqrt{\lambda_{max}}+\sqrt{\lambda_{min}}}{\sqrt{\lambda_{max}}-\sqrt{\lambda_{min}}}\ =rac{\sqrt{\kappa}+1}{\sqrt{\kappa}-1}$$

where $\kappa = \kappa_2(A) = \lambda_{max}/\lambda_{min}$.

Substituting this in previous result yields

$$\|x_*-x_m\|_A\leq 2\left[rac{\sqrt{\kappa}-1}{\sqrt{\kappa}+1}
ight]^m\|x_*-x_0\|_A.$$

Compare with steepest descent!

Theory for Nonhermitian case

Much more difficult!

► No convincing results on 'global convergence' for most algorithms: FOM, GMRES(k), BiCG (to be seen) etc..

Can get a general a-priori – a-posteriori error bound

Convergence results for nonsymmetric case

Methods based on minimum residual better understood.

▶ If $(A + A^T)$ is positive definite $((Ax, x) > 0 \forall x \neq 0)$, all minimum residual-type methods (ORTHOMIN, ORTHODIR, GCR, GMRES,...), + their restarted and truncated versions, converge.

> Convergence results based on comparison with one-dim. MR [Eisenstat, Elman, Schultz 1982] \rightarrow not sharp.

MR-type methods: if $A = X\Lambda X^{-1}$, Λ diagonal, then

$$egin{aligned} \|b-Ax_m\|_2 &\leq ext{Cond}_2(X) \min_{p \in \mathcal{P}_{m-1}, p(0)=1} &\max_{\lambda \in \Lambda(A)} |p(\lambda)| \ &(\mathcal{P}_{m-1} \equiv ext{set of polynomials of degree} &\leq m-1, \ \Lambda(A) \equiv ext{spectrum of } A) \end{aligned}$$

Text: 6.11 – theory