

Logistics:

Lecture notes and minimal information will be located here:

8314 at CSE-labs

www-users.cselabs.umn.edu/classes/Spring-2021/csci8314/

- **>** There you will find :
- Lecture notes, Schedule of assignments/ tests, class info
- ► Canvas will contain the rest of the information: assignments, grades, etc.

- start8314

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About lecture notes:

Lecture notes (like this first set) will be posted on the class web-site – usually before the lecture.

- Note: format used in lectures may be formatted differently but same contents.
- > Review them to get some understanding if possible before class.
- > Read the relevant section (s) in the texts or references provided
- Lecture note sets are grouped by topics (sections in the textbook) rather than by lecture.
- ▶ In the notes the symbol <a>[indicates suggested easy exercises or questions often [not always] done in class.

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> Also: occasional practice exercises posted

Matlab

- > We will often use matlab for testing algorithms.
- Other documents will be posted in the matlab section of the class web-site.
- > Also:
- I post the matlab diaries used for the demos (if any).

CSCI 8314: SPARSE MATRIX COMPUTATIONS

GENERAL INTRODUCTION

- General introduction a little history
- Motivation
- Resources
- What will this course cover

What this course is about

- Solving linear systems and (to a lesser extent) eigenvalue problems with matrices that are sparse.
- Sparse matrices : matrices with mostly zero entries [details later]
- > Many applications of sparse matrices...
- > ... and we are seing more with new applications everywhere

A brief history

Sparse matrices have been identified as important early on – origins of terminology is quite old. Gauss defined the first method for such systems in 1823. Varga used explicitly the term 'sparse' in his 1962 book on iterative methods.

 $https://www-users.cs.umn.edu/{\sim}saad/PDF/icerm2018.pdf$

 Special techniques used for sparse problems coming from Partial Differential Equations

One has to wait until to the 1960s to see the birth of the general technology available today

 Graphs introduced as tools for sparse Gaussian elimination in 1961 [Seymour Parter]

> Early work on reordering for banded systems, envelope methods

► Various reordering techniques for general sparse matrices introduced.

- Minimal degree ordering [Markowitz 1957] ...
- > ... later used in Harwell MA28 code [Duff] released in 1977.
- > Tinney-Walker Minimal degree ordering for power systems [1967]
- ▶ Nested Dissection [A. George, 1973]
- > SPARSPAK [commercial code, Univ. Waterloo]
- > Elimination trees, symbolic factorization, ...

History: development of iterative methods

1950s up to 1970s : focus on "relaxation" methods

Development of 'modern' iterative methods took off in the mid-70s. but...

The main ingredients were in place earlier [late 40s, early 50s: Lanczos; Arnoldi ; Hestenes (a local!) and Stiefel;]

➤ The next big advance was the push of 'preconditioning': in effect a way of combining iterative and (approximate) direct methods – [Meijerink and Van der Vorst, 1977]

- Intro

– Intro

History: eigenvalue problems

- Another parallel branch was followed in sparse techniques for large eigenvalue problems.
- ➤ A big problem in 1950s and 1960s : flutter of airplane wings.. This leads to a large (sparse) eigenvalue problem
- Overlap between methods for linear systems and eigenvalue problems [Lanczos, Arnoldi]

Resources

Matrix market

http://math.nist.gov/MatrixMarket/

SuiteSparse site (Formerly : Florida collection)

https://sparse.tamu.edu/

> SPARSKIT, etc. [SPARSKIT = old written in Fortran. + more recent 'solvers']

 $http://www.cs.umn.edu/{\sim}saad/software$

Resources – continued

Books: on sparse direct methods.

- Book by Tim Davis [SIAM, 2006] see syllabus for info
- Best reference [old, out-of print, but still the best]:
- Alan George and Joseph W-H Liu, Computer Solution of Large Sparse Positive Definite Systems, Prentice-Hall, 1981. Englewood Cliffs, NJ.
- > Of interest mostly for references:
- I. S. Duff and A. M. Erisman and J. K. Reid, Direct Methods for Sparse Matrices, Clarendon press, Oxford, 1986.
- Some coverage in Golub and van Loan [John Hopinks, 4th edition, see chapters 10 to end]

Overall plan for this course

> We will begin by sparse matrices in general, their origin, storage, manipulation, etc..

Graph theory viewpoint

1-13

- > We will then spend some time on sparse direct methods
- ... back to graphs: Graph Laplaceans and applications; Networks;
- ...
- > .. and then on eigenvalue problems and
- > ... iterative methods for linear systems
- > ... Plan is somewhat dynamic
- > ... at the end of semester: a few lectures given by you

1-14

1-12

– Intro

Intro

1-15

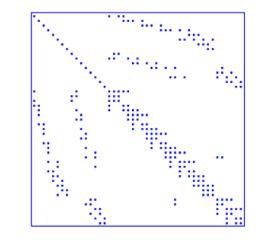
– Intro

- Intro

SPARSE MATRICES

- See Chap. 3 of text
- See the "links" page on the class web-site
- See also the various sparse matrix sites.
- Introduction to sparse matrices
- Sparse matrices in matlab -

What are sparse matrices?



Pattern of a small sparse matrix

1-17

- > Vague definition: matrix with few nonzero entries
- For all practical purposes: an $m \times n$ matrix is sparse if it has $O(\min(m, n))$ nonzero entries.
- \blacktriangleright This means roughly a constant number of nonzero entries per row and column -
- This definition excludes a large class of matrices that have $O(\log(n))$ nonzero entries per row.
- Other definitions use a slow growth of nonzero entries with respect to *n* or *m*.

"...matrices that allow special techniques to take advantage of the large number of zero elements." (J. Wilkinson)

A few applications which lead to sparse matrices:

Structural Engineering, Computational Fluid Dynamics, Reservoir simulation, Electrical Networks, optimization, Google Page rank, information retrieval (LSI), circuit similation, device simulation,

Goal of Sparse Matrix Techniques

> To perform standard matrix computations economically i.e., without storing the zeros of the matrix.

Example: To add two square dense matrices of size n requires $O(n^2)$ operations. To add two sparse matrices A and B requires O(nnz(A) + nnz(B)) where nnz(X) = number of nonzero elements of a matrix X.

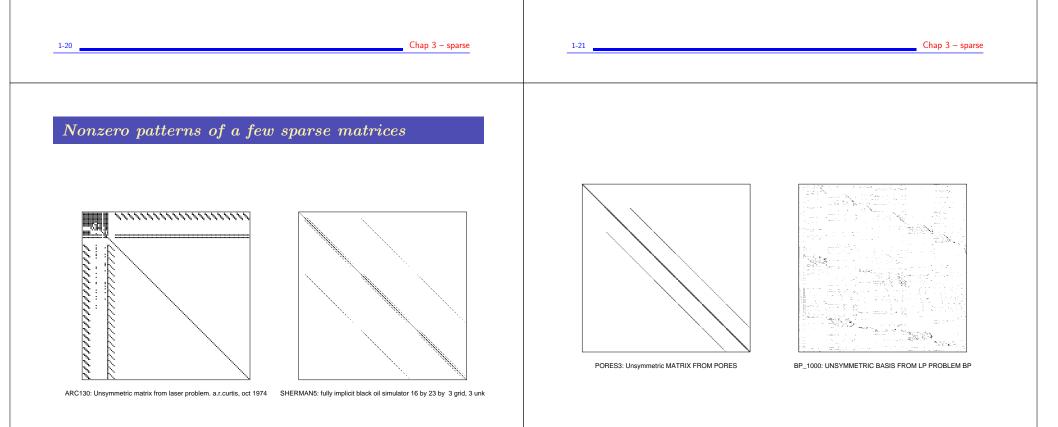
For typical Finite Element /Finite difference matrices, number of nonzero elements is O(n).

Remark: A^{-1} is usually dense, but L and U in the LU factorization may be reasonably sparse (if a good technique is used) Look up Cayley-Hamilton's theorem if you do not know about it.

Z₁₃ Show that the inverse of a matrix (when it exists) can be expressed as a polynomial of A, where the polynomial is of degree $\leq n - 1$.

Z14 When is the degree < n-1? [Hint: look-up minimal polynomial of a matrix]

✓n₅ What is the patter of the inverse of a tridiagonal matrix? a bidiagonal matrix?



1-23

Types of sparse matrices

► <u>Two types of matrices: structured (e.g. Sherman5) and un-</u> structured (e.g. BP_1000)

➤ The matrices PORES3 and SHERMAN5 are from Oil Reservoir Simulation. Often: 3 unknowns per mesh point (Oil , Water saturations, Pressure). Structured matrices.

> 40 years ago reservoir simulators used rectangular grids.

► Modern simulators: Finer, more complex physics ► harder and larger systems. Also: unstructured matrices

> A naive but representative challenge problem: $100 \times 100 \times 100$ grid + about 10 unknowns per grid point > $N \approx 10^7$, and $nnz \approx 7 \times 10^8$.

1	2

Chap 3 – sparse

Two types of methods for general systems:

Direct methods : based on sparse Gaussian eimination, sparse Cholesky,..

Iterative methods: compute a sequence of iterates which converge to the solution - preconditioned Krylov methods..

Remark: These two classes of methods have always been in competition.

- \blacktriangleright 40 years ago solving a system with n = 10,000 was a challenge
- > Now you can solve this in a fraction of a second on a laptop.

Sparse direct methods made huge gains in efficiency. As a result they are very competitive for 2-D problems.

Solving sparse linear systems: existing methods

A x = b

 $-\Delta \mathbf{u} = \mathbf{f} + \mathbf{b}\mathbf{c}$

Iterative Methods

Preconditioned Krylov

General

Purpose

Multigrid

Methods

Specialized

Direct sparse

Solvers

Fast Poisson

Solvers

> 3-D problems lead to more challenging systems [inherent to the underlying graph]

Difficulty:

- No robust 'black-box' iterative solvers.
- At issue: Robustness in conflict with efficiency.

Iterative methods are starting to use some of the tools of direct solvers to gain 'robustness'

Consensus:

1. Direct solvers are often preferred for two-dimensional problems (robust and not too expensive).

2. Direct methods loose ground to iterative techniques for threedimensional problems, and problems with a large degree of freedom per grid point,

Sparse matrices in matlab

- Matlab supports sparse matrices to some extent.
- > Can define sparse objects by conversion

```
A = sparse(X) ; X = full(A)
```

> Can show pattern

spy(X)

> Define the analogues of ones, eye:

speye(n,m), spones(pattern)

A few reorderings functions provided.. [will be studied in detail later]

symrcm, symamd, colamd, colperm

> Random sparse matrix generator:

sprand(S) or sprand(m,n, density)

```
(also textttsprandn(...) )
```

> Diagonal extractor-generator utility:

spdiags(A) , spdiags(B,d,m,n)

> Other important functions:

spalloc(..) , find(..)

Chap 3 – sparse

Chap 3 – sparse

Graph Representations of Sparse Matrices

> Graph theory is a fundamental tool in sparse matrix techniques.

DEFINITION. A graph G is defined as a pair of sets G = (V, E) with $E \subset V \times V$. So G represents a binary relation. The graph is undirected if the binary relation is reflexive. It is directed otherwise. V is the vertex set and E is the edge set.

Example: Given the numbers 5, 3, 9, 15, 16, show the two graphs representing the relations

R1: Either x < y or y divides x.

1-31

R2: \boldsymbol{x} and \boldsymbol{y} are congruent modulo 3. [mod(x,3) = mod(y,3)]

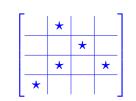
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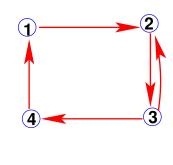
Chap 3 – sparse1

- > Adjacency Graph G = (V, E) of an $n \times n$ matrix A:
- Vertices $V = \{1, 2, ..., n\}$.
- Edges $E = \{(i, j) | a_{ij} \neq 0\}$.
- \blacktriangleright Often self-loops (i,i) are not represented [because they are always there]
- **>** Graph is undirected if the matrix has a symmetric structure:

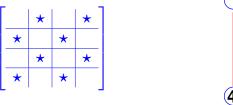
$$a_{ij} \neq 0$$
 iff $a_{ji} \neq 0$.

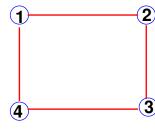
Example: (directed graph)



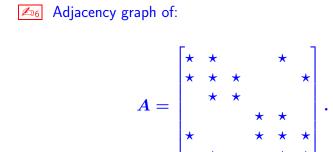


Example: (undirected graph)





Chap 3 – sparsel



⊿₁₇ Graph of a tridiagonal matrix? Of a dense matrix?

Recall what a star graph is. Show a matrix whose graph is a star graph. Consider two situations: Case when center node is labeled first and case when it is labeled last.

- > Note: Matlab now has a *graph* function.
- > G = graph(A) creates adjacency graph from A
- ► G is a matlab class/
- \succ G.Nodes will show the vertices of G
- ▶ G.Edges will show its edges.
- > plot(G) will show a representation of the graph

1-32

Do the following:

- Load the matrix 'Bmat.mat' located in the class web-site (see 'matlab' folder)
- Visualize pattern (spy(B)) + find: Number of nonzero elements, size, ...
- Generate graph without self-edges:

G = graph(B,'OmitSelfLoops'

- Plot the graph –
- \$1M question: Any idea on how this plot is generated?

1-36