

A Translation-Based Animation of Dependently-Typed Specifications  
From LF to *hohh*(and back again)

Mary Southern and Gopalan Nadathur

Department of Computer Science and Engineering  
University of Minnesota

This work was funded by NSF grant CCF-0917140.

## Some Motivation

We are interested in formalizing systems that are described in a rule-based and syntax directed fashion

Two approaches with complementary benefits exist for formalizing such systems:

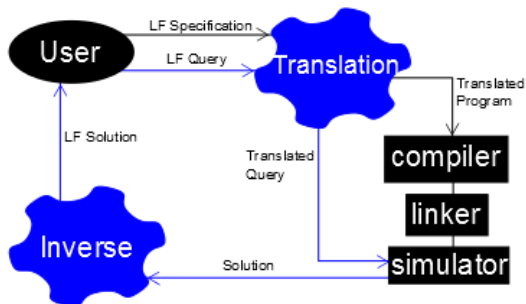
- ▶ An approach based on using **dependently-typed**  $\lambda$ -calculi  
*Primary Virtue:* Dependent types are a convenient and widely used means for encoding specifications
- ▶ An approach that uses **logical predicates** over  $\lambda$ -calculus terms  
*Primary Virtue:* Such a logic has an efficient implementation and specifications in it can also be expressively reasoned about

*Our Goal:* To harness the benefits of *both* approaches

Specifically, we want to

- ▶ let the first approach be used for developing specifications
- ▶ use a translation to the second form to realize animation

# Map of Talk



Motivation

Specifications

A Translation

An Inverse

Looking Forward

# Edinburgh Logical Framework (LF)

## Syntax of Expressions

Kind  $K := \text{Type} \mid \Pi x:A.K$

Type  $A := a \ M \dots M \mid \Pi x:A.A$

Object  $M := c \mid x \mid X \mid \lambda x:A.M \mid M \ M$

We are interested in deriving judgments of the form:

$$\Gamma \vdash_{\Sigma} M : A$$

This is done with respect to:

- ▶ Signature  $\Sigma := \cdot \mid \Sigma, c : A \mid \Sigma, a : K$
- ▶ Context  $\Gamma := \cdot \mid \Gamma, x : A$
- ▶ Meta-Variable Context  $\Delta$

## Example Specification

$\text{nat } N := 0 \mid S N$

$\text{list } L := [] \mid (N :: L)$

$$\frac{}{L_1 @ L_2 = L_3} \qquad \frac{L_1 @ L_2 = L_3}{(X :: L_1) @ L_2 = (X :: L_3)}$$

$\text{nat} : \text{type}.$

$\text{list} : \text{type}.$

$z : \text{nat}.$

$\text{nil} : \text{list}.$

$s : \text{nat} \rightarrow \text{nat}.$

$\text{cons} : \text{nat} \rightarrow \text{list} \rightarrow \text{list}.$

$\text{app} : \text{list} \rightarrow \text{list} \rightarrow \text{list} \rightarrow \text{type}.$

$\text{app}_N : \prod L:\text{list}.\text{app } \text{nil } L L.$

$\text{app}_C : \prod X:\text{nat}.\prod L_1:\text{list}.\prod L_2:\text{list}.\prod L_3:\text{list}.$

$\prod A:\text{app } L_1 L_2 L_3.\text{app } (\text{cons } X L_1) L_2 (\text{cons } X L_3)$

## A Predicate Logic

- ▶ We work with a fragment of the logic of Higher-Order Hereditary Harrop Formulas (*hohh*)
- ▶ This logic underlies the logic programming language  $\lambda$  Prolog

Atomic formulas,  $A$ , are constructed using predicate symbols that take simply typed  $\lambda$ -terms as arguments.

### Formulas

$$D := A \mid G \supset D \mid \forall x.D \quad G := \top \mid A \mid D \supset G \mid \forall x.G$$

- ▶ A collection of  $D$ -formulas, or Program  $\mathcal{P}$ , encodes a specification and a  $G$  formula corresponds to a query

# Logic Programming - Predicate Logic

We want to derive sequents of the form:  $\Xi; \mathcal{P} \longrightarrow G$   
where

- ▶  $\Xi$  is the signature containing the term constants
- ▶  $\mathcal{P}$  is a program (set of  $D$ -formulas)
- ▶  $G$  is the goal formula we wish to solve

Two main differences from Logic Programming in Prolog:

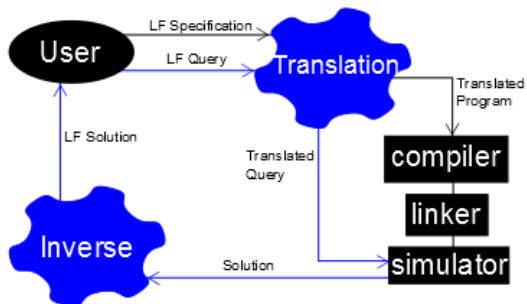
- ▶ Program can be extended dynamically

$$\frac{\Xi; \Gamma, D \longrightarrow G}{\Xi; \Gamma \longrightarrow D \supset G}$$

- ▶ Signature can be extended dynamically

$$\frac{\Xi, c; \Gamma \longrightarrow G[c/x]}{\Xi; \Gamma \longrightarrow \forall x. G}$$

# Map of Talk



Motivation

Specifications

A Translation

An Inverse

Looking Forward



# Overview of Translation

The translation is based on a two step process

1. First we map *both* LF types and objects into simply typed  $\lambda$ -terms.
  - ▶ we use *hohh* terms of type *If-type* for LF types
  - ▶ we use *hohh* terms of type *If-obj* for LF objects

Notice that the LF typing information is lost in this translation and only the functional structure of expressions is retained

2. We then encode LF typing relations in predicates over the *hohh* terms denoting LF objects and LF types  
In particular,
  - ▶ the predicate *hastype* :  $If-obj \rightarrow If-type \rightarrow o$  is used for this.

## A Translation 1/2

The encoding of LF terms,  $\langle \cdot \rangle$  is given by the rules below.

$$\begin{aligned} \langle c \rangle &:= c & \langle x \rangle &:= x & \langle X \rangle &:= X \\ \langle M N \rangle &:= \langle M \rangle \langle N \rangle & \langle \lambda x:A.M \rangle &:= \lambda x. \langle M \rangle \end{aligned}$$

The mapping,  $\phi(\cdot)$  flattens the types of LF terms:

$$\begin{aligned} \phi(\text{Type}) &:= \text{lf-type} & \phi(\Pi x:A.B) &:= \phi(A) \rightarrow \phi(B) \\ \phi(A) &:= \text{lf-obj} & \text{when } A \text{ is a base type} \end{aligned}$$

### Example Encoding

$\text{nat} : \text{lf-type}.$

$\text{list} : \text{lf-type}.$

$z : \text{lf-obj}.$

$\text{nil} : \text{lf-obj}.$

$s : \text{lf-obj} \rightarrow \text{lf-obj}.$

$\text{cons} : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj}.$

$\text{app} : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-type}.$

$\text{app}_N : \text{lf-obj} \rightarrow \text{lf-obj}.$

$\text{app}_C : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj}.$

## A Translation 2/2

Then, LF types are translated as follows:

$$\{\{A\}\} \quad := \quad \lambda M. \text{hastype } M \langle A \rangle \quad \text{if } A \text{ is a base type}$$
$$\{\{\Pi x:A.B\}\} \quad := \quad \lambda M. \forall x. (\{\{A\}\} x) \supset (\{\{B\}\} (M x))$$

For example, consider the translation of  $\Pi L:\text{list.app nil } L L$ :

$$\{\{\Pi L:\text{list.app nil } L L\}\}$$
$$\lambda M. \forall L. (\{\{\text{list}\}\} L) \supset (\{\{\text{app nil } L L\}\} (M L))$$
$$\lambda M. \forall L. (\text{hastype } L \text{ list}) \supset (\text{hastype } (M L) (\text{app nil } L L))$$

Thus, the LF signature item  $\text{app}_N : \Pi L:\text{list.app nil } L L$  yields the  $\lambda$ -Prolog formula

$$\forall L. (\text{hastype } L \text{ list} \supset \text{hastype } (\text{app}_N L) (\text{app nil } L L))$$

## Improving the Translation

Consider the constant  $app\_C$ .

$$app\_C : \Pi X:nat. \Pi L_1:list. \Pi L_2:list. \Pi L_3:list. \Pi A:app L_1 L_2 L_3. \\ app (cons X L_1) L_2 (cons X L_3)$$

Whenever we are matching an instance of this type, we must ensure that the terms being substituted for the  $\Pi$ -bound variables are of the correct type.

- ▶ Certain terms will appear in such a way that we know this to be the case.

Consider a well-formed type:  $app (cons x l1) l2 (cons x l3)$ .

- ▶ Clearly then, whatever the term  $l1$  (resp.  $l2$ ,  $l3$ ), it must be of type  $list$
- ▶ Similarly  $x$  must be of type  $nat$
- ▶ But is there a term of type  $app l1 l2 l3$ ?

# Characterizing Redundancies

This **type checking** becomes the *hastype formula* of the  $\Pi$ -bound variable.

By categorizing which of these checks is unnecessary, we are able to **reduce the number of goals** which must be satisfied during proof search.

- ▶ The essential idea is that we do not need to perform such a check when there is an occurrence whose structure is not lost or altered by other substitutions.

We define a criterion, called **Strictness**, which captures this idea.

## Strictness

1. There is an occurrence, in the head of the type, which does not disappear after performing substitutions for the other  $\Pi$ -quantified variables.
2. This occurrence may only be applied to distinct  $\lambda$ -bound variables.

# Strictness

There are two main judgments associated with strictness:

$$\Gamma; x \sqsubset_t A \quad \text{and} \quad \Delta; \delta; x \sqsubset_o M$$

- ▶  $\Gamma$  collects  $\Pi$ -bound variables
- ▶  $\Delta$  contains the  $\Pi$ -bound variables
- ▶  $\delta$  collects  $\lambda$ -bound variables

Translation now proceeds in two modes:

- ▶ In the positive context we remove the *hastype* clause for strictly occurring variables.
- ▶ In the negative context we proceed as before.

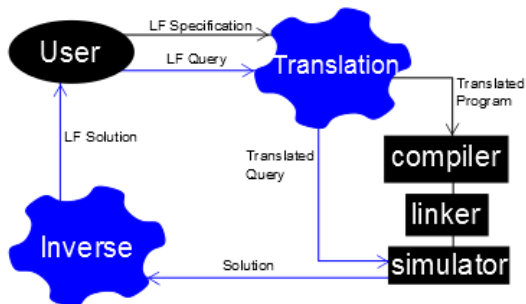
## Example Specification - Translated

$nat : \text{lf-type.}$                      $list : \text{lf-type.}$   
 $z : \text{lf-obj.}$                          $nil : \text{lf-obj.}$   
 $s : \text{lf-obj} \rightarrow \text{lf-obj.}$          $cons : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj.}$

$app : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-type.}$   
 $app\_N : \text{lf-obj} \rightarrow \text{lf-obj.}$   
 $app\_C : \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj} \rightarrow \text{lf-obj.}$

$\forall L. \text{hastype} (app\_N L) (app\ nil\ L\ L).$   
 $\forall X. \forall L_1. \forall L_2. \forall L_3. \forall A. \text{hastype} A (app\ L_1\ L_2\ L_3) \supset$   
     $\text{hastype} (app\_C\ X\ L_1\ L_2\ L_3\ A) (app\ (cons\ X\ L_1)\ L_2\ (cons\ X\ L_3)).$

# Map of Talk



Motivation

Specifications

A Translation

An Inverse

Looking Forward



## Dealing with Queries

After writing an LF specification, one may want to present and solve queries of the form  $M : A$ .

- ▶ We allow logic variables to appear in the type  $A$ .

LF Query       $Proof : \Pi x:nat.app\ nil\ (cons\ z\ (cons\ x\ nil))\ (L\ x)$

Translated Query

$\forall x.hastype\ Proof\ (app\ nil\ (cons\ z\ (cons\ x\ nil))\ (L\ x))$

Solution

$L = \lambda y.cons\ z\ (cons\ y\ nil)$

$Proof = \lambda y.app\_N\ (cons\ z\ (cons\ y\ nil))$

We would like to now return our solution to LF.

There are two concerns we should keep in mind:

- ▶ Under our chosen signature, there may be well-formed STLC terms which have **no corresponding LF term**.  
Eg.  $arrow\ empty\ (app\ unit\ unit)$
- ▶ Alternatively, there may be terms with **multiple corresponding LF terms**.  
Eg.  $(\lambda x.x)$

## An Inverse Encoding

We are not interested in inverting arbitrary terms

- ▶ All terms will correspond to a well-formed LF term.
- ▶ LF typing information ensures a unique inverse.

We define the inverse as a relationship between:

- ▶ the  $\lambda$ -term  $t$
- ▶ the LF type  $A$
- ▶ the LF typing information  $\Theta$
- ▶ the LF term  $M$

There are two judgments

$$\text{inv}^\downarrow(t; A; \Theta) = M \quad \text{and} \quad \text{inv}^\uparrow(t; A; \Theta) = M$$

The first expects  $A$  as input while the second synthesizes  $A$ .

Returning to our example:

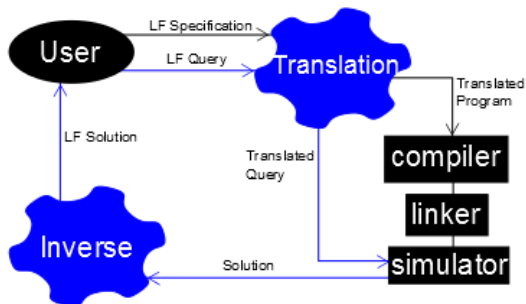
**Solution**  $L = \lambda y. \text{cons } z (\text{cons } y \text{ nil})$

*Proof*  $= \lambda y. \text{app\_N } (\text{cons } z (\text{cons } y \text{ nil}))$

**LF Solution**  $L = \lambda y:\text{nat}. \text{cons } z (\text{cons } y \text{ nil})$

*Proof*  $= \lambda y:\text{nat}. \text{app\_N } (\text{cons } z (\text{cons } y \text{ nil}))$

# Map of Talk



Motivation

Specifications

A Translation

An Inverse

Looking Forward

## Ongoing Work

- ▶ Show correctness of this translation.
- ▶ Developing an implementation of this system.
- ▶ Use this translation to extend Abella for reasoning about LF specifications.

End

## Correctness of the Translation

- ▶ We need to show that the substitutions found in LF and under the translation are 'equivalent'.
- ▶ Our approach for this proof is to use simulation.

### Theorem

*Let  $\Sigma$  be an LF signature and let  $A$  be an LF type that possibly contains meta-variables.*

- 1. If the query  $M : A$  is solved with the ground answer substitution  $\sigma$ , then there is an invertible answer substitution  $\theta$  for the goal  $\{\{A\}\} \langle M \rangle$  wrt  $\{\{\Sigma\}\}$  such that the inverse  $\theta'$  of  $\theta$  generalizes  $\sigma$  (i.e. there exists a  $\sigma'$  such that  $\sigma' \circ \theta' = \sigma$ ).*
- 2. If  $\theta$  is an invertible answer substitution for  $\{\{A\}\} \langle M \rangle$ , then its inverse is an answer substitution for  $M : A$ .*

## Rules for the Strictness Criterion

$$\frac{\text{dom}(\Gamma); \cdot; x \sqsubset_o A_i \text{ for some } A_i \text{ in } \vec{A}}{\Gamma; x \sqsubset_t c \vec{A}} \text{APP}_t \quad \frac{\Gamma, y : A; x \sqsubset_t B}{\Gamma; x \sqsubset_t \Pi y:A.B} \text{PI}_t$$

$$\frac{\Gamma_1; x \sqsubset_t B \quad \Gamma_1, y : B, \Gamma_2; y \sqsubset_t A}{\Gamma_1, y : B, \Gamma_2; x \sqsubset_t A} \text{CTX}_t$$

$$\frac{y_i \in \delta \text{ for each } y_i \text{ in } \vec{y} \quad \text{each variable in } \vec{y} \text{ is distinct}}{\Delta; \delta; x \sqsubset_o x \vec{y}} \text{INIT}_o$$

$$\frac{y \notin \Delta \text{ and } \Delta; \delta; x \sqsubset_o M_i \text{ for some } M_i \text{ in } \vec{M}}{\Delta; \delta; x \sqsubset_o y \vec{M}} \text{APP}_o$$

$$\frac{\Delta; \delta, y; x \sqsubset_o M}{\Delta; \delta; x \sqsubset_o \lambda y:A.M} \text{ABS}_o$$

## Rules for the Inverse Encoding

$$\frac{\frac{X : A \in \Delta}{\text{inv}^\uparrow(X; A; \Theta) = X} \text{inv-var}}{\text{inv}^\downarrow(M; B; \Theta, x : A) = M'} \text{inv-abs}$$
$$\frac{\text{inv}^\uparrow(M_1; \Pi x : B. A; \Theta) = M'_1 \quad \text{inv}^\downarrow(M_2; B; \Theta) = M'_2}{\text{inv}^\uparrow(M_1 \ M_2; A[M'_2/x]; \Theta) = M'_1 \ M'_2} \text{inv-app}$$
$$\frac{u : A \in \Theta}{\text{inv}^\uparrow(u; A; \Theta) = u} \text{inv-const} \quad \frac{\text{inv}^\uparrow(M; A; \Theta) = M'}{\text{inv}^\downarrow(M; A; \Theta) = M'} \text{inv-syn}$$